

Additive bounding for the Double TSP with Multiple Stacks

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Optimization and Decision Science Conference 2020

November 19th, 2020

The DTSPMS

The **Double Traveling Salesman Problem with Multiple Stacks** is an NP-*hard* combinatorial optimization problem.

- Data:
 - two weighted graphs (*pickup* and *delivery*) with a depot each
 - a vehicle with a given number of stacks (LIFO policy)
- solution: a Hamiltonian cycle for each graph, based at the depot
- objective: minimize the total cost of the two cycles
- constraints: the two cycles must be compatible with the LIFO policy for each stack: picked up items are put on top of a stack and only items on top of a stack can be delivered.

A sample instance

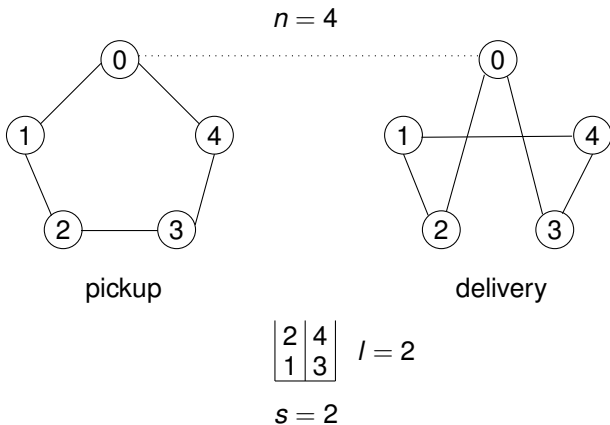


Figure: A sample instance with $n = 4$, $s = 2$, $l = 2$

State of the art

Only very small instances have been solved to optimality.

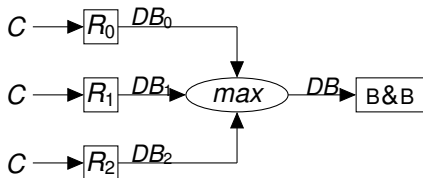
- Petersen, Archetti, Speranza (2010): branch-and-cut on a two-index vehicle flow formulation with additional infeasible path constraints;
- Carrabs, Cerulli, Speranza (2013): branch-and-bound for the DTSPMS with 2 stacks;
- Alba Martínez, Cordeau, Dell'Amico, Iori (2013): branch-and-cut: up to $n = 28$ nodes in one hour.

Our goal

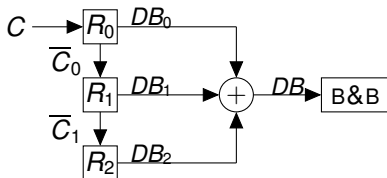
- testing the tightness of additive bounds (Fischetti, Toth, 1989);
- using them in a branch-and-bound algorithm.

Additive Bounds

Multiple bounds



Additive bounds



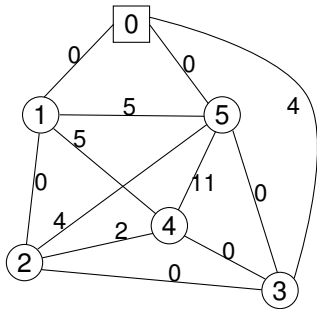
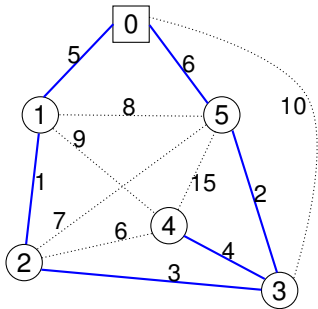
- $C \rightarrow$ original costs
- $\bar{C} \rightarrow$ reduced costs
- $R \rightarrow$ relaxations
- $DB \rightarrow$ dual bounds

Routing step

- *Held and Karp* method to compute TSP lower bound
 - *primal* step – compute 1-*tree*
 - *dual* step – modify edge costs using *subgradient optimization*

1-*tree* computed by HK

the corresponding *residual instance*



TSP optimal cost: 24

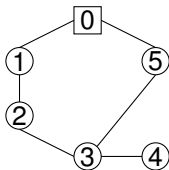
1-*tree* cost: 21 (HKLB)

Listing step

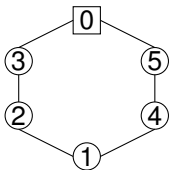
Incompatibility graph, from an arbitrary orientation of the two cycles:

- **STRAIGHT edge**: $i \prec j$ in both pickup and delivery cycles
- **REVERSE edge**: $i \prec j$ in pickup cycle and $j \prec i$ in delivery cycle

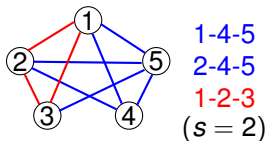
pickup 1-*tree*



delivery 1-*tree*



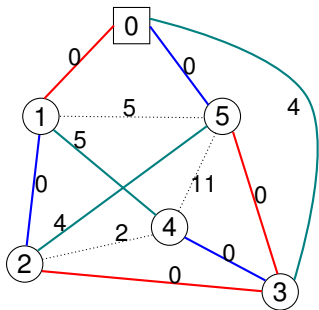
incompatibility graph



Find all cliques of cardinality $s + 1$, where s is the number of stacks.

Repair step

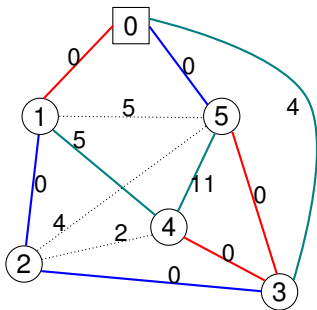
Destructive



• + • before repair

- minimum cost *subtour* of clique **1-4-5** of cost **13** (0-3-4-1-2-5-0)
- similarly for **1-2-3**, cost **9**

Non-destructive

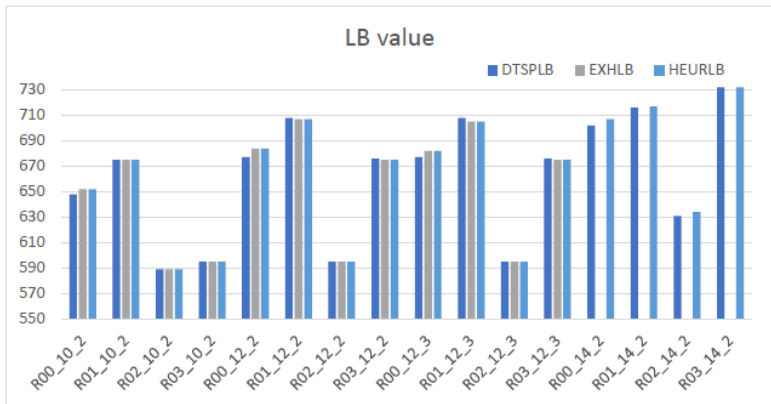


• + • after repair

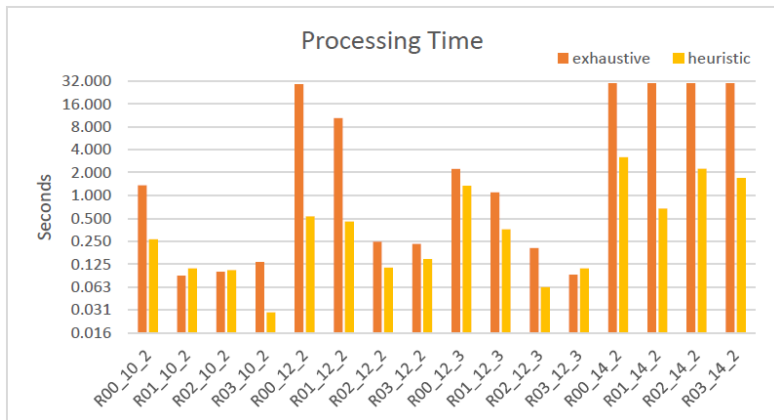
- minimum cost *subtour* of pair (**1-4-5**, **1-2-3**) of cost **20** (0-3-2-1-4-5-0)

Non-destructive repair cost:
exact or heuristic.

Computational results: lower bounds



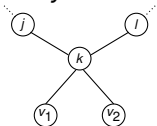
Computational results: computing time



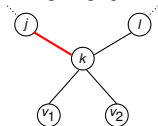
Branching

- 1-tree branching ($DEG(k) > 2$)
 - *forbidden* and *fixed* edges

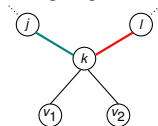
non-cycle 1-tree



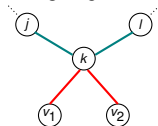
child 0



child 1



child 2

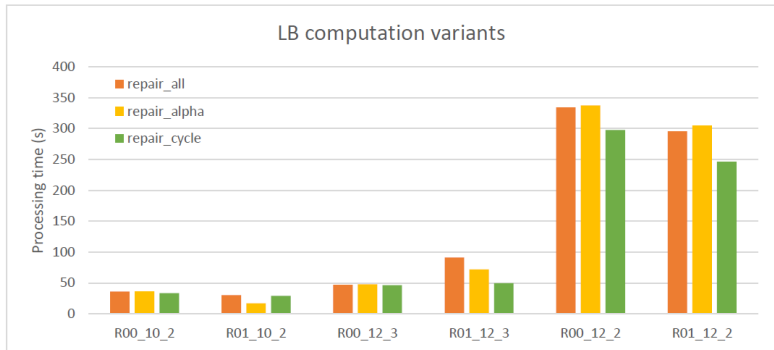


- *repairing subtour* branching
 - similarly, only with *positive* reduced cost edges

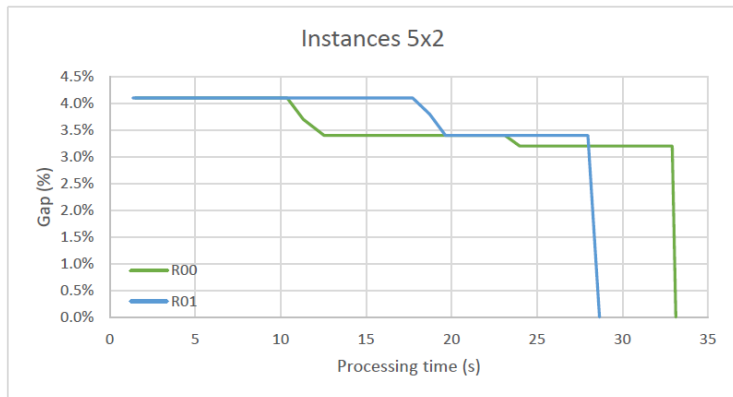
Bounding

Three variants tested for computing the additive LB

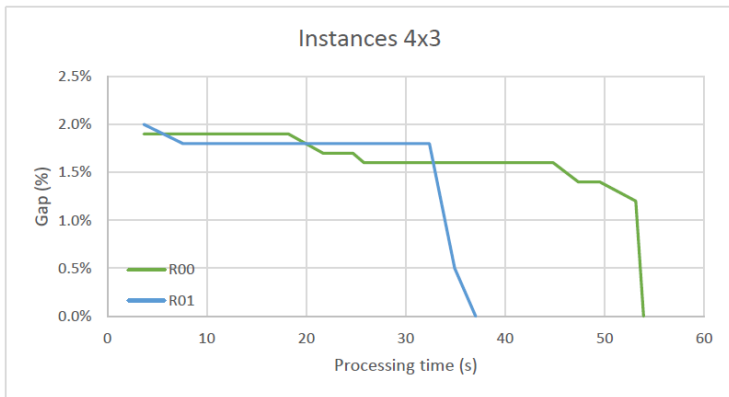
- `repair_all` – repair is always performed
- `repair_alpha` – repair is performed only when $\alpha = \frac{UB-LB}{UB}$ is small enough
- `repair_cycle` – repair is performed only when 1-trees are cycles



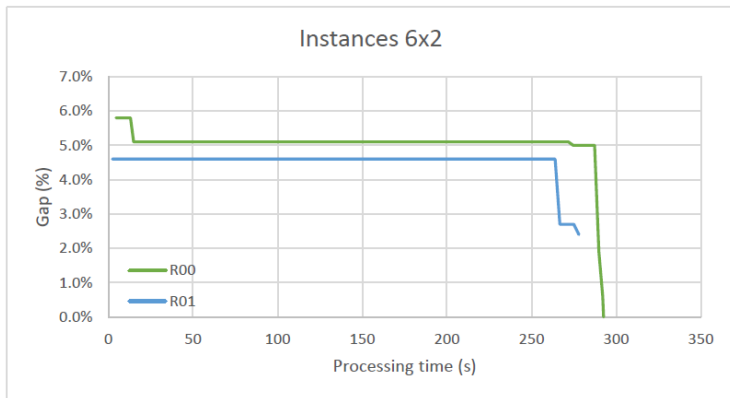
DTSPMS B&B algorithm – Experiments (5 × 2)



DTSPMS B&B algorithm – Experiments (4 × 3)



DTSPMS B&B algorithm – Experiments (6 × 2)



Conclusions

Conclusions

- additive lower bounds exceed the double TSP bound in about 75% of instances;
- *heuristic non-destructive* cost computation is very effective;
- `repair_cycle` saves processing time;
- results are still far from state-of-the-art.

Future developments

- Improve the computation of the Held-Karp lower bound;
- combinatorial explosion due to combinatorial number of checks
→ develop a **heuristic** also for *destructive* repair costs.