

PyQB

Programming in Python¹

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Lecture XXIV: Probabilistic programming



Describing one single "scientific method" is problematic, but a schema many will accept is:

- Imagine a hypothesis
- Oesign (mathematical/convenient) models consistent with the hypothesis
- Ollect experimental data
- Oiscuss the fitness of data given the models

It is worth noting that the falsification of models is not *automatically* a rejection of hypotheses (and, more obviously, neither a validation).



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In this discussion, a useful relationship between data and models is Bayes Theorem.

$$P(M, D) = P(M|D) \cdot P(D) = P(D|M) \cdot P(M)$$

Therefore:

$$P(M|D) = \frac{P(D|M) \cdot P(M)}{P(D)}$$

The plausibility of the model given some observed data, is proportional to the number of ways data can be *produced* by the model and the prior plausibility of the model itself.

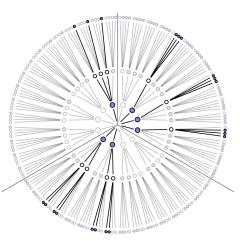


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Simple example

- Model: a bag with 4 balls in 2 colors B/W (but we don't know which of BBBB, BBBW, BBWW, BWWW, WWWW)
- Observed: BWB
- Which is the plausibility of BBBB, BBBW, BBWW, BWWW, WWWW?

Bayes Theorem is counting



Picture from: R. McElreath, Statistical Rethinking

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This Bayesian strategy is (conceptually) easy to transform in a computational process.

- Code the models
- Q Run the models
- Compute the plausibility of the models based on observed data

- Which is the proportion p of water covering Earth? The models are indexed by the float 0
- Given p, the probability of observing some W,L in a series of independent random observations is: $P(W, L|p) = \frac{(W+L)!}{W(L)!}p^W \cdot (1-p)^L$ (binomial distribution).

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- Do we have an initial (prior) idea?
- Make observations, apply Bayes, update prior!



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A conventional way of expressing the model

 $W \sim Binomial(W + L, p)$ $p \sim Uniform(0, 1)$

Probabilistic programming is systematic way of coding this kind of models, combining predefined statistical distributions and Monte Carlo methods for computing the posterior plausibility of parameters.

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In principle you can do it by hand

```
def dbinom(success: int, size: int, prob: float) -> float:
   fail = size - success
   return math.factorial(size)/(math.factorial(success)*math.factorial(fail))*prob**succ
  → ess*(1-prob)**(fail)
Then.
  W, L = 7, 3 # for example 'WWWLLWWLWW'
  p_grid = np.linspace(start=0, stop=1, num=20)
  prior = np.ones(20)/20
  likelihood = dbinom(W, n=W+L, p=p_grid)
  unstd_posterior = likelihood * prior
  posterior = unstd_posterior / unstd_posterior.sum()
Unfeasible with many variables!
```

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import pymc as pm

```
W, L = 7, 3
earth = pm.Model()
with earth:
    p = pm.Uniform("p", 0, 1) # uniform prior
    w = pm.Binomial("w", n=W+L, p=p, observed=W)
    posterior = pm.sample(2000)
```

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```
posterior['p']
```