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# Programming in Python<sup>1</sup>

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## Lecture XXII: Probabilistic programming

Describing one single "scientific method" is problematic, but a schema many will accept is:

- Imagine a hypothesis
- Obesign (mathematical/convenient) models consistent with the hypothesis
- Ollect experimental data
- Oiscuss the fitness of data given the models

It is worth noting that the falsification of models is not *automatically* a rejection of hypotheses (and, more obviously, neither a validation).

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In this discussion, a useful relationship between data and models is Bayes Theorem.

$$P(M,D) = P(M|D) \cdot P(D) = P(D|M) \cdot P(M)$$

Therefore:

$$P(M|D) = \frac{P(D|M) \cdot P(M)}{P(D)}$$

The plausibility of the model given some observed data, is proportional to the number of ways data can be *produced* by the model and the prior plausibility of the model itself.



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## Simple example

- Model: a bag with 4 balls in 2 colors B/W (but we don't know which of BBBB, BBBW, BBWW, BWWW, WWWW)
- Observed: BWB
- Which is the plausibility of BBBB, BBBW, BBWW, BWWW, WWWW?

Bayes Theorem is counting



Picture from: R. McElreath, Statistical Rethinking

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This Bayesian strategy is (conceptually) easy to transform in a computational process.

- Code the models
- Q Run the models
- Compute the plausibility of the models based on observed data



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- Which is the proportion p of water covering Earth? The models are indexed by the float 0
- Given p, the probability of observing some W,L in a series of independent random observations is:  $P(W, L|p) = \frac{(W+L)!}{W(L)!}p^W \cdot (1-p)^L$  (binomial distribution).

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- Do we have an initial (prior) idea?
- Make observations, apply Bayes, update prior!



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# A conventional way of expressing the model

 $W \sim Binomial(W + L, p)$  $p \sim Uniform(0, 1)$ 

Probabilistic programming is systematic way of coding this kind of models, combining predefined statistical distributions and Monte Carlo methods for computing the posterior plausibility of parameters.

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```
def dbinom(success: int, size: int, prob: float) -> float:
   fail = size - success
  return np.math.factorial(size)/(np.math.factorial(success)*np.math.factorial(fail))*p

→ rob**success*(1-prob)**(fail)

  W. L = 7.3
  p_grid = np.linspace(start=0, stop=1, num=20)
  prior = np.ones(20)/20
  likelihood = dbinom(W, n=W+L, p=p_grid)
  unstd_posterior = likelihood * prior
  posterior = unstd_posterior / unstd_posterior.sum()
Unfeasible with many variables!
```



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```
W, L = 7, 3
earth = pm.Model()
with earth:
    p = pm.Uniform("p", 0, 1) # uniform prior
    w = pm.Binomial("w", n=W+L, p=p, observed=W)
    posterior = pm.sample(2000)
```

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posterior['p']

import pymc as pm



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The probabilistic programming approach of pymc3 is built on two "technologies":

 A library that mixes numerical and symbolic computations (Theano, soon becoming Aesara)

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Markov Chain Monte-Carlo (MCMC) algorithms to estimate posterior densities



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It bounds numerical computations to its symbolic structure
("graph")
import theano
from theano import tensor
a = tensor.dscalar('alpha')
b = tensor.dscalar('beta')

c = a + b \* \* 2

f = theano.function([a,b], c)

assert f(1.5, 2) == 5.5



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Variables can be used to compute values, but also symbolic manipulations.

```
d = tensor.grad(c, b)
```

```
f_prime = theano.function([a, b], d)
```

```
assert f_prime(1.5, 2) == 4.
```

Note you still need to give an a because the symbolic structure needs it.

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It's way of estimating (relative) populations of "contiguous" states.

- It needs the capacity of evaluate the population/magnitude of any two close states (but a global knowledge of all the states *at the same time*)
- It's useful to estimate *posterior* distribution *without* explicitly computing P(D):  $P(M|D) = \frac{P(D|M) \cdot P(M)}{P(D)}$



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#### Metropolis

```
The easiest MCMC approach is the so-called Metropolis algorithm (in fact appeared as Metropolis, N., Rosenbluth, A., Rosenbluth, M., Teller, A., and Teller, E., 1953)
```

```
steps = 100000
positions = np.zeros(steps)
populations = [1,2,3,4,5,6,7.8,9,10]
current = 3
for i in range(steps):
    positions[i] = current
    proposal = (current + np.random.choice([-1,1])) %
    \rightarrow len(populations)
    prob_move = populations[proposal] /
    \rightarrow populations[current]
    if np.random.uniform(0, 1) < prob_move:</pre>
        current = proposal
```

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#### Convergence

First 100 moves



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last 300 moves

**Eventual** convergence is guaranteed, but it can be painful slow (and you dont't know if you are there...). Many algorithms try to improve: Gibbs, Hamiltonian-MC, NUTS...

Density of state visits

## Putting them together

#### import pymc3 as pm

```
linear_regression = pm.Model()
```

```
with linear_regression:
    # Theano variables
   sigma = pm.Uniform('sigma_h', 0, 50)
   alpha = pm.Normal('alpha', 178, 20)
   beta = pm.Normal('beta', 0, 10)
   mu = alpha + beta*(adult_males['weight'] -
    → adult_males['weight'].mean())
    # Observed!
   h = pm.Normal('height', mu, sigma,
    → observed=adult_males['height'])
   trace = pm.sample() # MCMC sampling
```



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