Decision Methods and Models Master's Degree in Computer Science

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Lesson 15: Decision-making under uncertainty

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Decision-making under uncertainty

We assume

- a preference relation Π that is a weak order with a known consistent value function u(f) (replaced by a cost f)
- a uncertain environment: $|\Omega| > 1$
- a single decision-maker: $|D| = 1 \Rightarrow \Pi_d$ reduces to Π



The problem becomes $\min_{x \in X} f(x, \omega)$ with $\omega \in \Omega$ known after x is selected

If ω is known in advance, the problem falls into parametric optimisation: solution $x^*(\omega)$ represents a strategy prepared for every possible scenario

The situation has applications in many different fields

- finance: decide how much to invest and in what
- marketing: decide prices and advertising campaigns
- research and development: decide which research projects to finance and how much

• . . .

but also less obvious fields such as algorithmics

- X is the set of alternative algorithms for a problem
- Ω is the set of instances
- f (x, ω) is the optimality gap (or computational time) achieved by algorithm x on instance ω

Descriptive models provide information on the scenarios Different kinds of information generate different classes of problems ignorance: the only information is the scenario set Ω risk: we know the scenario set Ω and a probability function π_{ω} \ldots

Notice that even ruling out unpredicted scenarios is hard ("black swans")

Given X and Ω , other descriptive models provide the impacts $f(x, \omega)$

Suitable conditions allow to introduce a relation on alternatives that can filter out some of them and simplify (or even solve) the problem

$$x \preceq x' \Leftrightarrow f(x,\omega) \preceq f(x',\omega)$$
 for all $\omega \in \Omega$

If the strong domination is strict, solution x' can be safely removed

The definition is formally equivalent to Paretian preference, with scenario $\omega \in \Omega$ replacing indicators $l \in P$: $f_l(x) \to f(x, \omega)$

- similar methods find nondominated solutions and Paretian solutions
- but, while the indicators are *p*, the scenarios can be infinitely many (*in that case, the extension is not trivial*)

Consider a set of investments with the corresponding impacts (benefits)

ROI	Recession	Moderate growth	Strong growth
Stock fund	-25%	0%	35%
Bond fund	-10%	5%	15%
Treasuries	8%	8%	8%
"Toxic" fund	-5%	6%	8%

The toxic fund is dominated by treasuries

Probabilistic dominance

$x \preceq x' \quad \Leftrightarrow \quad Pr(f(x) \leq f) \geq Pr(f(x') \leq f) \text{ for all } f \in F$

State (die result)	1	2	3	4	5	6	
Gamble A wins \$	1	1	2	2	2	2	first-order stochastic dominance (FSD)
${\rm Gamble} \; {\rm B} \; {\rm wins} \; \$$	1	1	1	2	2	2	$P[A \geq x] \geq P[B \geq x]$ for all x,
${\rm Gamble} \gets {\rm C} \text{ wins } \$$	3	3	3	1	1	1	

A strongly dominates B (yield as good for all possible outcomes of the die roll)

C does not strongly dominate B (B gives a better yield in scenarios 4 to 6)

C probabilistically dominates B because

- $Pr(B \ge 1) = Pr(C \ge 1) = 1$
- $Pr(B \ge 2) = Pr(C \ge 2) = 3/6$
- $Pr(B \ge 3) = 0 < Pr(C \ge 3) = 3/6$

A and C exhibit no probabilistic dominance

•
$$Pr(A \ge 2) = 4/6 > Pr(C \ge 2) = 3/6$$

•
$$Pr(C \ge 3) = 3/6 > Pr(A = \ge 3) = 0$$

Dominance and algorithm performance

A typical application is the selection of heuristic algorithms where

- an alternative x is a heuristic algorithm A
- a scenario ω is a problem instance I
- the impact $f(x, \omega)$ is the percent gap (relative difference) $\delta_A(I)$

In this context

strong dominance means a lower gap on all instances (very rare)

$$A \preceq A' \quad \Leftrightarrow \quad \delta_A(I) \leq \delta_{A'}(I) \text{ for all } I \in P$$

• probabilistic dominance means hitting below any given threshold $\overline{\delta}$ for more instances (higher *Solution Quality Distribution* diagram):

$$A \preceq A' \quad \Leftrightarrow \quad {\it Pr}(\delta_{\cal A}(I) \leq ar{\delta}) \geq {\it Pr}(\delta_{{\cal A}'(I)} \leq ar{\delta}) ext{ for all } f \in F$$



Different scenario modelling approaches

The scenario set Ω is in general a set of vectors in \mathbb{R}^s

Two notable cases are

• the scenario-based description (common in economy): Ω is a finite list of scenarios

$$\Omega = \left\{ \omega^{(1)}, \dots, \omega^{(|\Omega|)} \right\}$$

2 the interval-based description (common in engineering): Ω is the Cartesian product of a s real intervals on the exogenous variables

$$\Omega = \begin{bmatrix} \omega_1^{\min}, \omega_1^{\max} \end{bmatrix} \times \ldots \times \begin{bmatrix} \omega_s^{\min}, \omega_s^{\max} \end{bmatrix}$$



Example

Suppose that we are computing the fastest path on a street network in which two arcs have uncertain travel times ω_1 and ω_2

• in a scenario-based description, we might have

$$\omega = \begin{bmatrix} 2\\1 \end{bmatrix} \text{ or } \begin{bmatrix} 5\\1 \end{bmatrix} \text{ or } \begin{bmatrix} 2\\6 \end{bmatrix} \quad \Leftrightarrow \quad \Omega = \{(2,1), (5,1), (2,6)\}$$

• in an interval-based description, we might have

$$egin{cases} 2 \leq \omega_1 \leq 5 \ 1 \leq \omega_2 \leq 6 \end{cases} \quad \quad \Leftrightarrow \quad \Omega = [2,5] imes [1,6] \end{cases}$$



How to choose?

The appropriate description depends on

- the precision of the representation
- the simplicity of the solution process

(is there an algorithm?)

On the one hand, the scenario description has a finite number of cases

- are they all and only the possible cases? (precision)
- are they few or combinatorially many? (simplicity)

On the other hand, the interval description

- implies that the exogenous variable are independent (precision)
- the scenario are infinitely many, but the worst scenario might be
 - the same for all solutions
 - easy to find (simplicity)

For example, take the maximum for all travel times