

Restricted Turing Machines and Language Recognition

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Università degli Studi di Milano, Italy

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March 14-18, 2016



UNIVERSITÀ DEGLI STUDI
DI MILANO

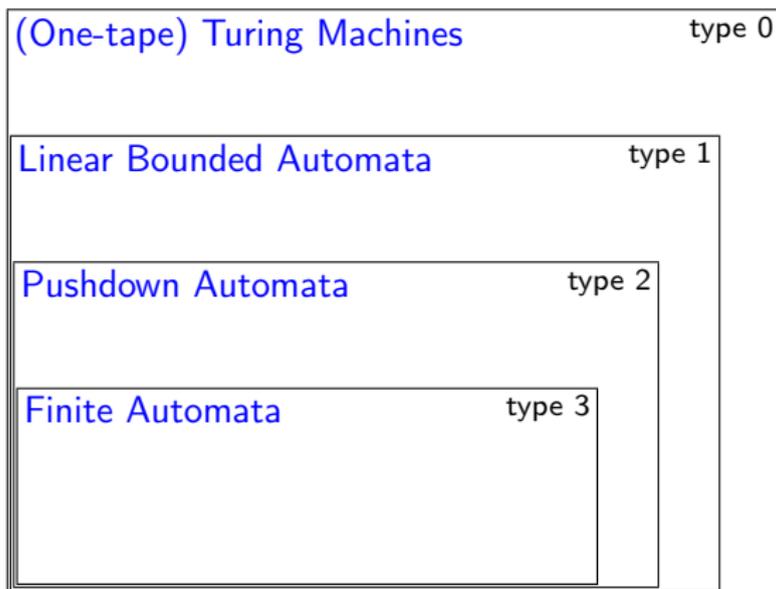
Part I: Fast One-Tape Turing Machines

Hennie Machines & C

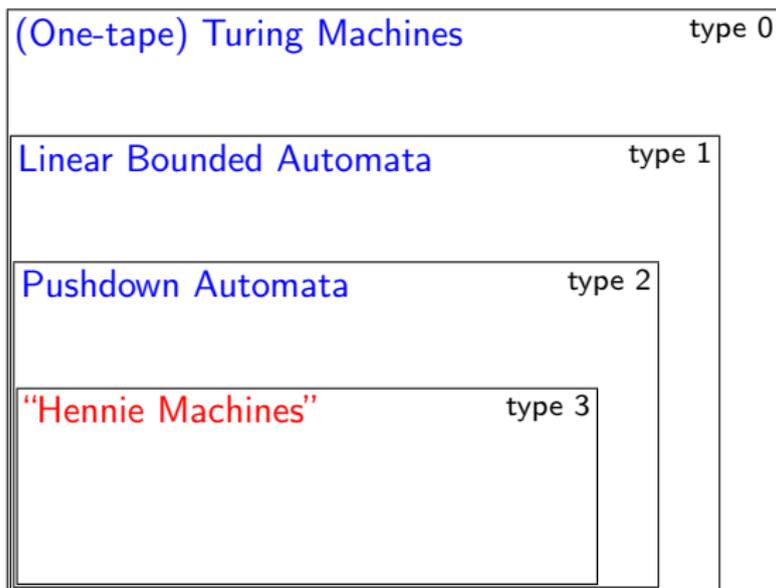
Part II: One-Tape Turing Machines
with Rewriting Restrictions

Limited Automata & C

The Chomsky Hierarchy



The Chomsky Hierarchy



Outline

- ▶ **Limited automata**
- ▶ Equivalence with CFLs
- ▶ Determinism vs nondeterminism
- ▶ Descriptive complexity aspects
- ▶ 1-limited automata and regular languages
- ▶ Related models

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- ▶ **Equivalence with CFLs**
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Limited Automata [Hibbard '67]

One-tape Turing machines with restricted rewritings

Definition

Fixed an integer $d \geq 1$, a *d-limited automaton* is

- ▶ a one-tape Turing machine
- ▶ which is allowed to rewrite the content of each tape cell *only in the first d visits*

Limited Automata [Hibbard '67]

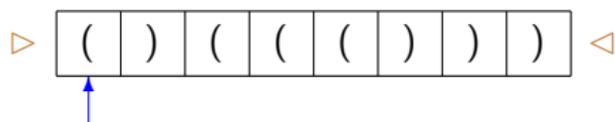
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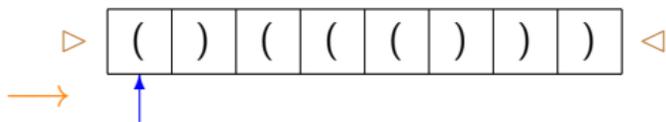
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- ▶ which is allowed to rewrite the content of each tape cell *only in the first d visits*

Example: Balanced Parentheses



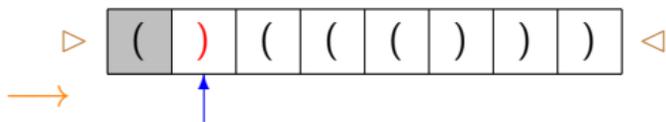
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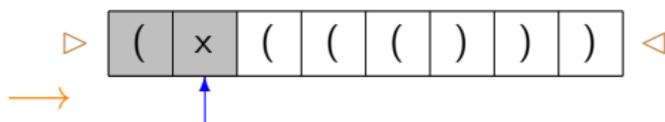
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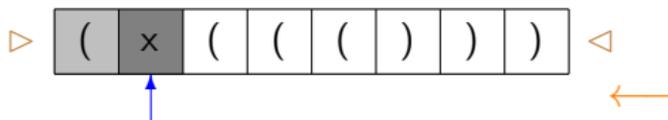
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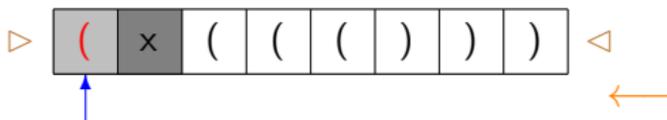
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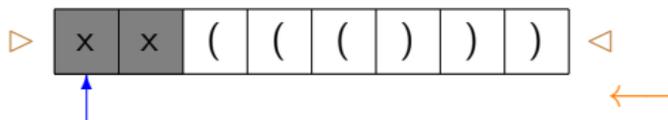
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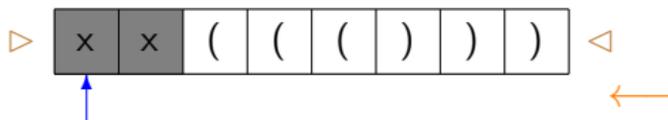
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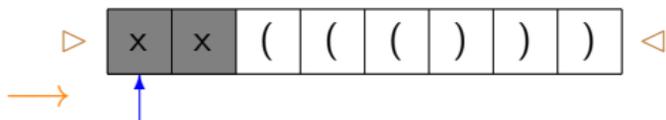
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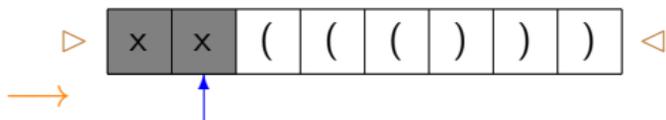
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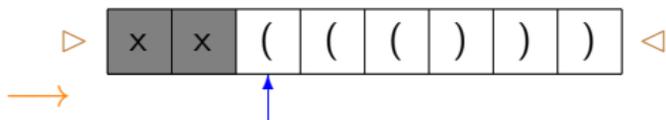
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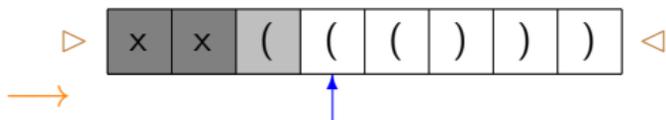
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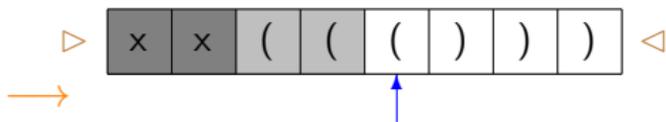
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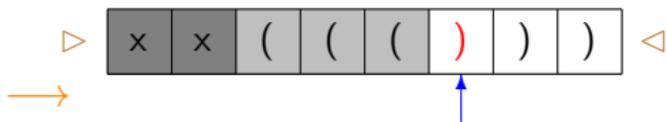
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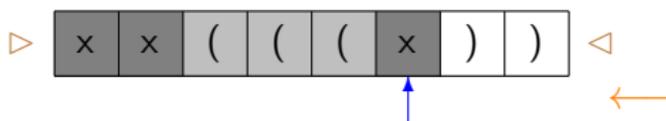
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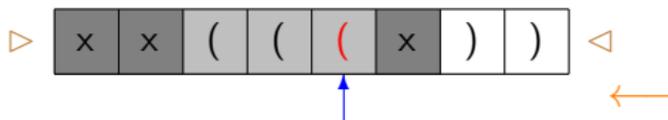
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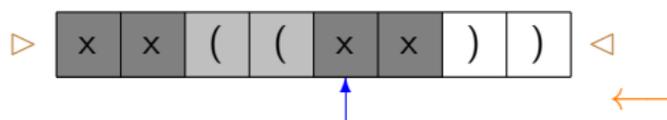
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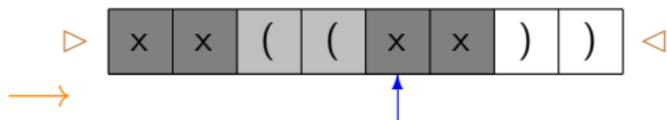
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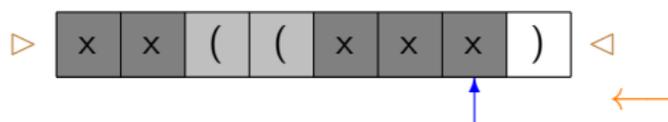
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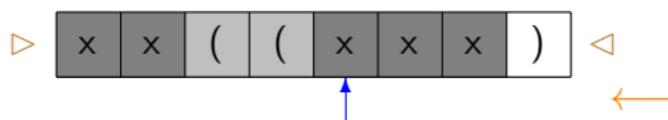
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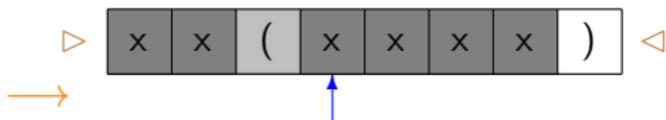
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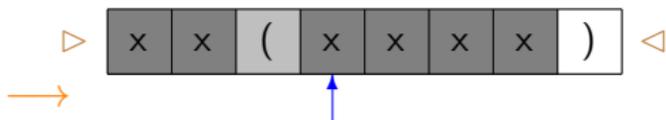
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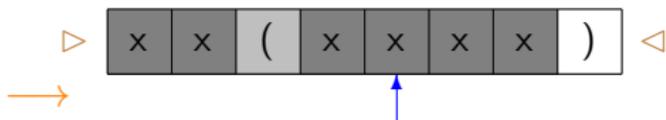
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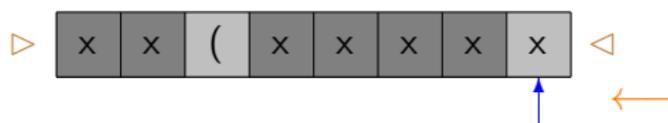
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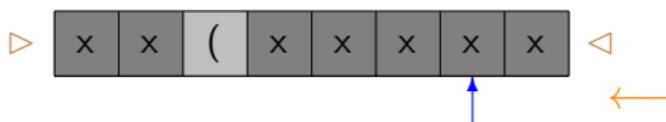
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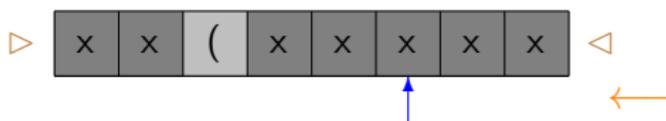
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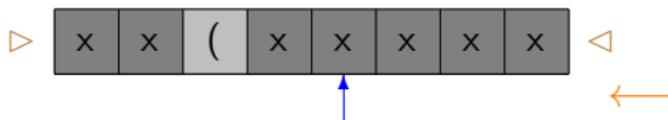
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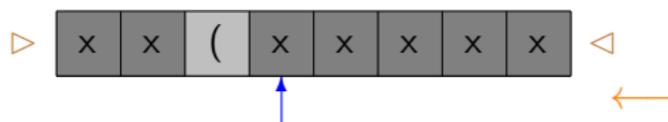
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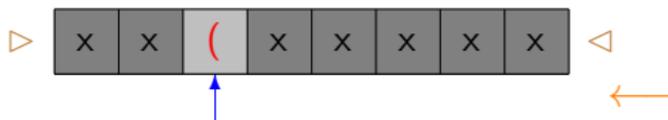
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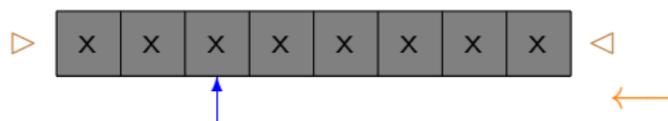
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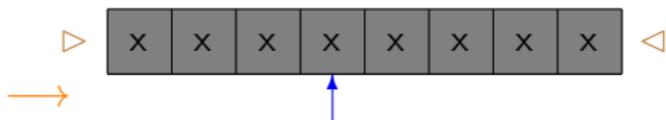
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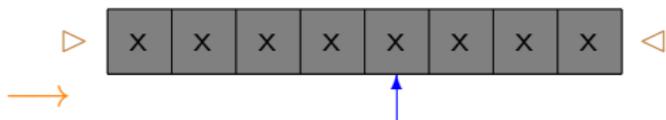
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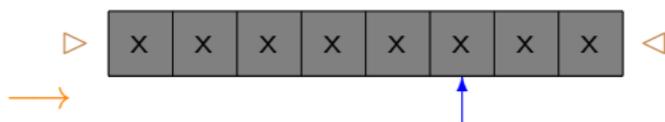
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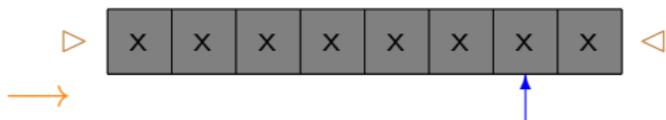
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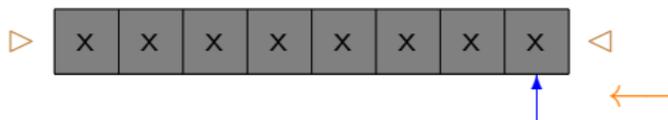


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- (i') If in (i) the right end of the tape is reached then scan all the tape and *accept* iff all tape cells contain x
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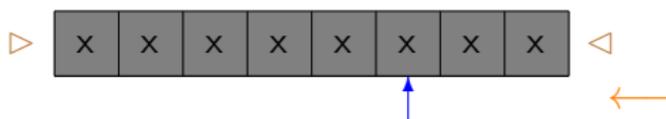


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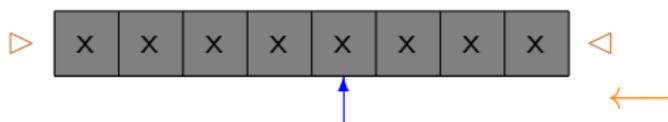


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- (iii') If in (iii) the left end of the tape is reached then *reject*

Example: Balanced Parentheses



- (i) Move to the right to search a closed parenthesis
- (ii) Rewrite it by x
- (iii) Move to the left to search an open parenthesis
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Each cell is rewritten only in the first 2 visits!

Limited Automata [Hibbard '67]

One-tape Turing machines with restricted rewritings

Definition

Fixed an integer $d \geq 1$, a *d-limited automaton* is

- ▶ a one-tape Turing machine
- ▶ which is allowed to rewrite the content of each tape cell *only in the first d visits*

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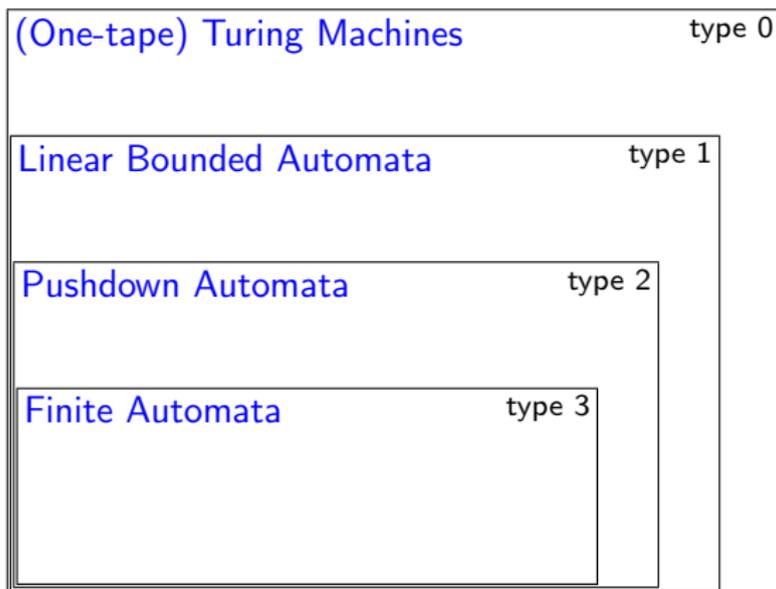
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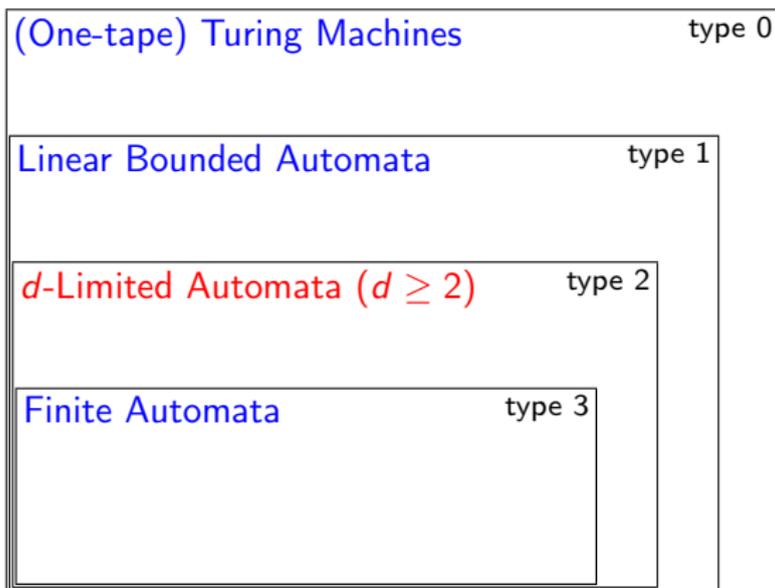
Computational power

- ▶ For each $d \geq 2$, *d-limited automata* characterize context-free languages [Hibbard '67]
- ▶ 1-limited automata characterize regular languages [Wagner&Wechsung '86]

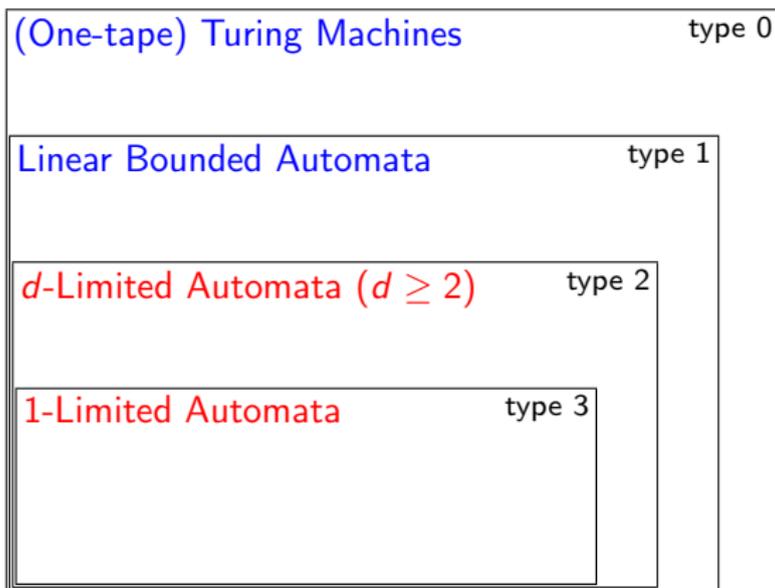
The Chomsky Hierarchy



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The Chomsky Hierarchy



Main tool:

Theorem ([Chomsky&Schützenberger '63])

Every context-free language $L \subseteq \Sigma^$ can be expressed as*

$$L = h(D_k \cap R)$$

where, for $\Omega_k = \{(1,)_1, (2,)_2, \dots, (k,)_k\}$:

- ▶ $D_k \subseteq \Omega_k^*$ is a Dyck language
- ▶ $R \subseteq \Omega_k^*$ is a regular language
- ▶ $h : \Omega_k \rightarrow \Sigma^*$ is an homomorphism

Furthermore, it is possible to restrict to *non-erasing* homomorphisms [Okhotin '12]

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Why Each CFL is Accepted by a 2-LA

L context-free language, with $L = h(D_k \cap R)$

- ▶ T nondeterministic transducer computing h^{-1}
- ▶ A_D 2-LA accepting the Dyck language D_k
- ▶ A_R finite automaton accepting R

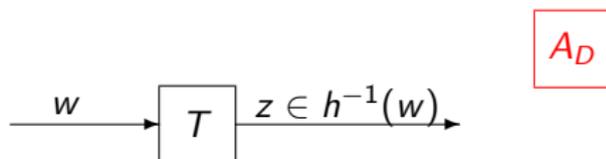
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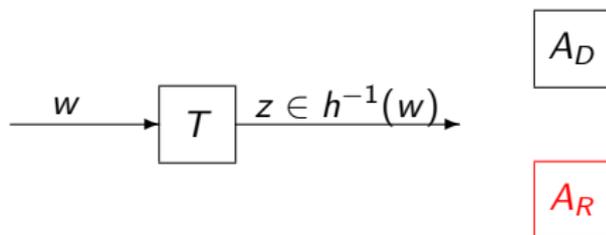
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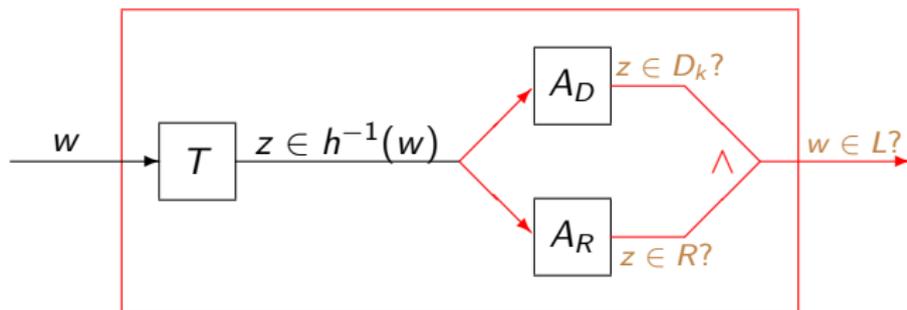
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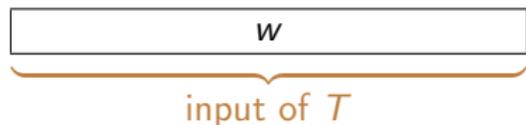
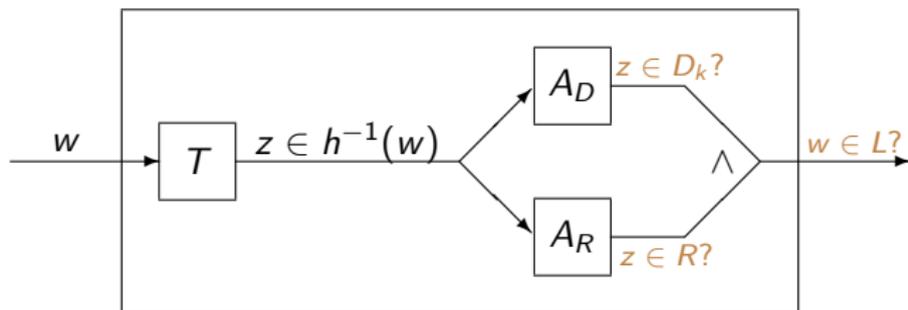
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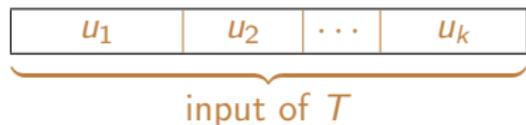
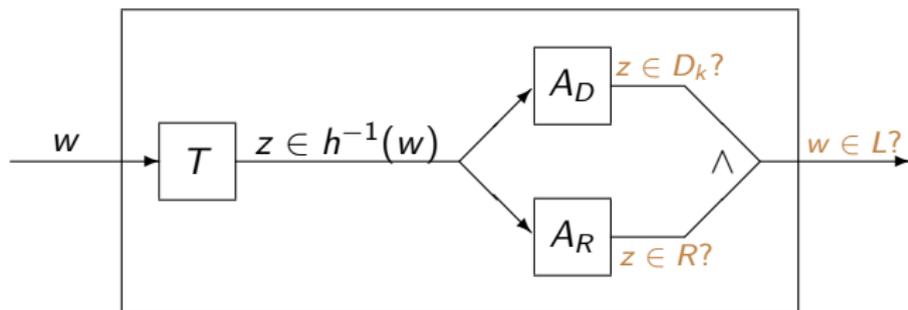
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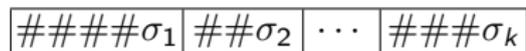
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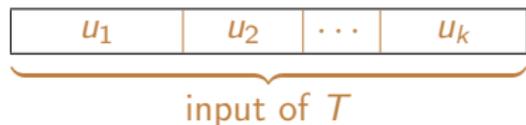
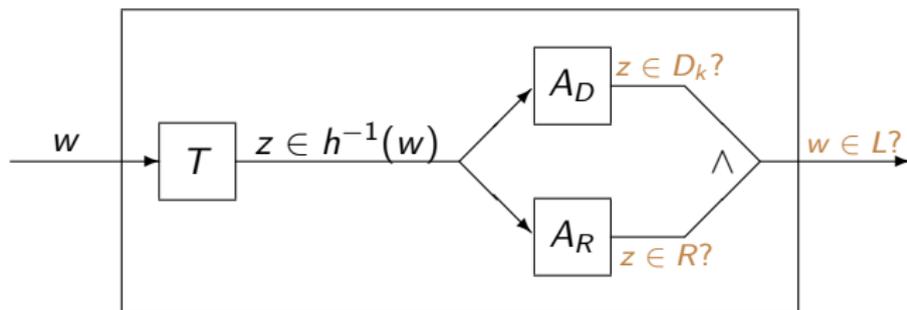
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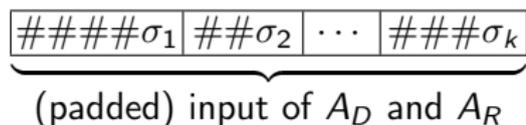
Non erasing homomorphism!

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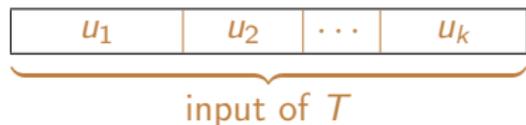
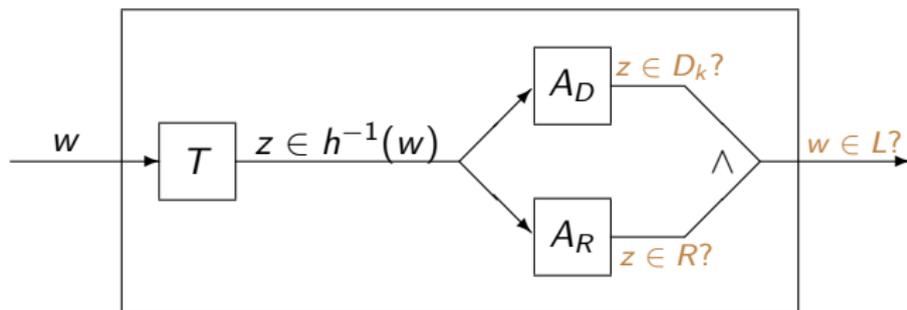
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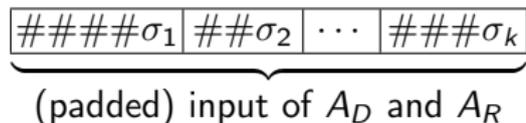
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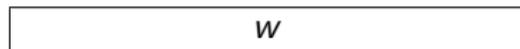
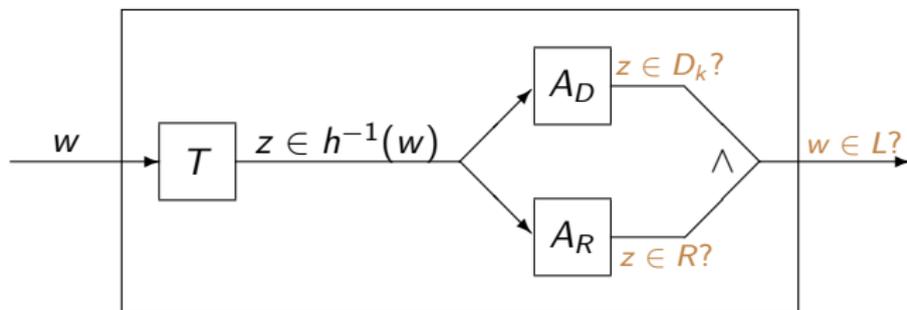


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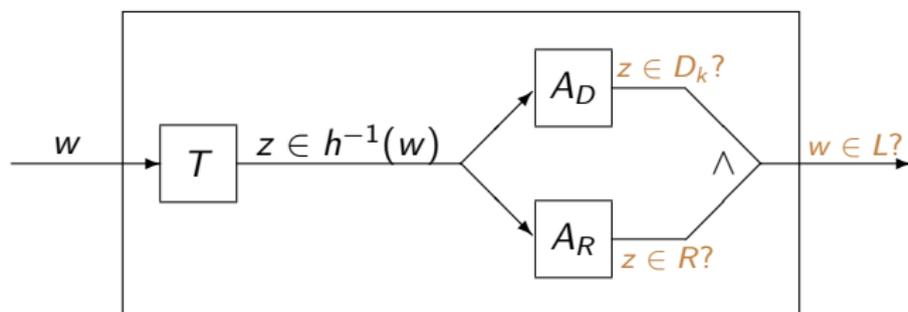
Not stored into the tape!

Each σ_i is produced "on the fly"

Why Each CFL is Accepted by a 2-LA

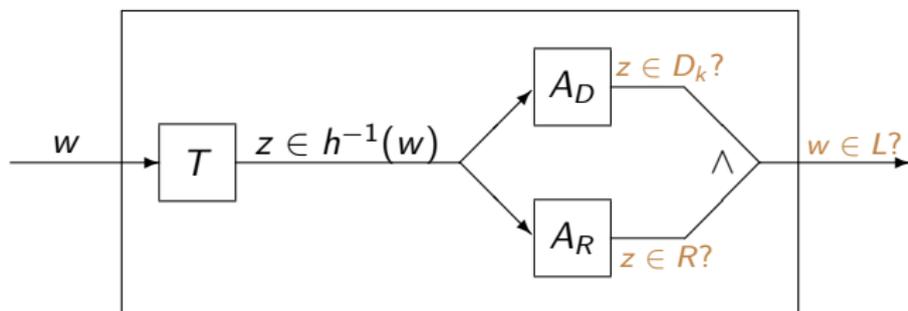


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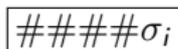
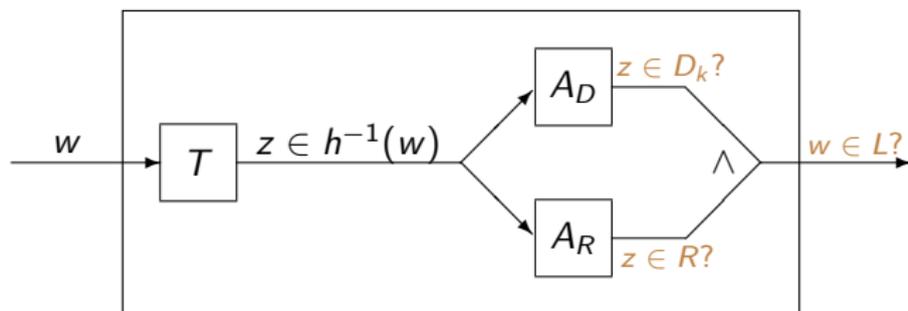
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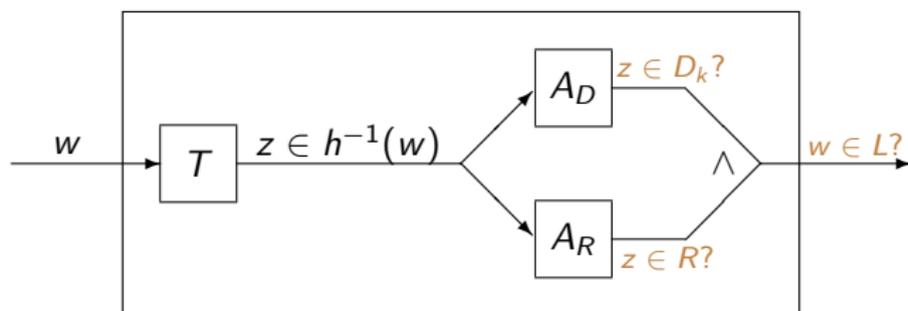


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γ_i : first rewriting by A_D

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$\#\#\#\#\sigma_i$

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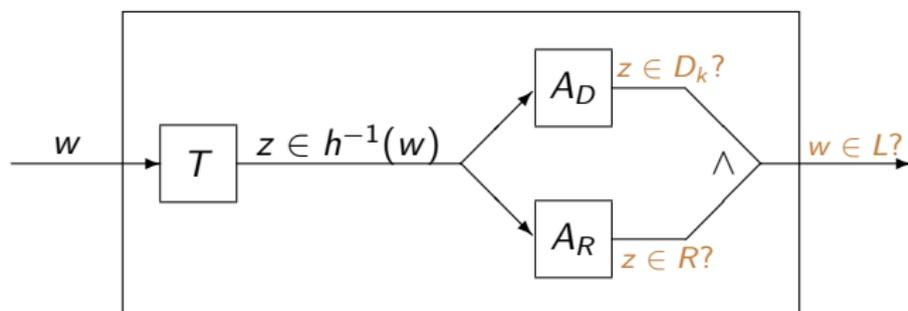
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- ▶ On the tape, u_i is replaced directly by $\#\#\#\#\gamma_i$
- ▶ One move of A_R on input σ_i is also simulated

Why Each CFL is Accepted by a 2-LA



σ_i

γ_i

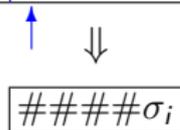
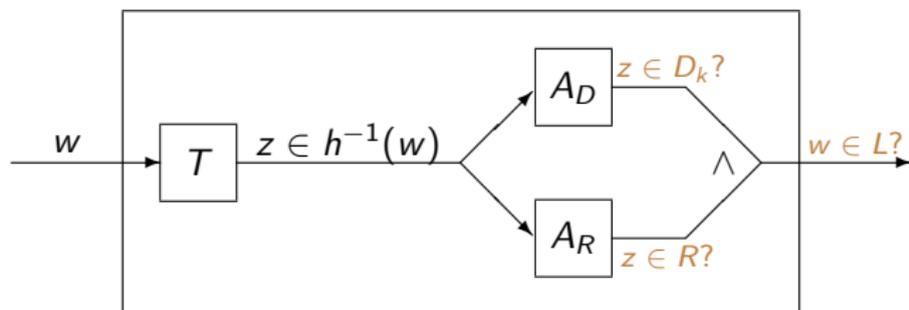
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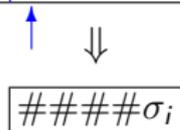
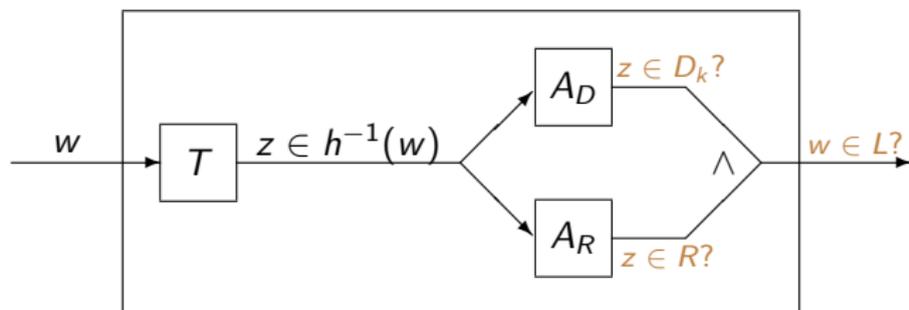


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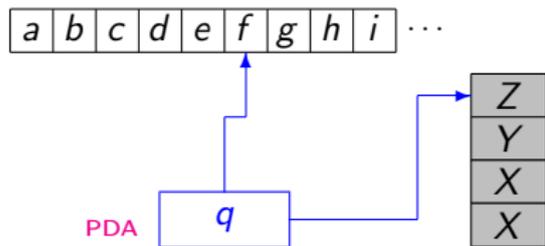
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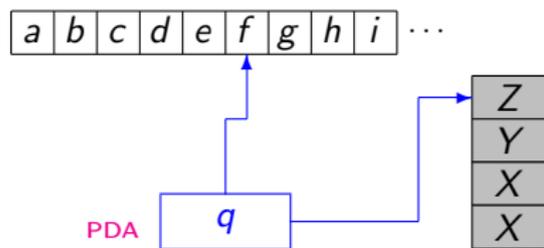
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PDAs vs Limited Automata

Simulation of Pushdown Automata by 2-Limited Automata



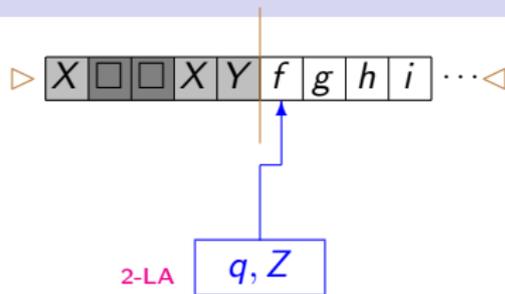
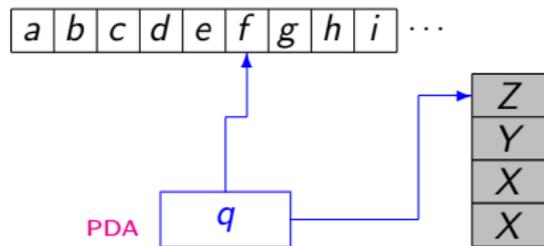
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Normal form for (D)PDAs:

- ▶ at each step, the stack height increases at most by 1
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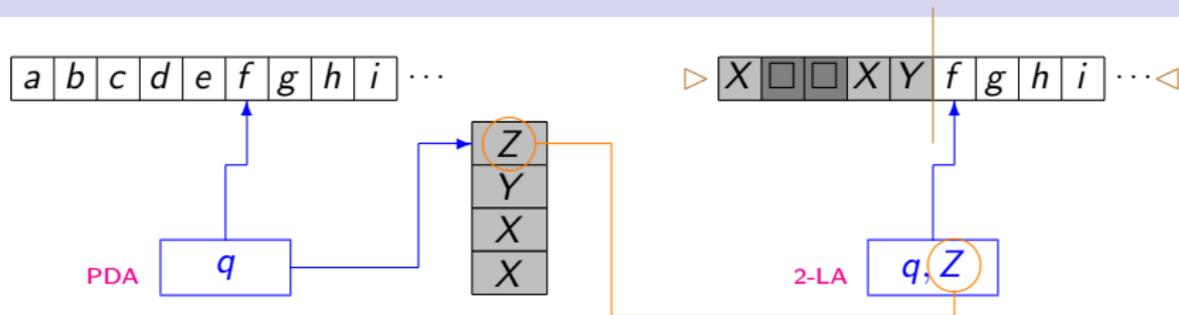
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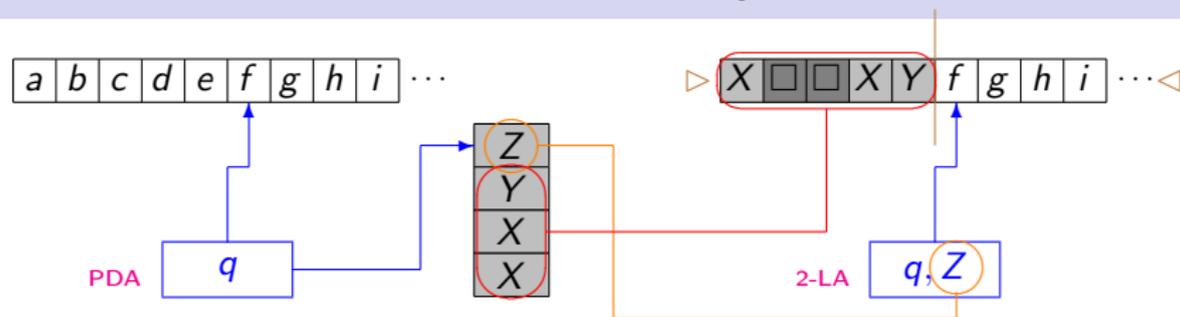
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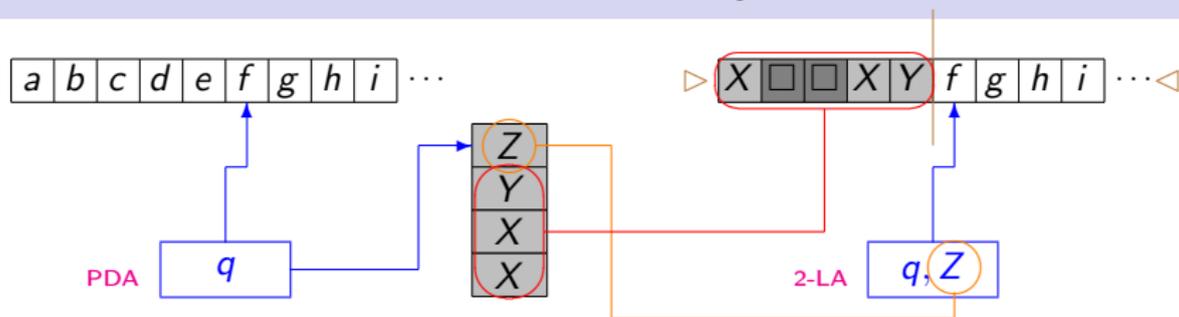
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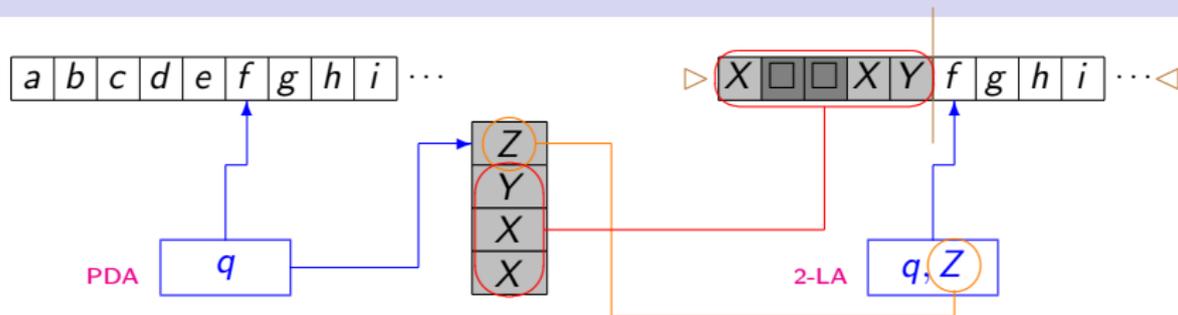
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What about the converse simulation, namely that of 2-LAs by PDAs?

[Hibbard '67]

Original simulation

[P.&Pisoni '15]

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- ▶ Exponential cost
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- ▶ Fixed a 2-limited automaton
- ▶ *Transition table* τ_w w is a “frozen” string

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$(q, d', p, d'') \in \tau_w$ iff M on a tape segment containing w has a computation path:

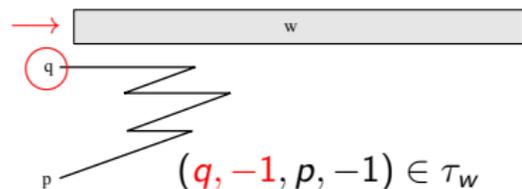
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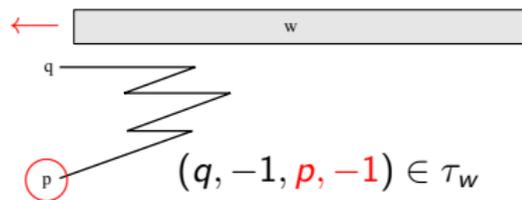
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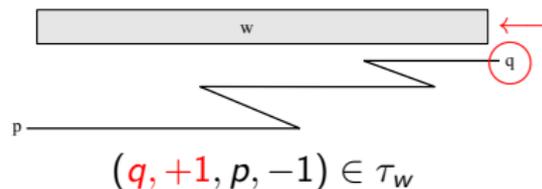
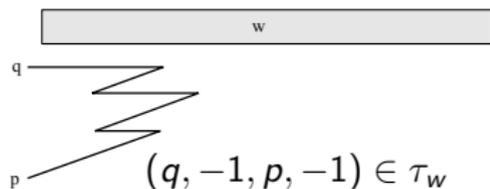
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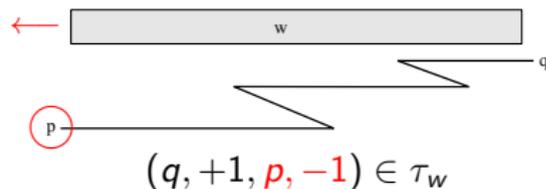
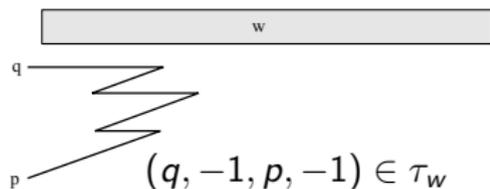
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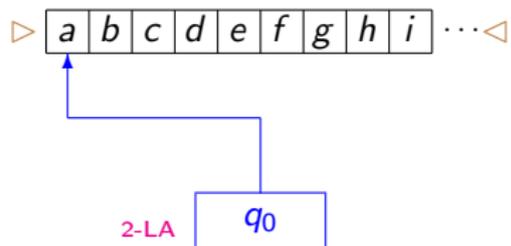


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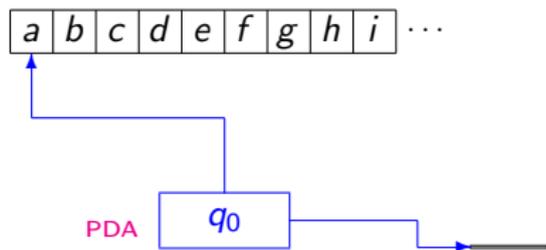
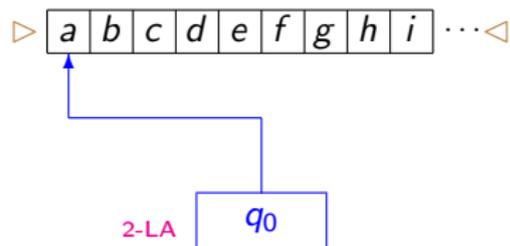
Simulation of 2-LAs by PDAs

Initial configuration



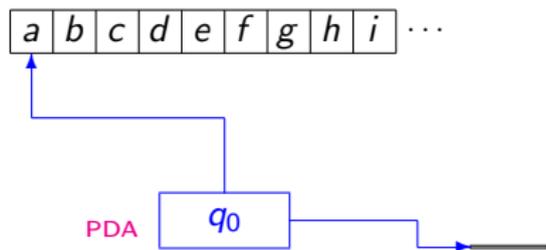
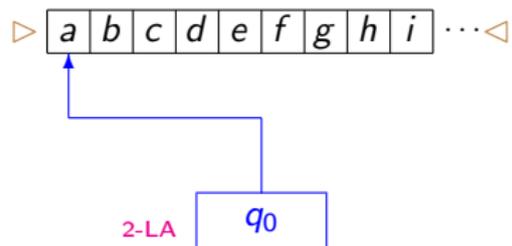
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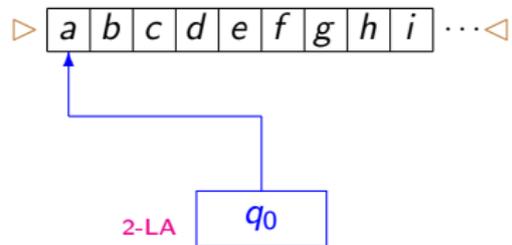


Simulation of 2-LAs by PDAs

Initial configuration



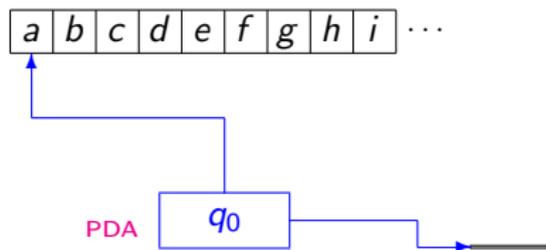
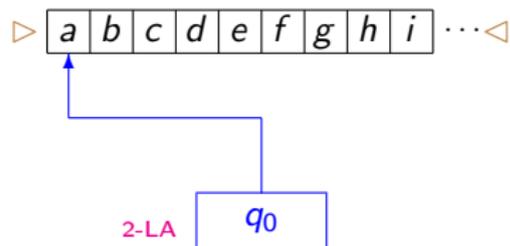
Some computation steps...



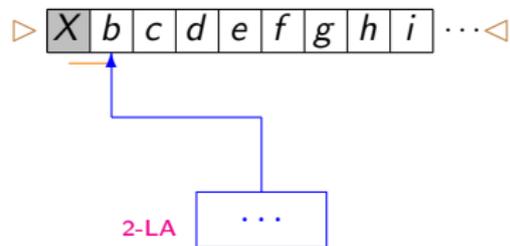
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Simulation of 2-LAs by PDAs

Initial configuration



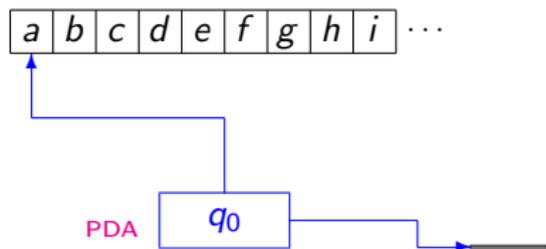
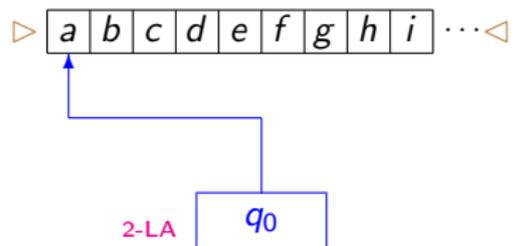
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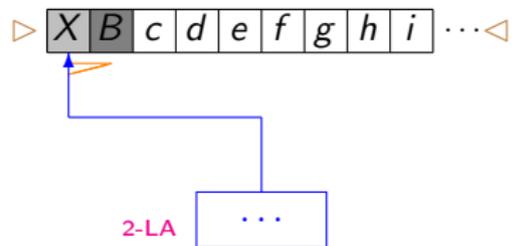
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Simulation of 2-LAs by PDAs

Initial configuration



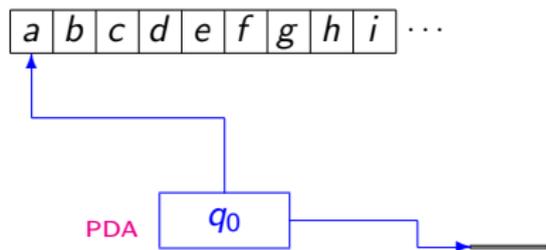
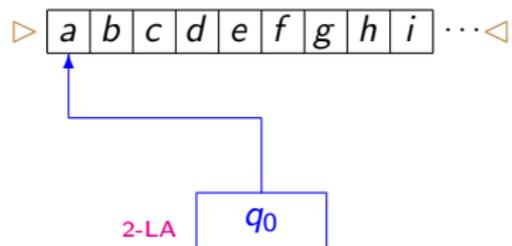
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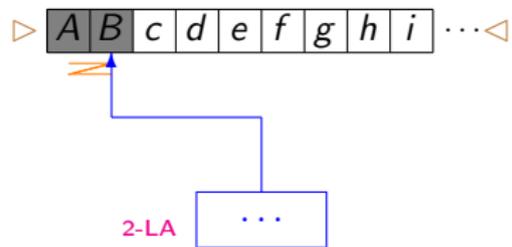
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Simulation of 2-LAs by PDAs

Initial configuration



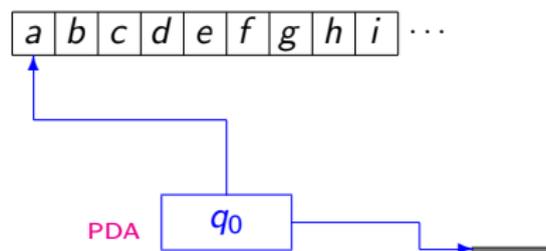
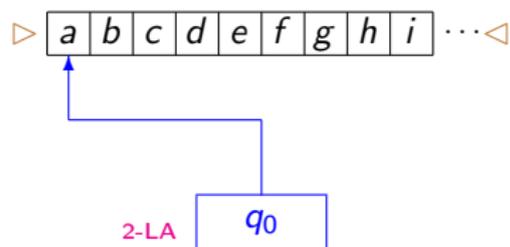
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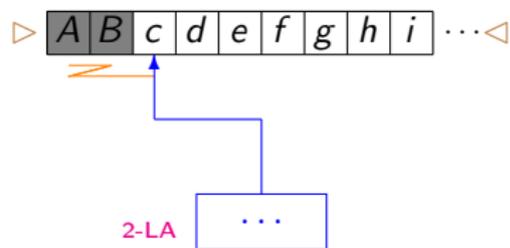
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Simulation of 2-LAs by PDAs

Initial configuration



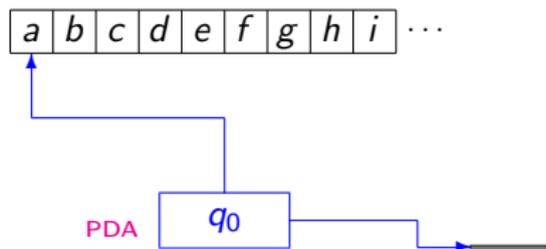
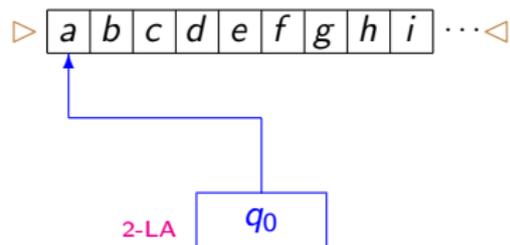
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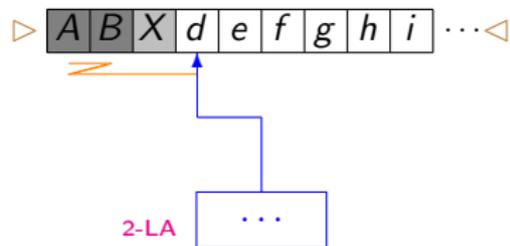
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Simulation of 2-LAs by PDAs

Initial configuration



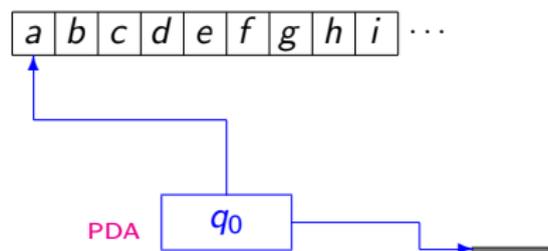
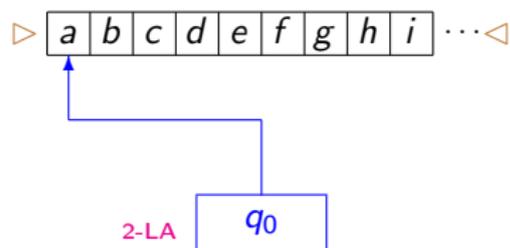
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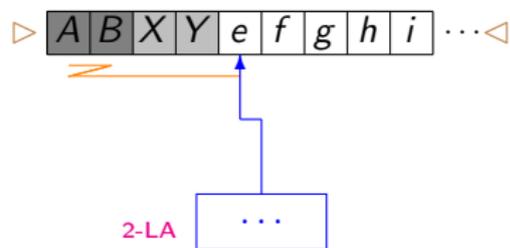
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Simulation of 2-LAs by PDAs

Initial configuration



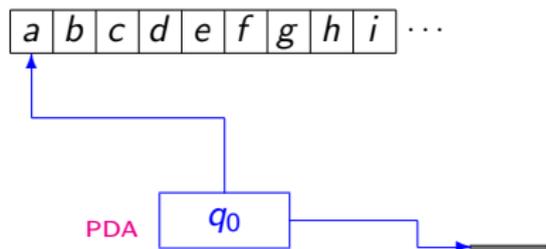
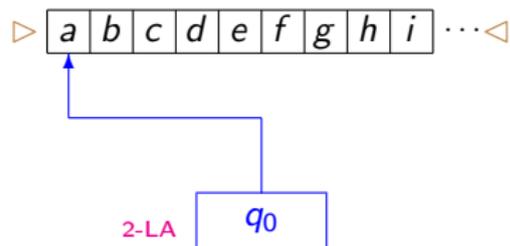
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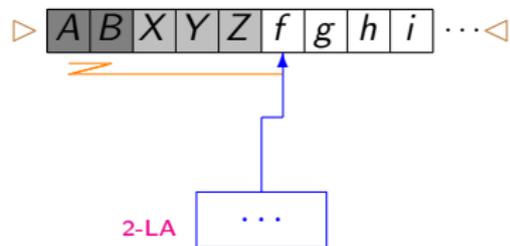
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Simulation of 2-LAs by PDAs

Initial configuration



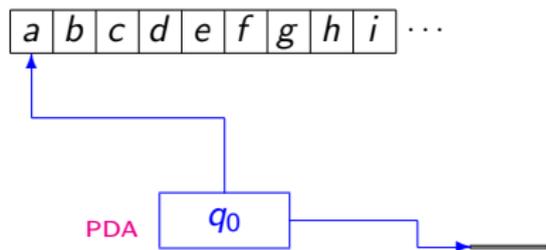
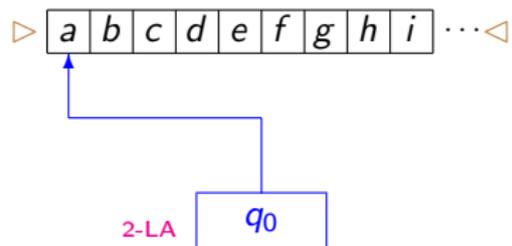
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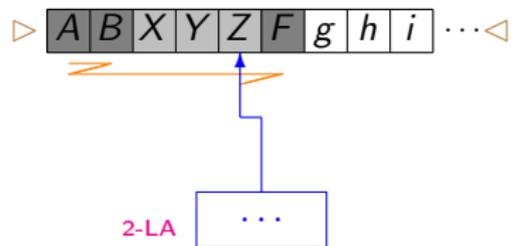
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Simulation of 2-LAs by PDAs

Initial configuration



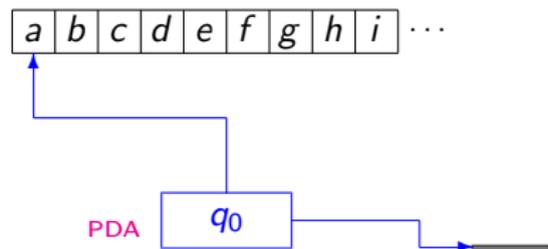
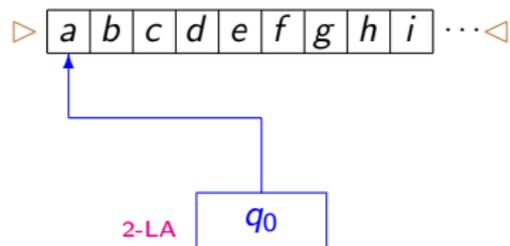
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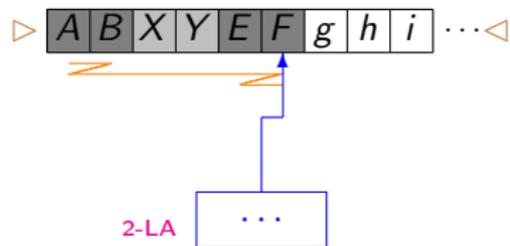
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Simulation of 2-LAs by PDAs

Initial configuration



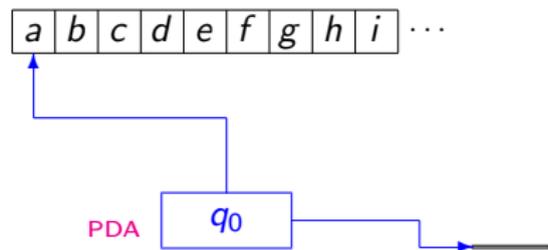
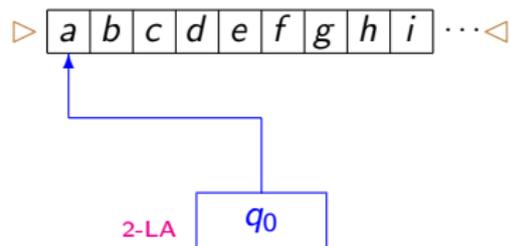
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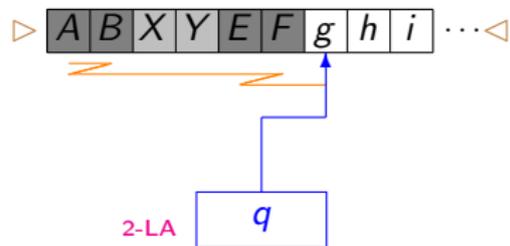
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Simulation of 2-LAs by PDAs

Initial configuration



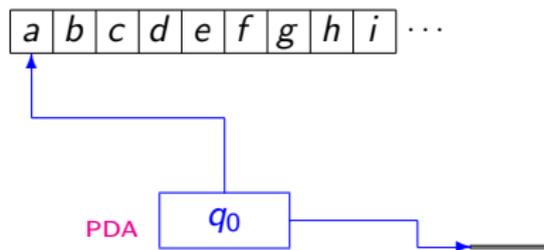
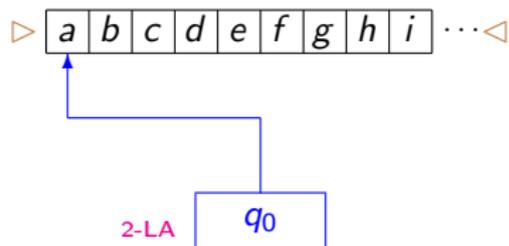
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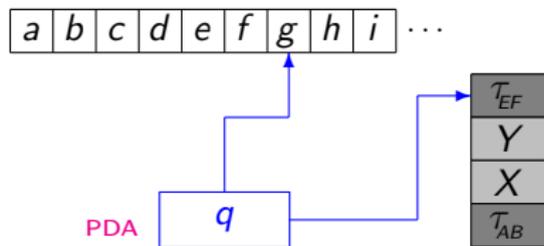
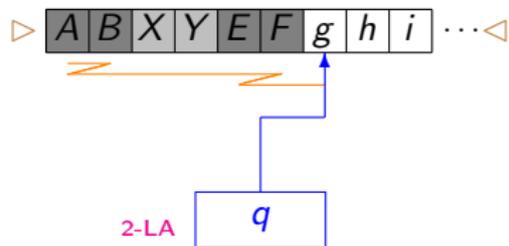
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Simulation of 2-LAs by PDAs

Initial configuration

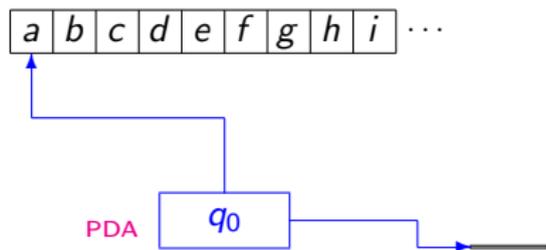
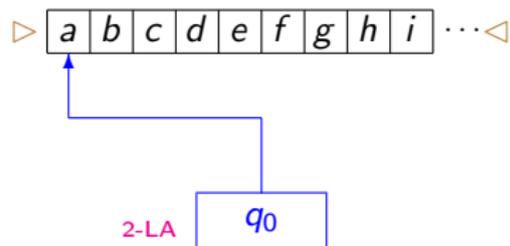


After some steps...

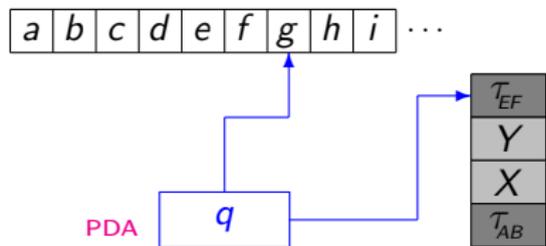
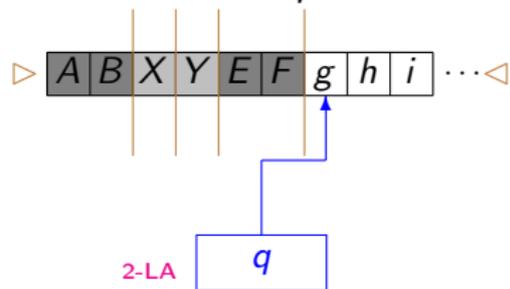


Simulation of 2-LAs by PDAs

Initial configuration

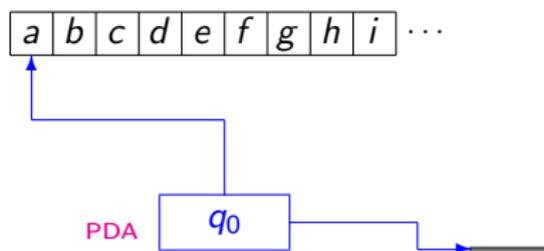
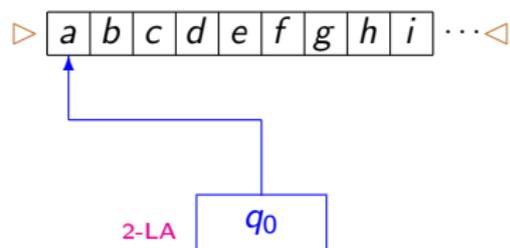


After some steps...

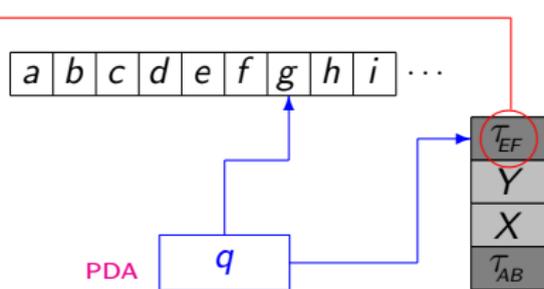
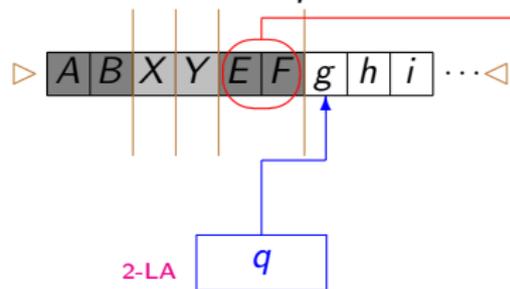


Simulation of 2-LAs by PDAs

Initial configuration

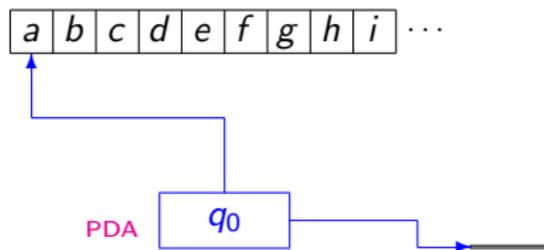
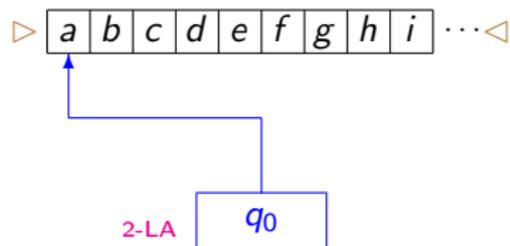


After some steps...

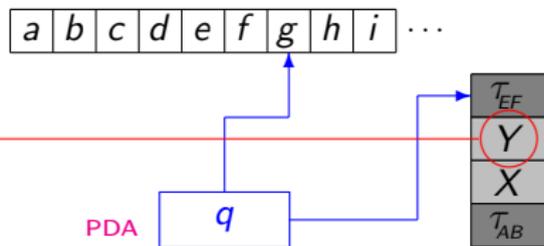
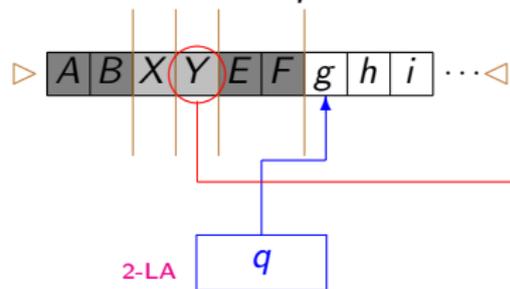


Simulation of 2-LAs by PDAs

Initial configuration

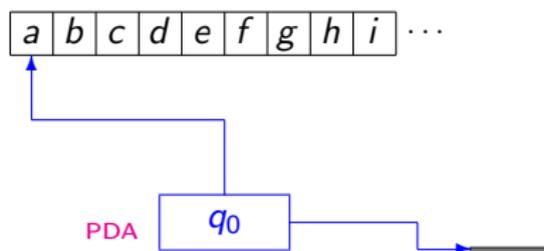
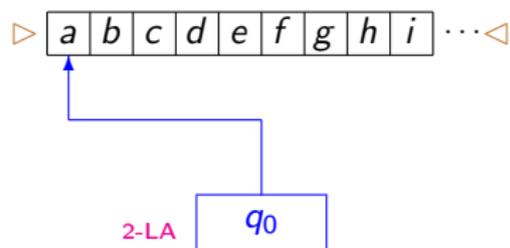


After some steps...

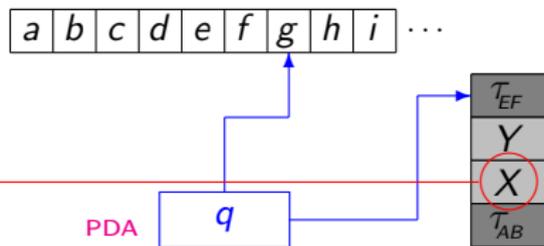
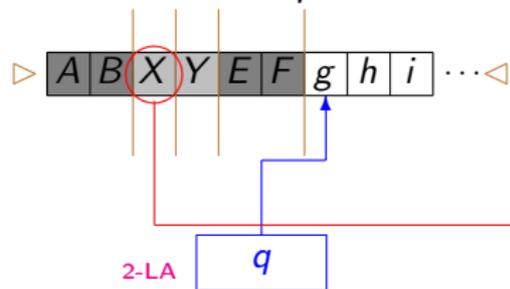


Simulation of 2-LAs by PDAs

Initial configuration

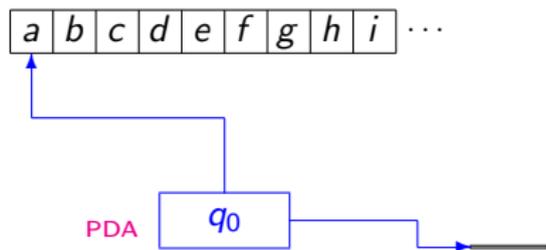
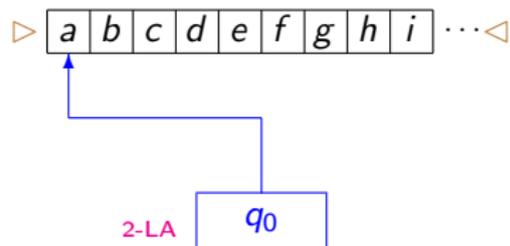


After some steps...

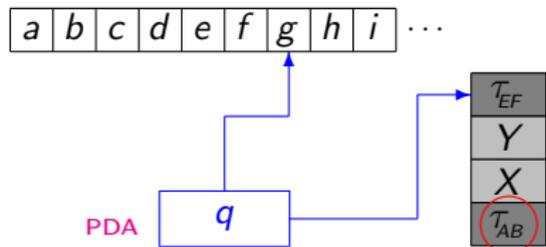
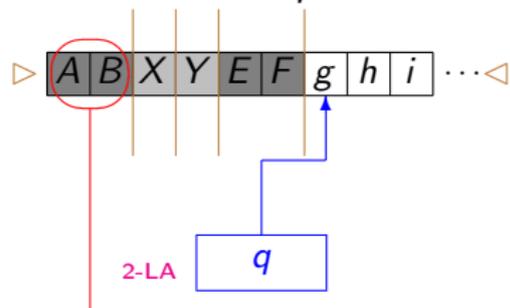


Simulation of 2-LAs by PDAs

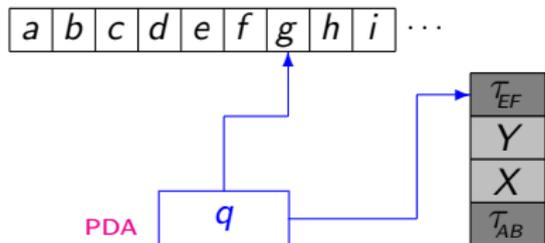
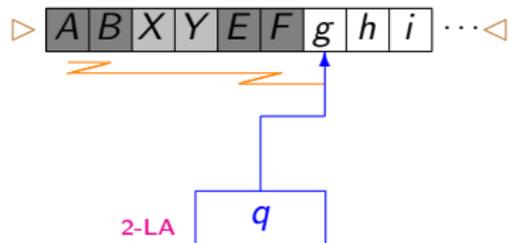
Initial configuration



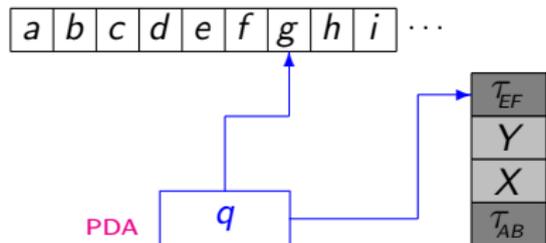
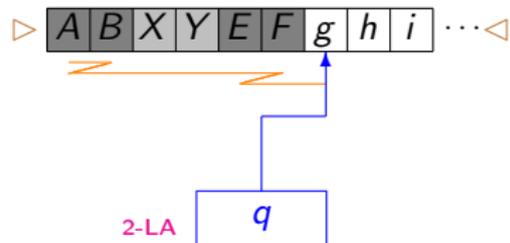
After some steps...



Simulation of 2-LAs by PDAs

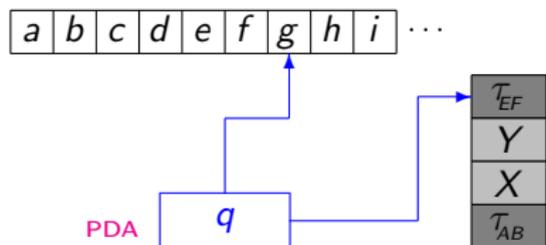
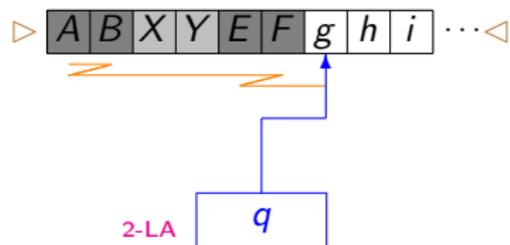


Simulation of 2-LAs by PDAs

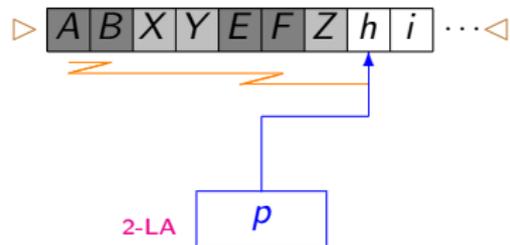


$\delta(q, g) \ni (p, Z, +1)$
move to the right
 \Downarrow

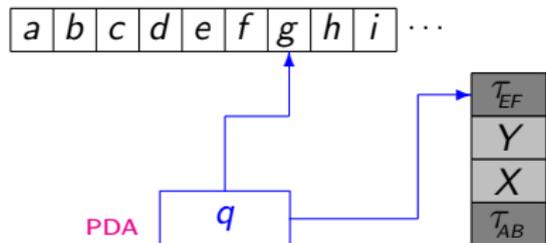
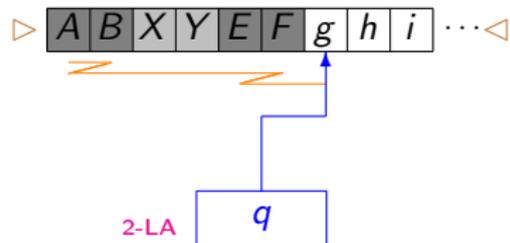
Simulation of 2-LAs by PDAs



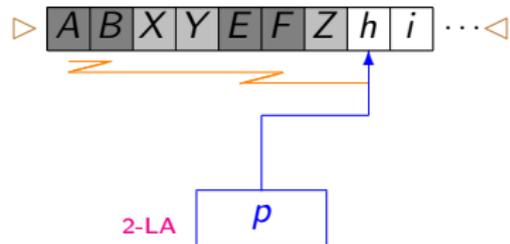
$\delta(q, g) \ni (p, Z, +1)$
 move to the right



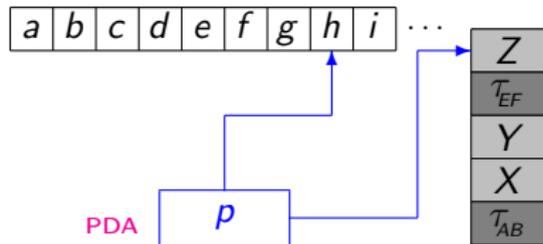
Simulation of 2-LAs by PDAs



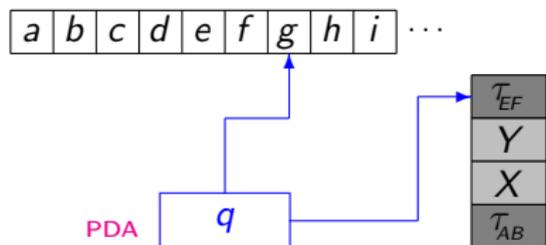
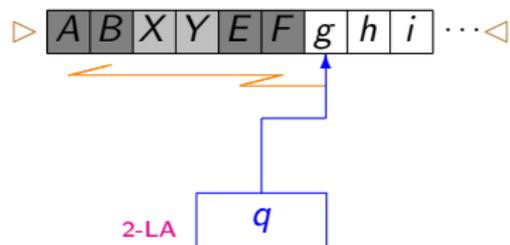
$\delta(q, g) \ni (p, Z, +1)$
move to the right



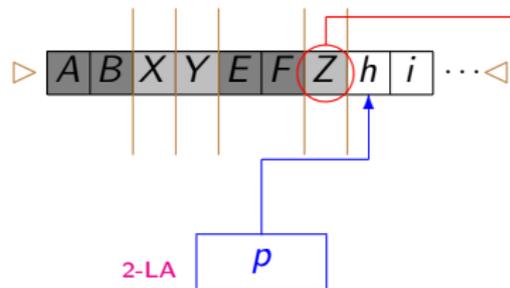
normal mode
push and direct simulation



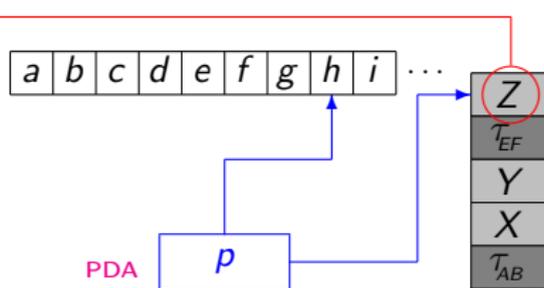
Simulation of 2-LAs by PDAs



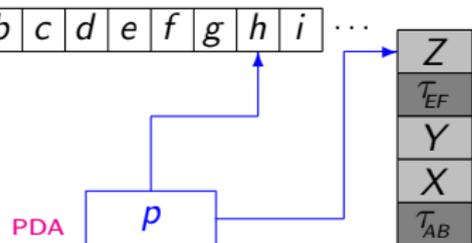
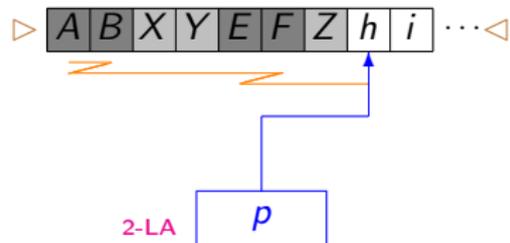
$\delta(q, g) \ni (p, Z, +1)$
move to the right



normal mode
push and direct simulation



Simulation of 2-LAs by PDAs

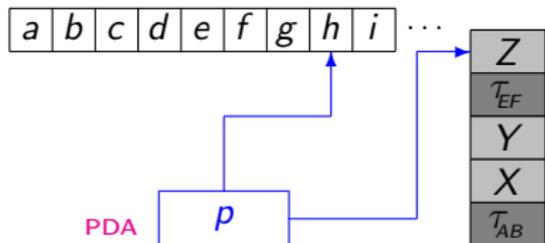
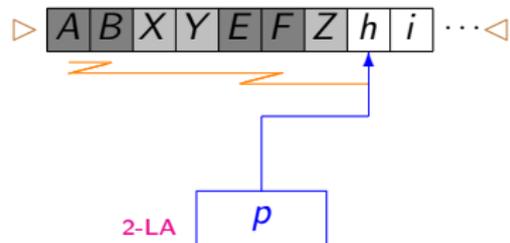


$$\delta(p, h) \ni (r, H, -1)$$

move to the left

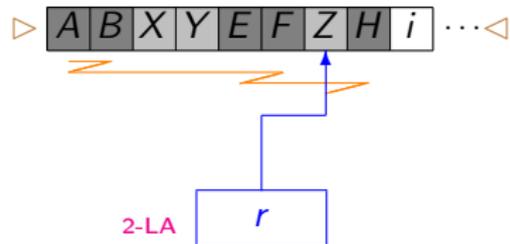


Simulation of 2-LAs by PDAs

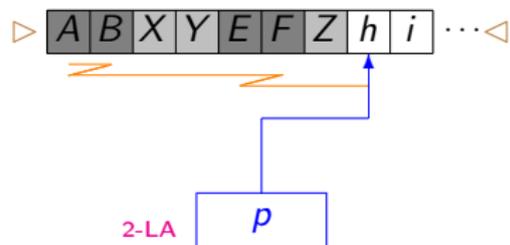


$$\delta(p, h) \ni (r, H, -1)$$

move to the left



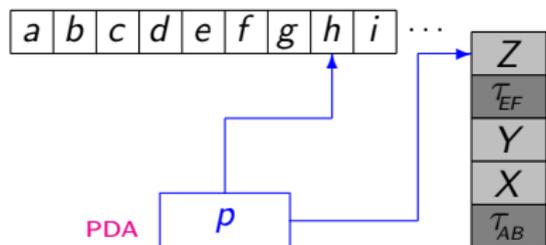
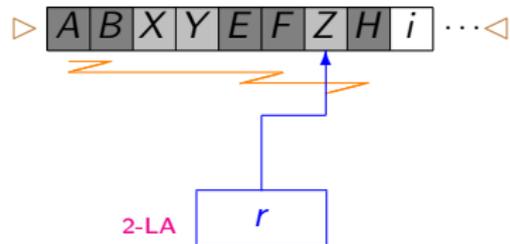
Simulation of 2-LAs by PDAs



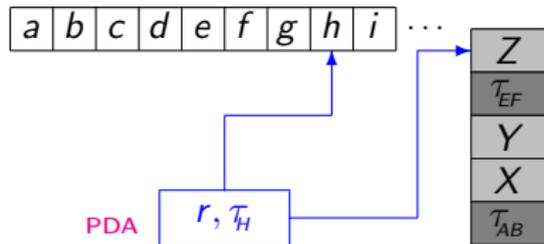
$$\delta(p, h) \ni (r, H, -1)$$

move to the left

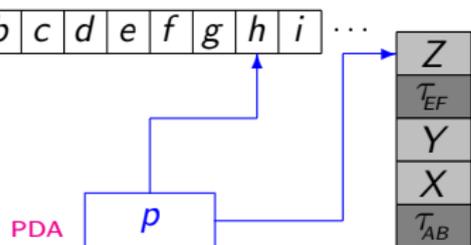
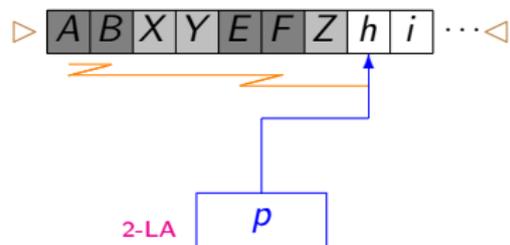
⇓



back mode



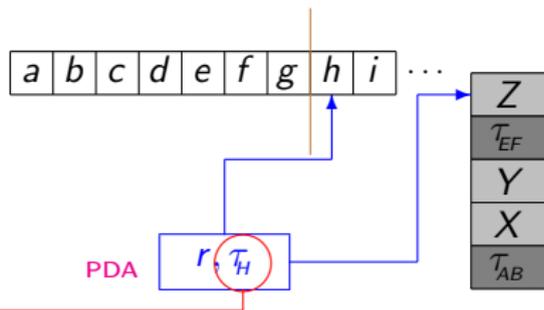
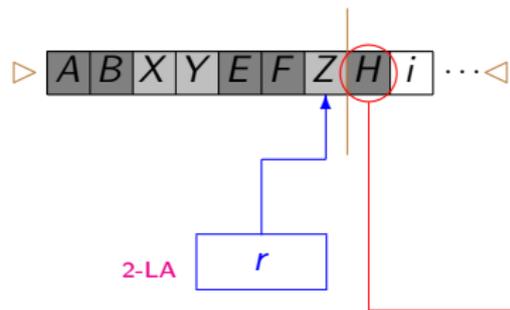
Simulation of 2-LAs by PDAs



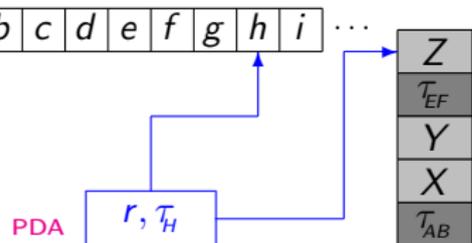
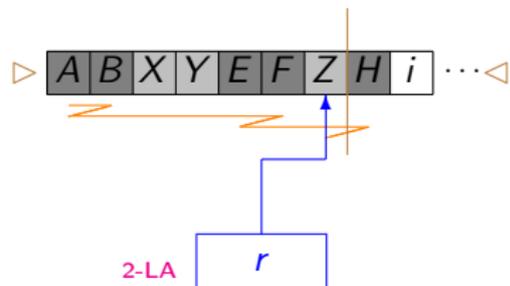
$$\delta(p, h) \ni (r, H, -1)$$

move to the left

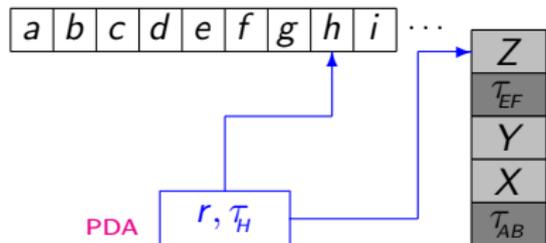
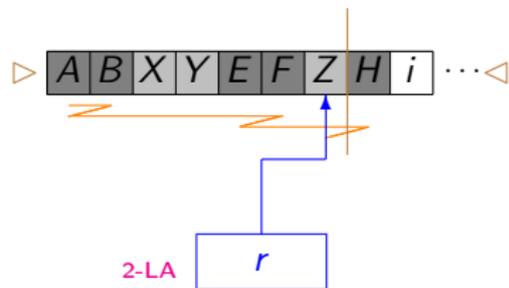
back mode



Simulation of 2-LAs by PDAs



Simulation of 2-LAs by PDAs

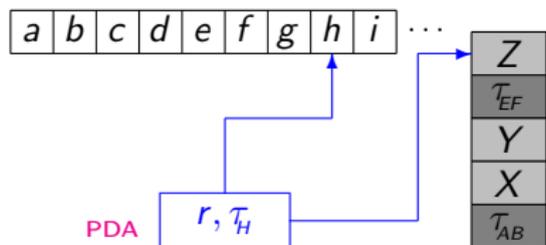
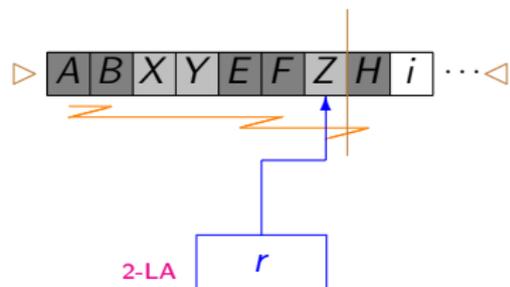


$$\delta(r, Z) \ni (q, G, -1)$$

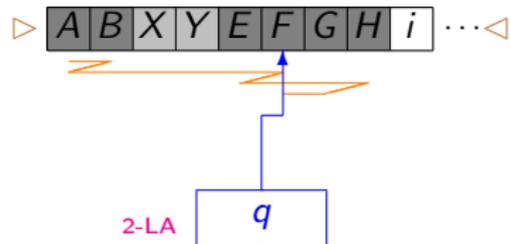
move to the left



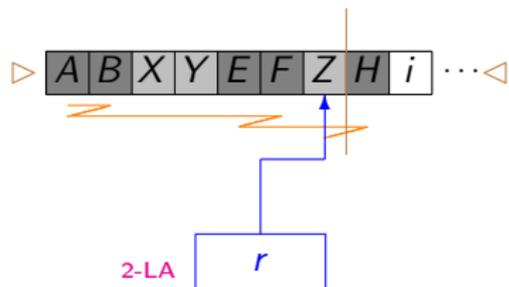
Simulation of 2-LAs by PDAs



$\delta(r, Z) \ni (q, G, -1)$
move to the left

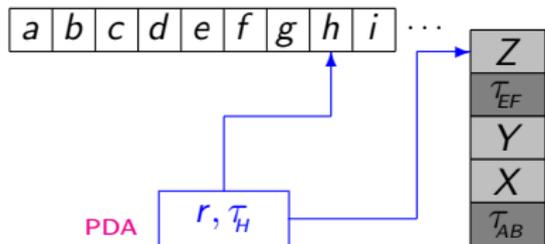
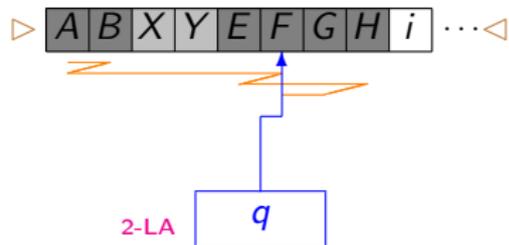


Simulation of 2-LAs by PDAs

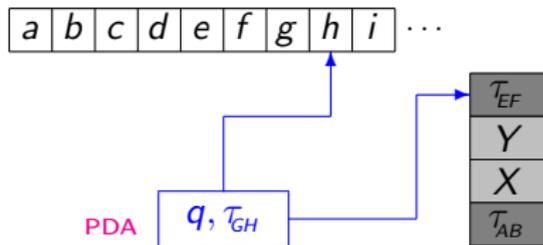


$$\delta(r, Z) \ni (q, G, -1)$$

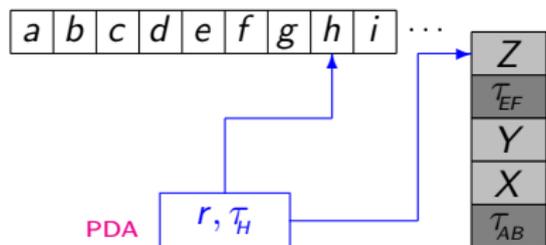
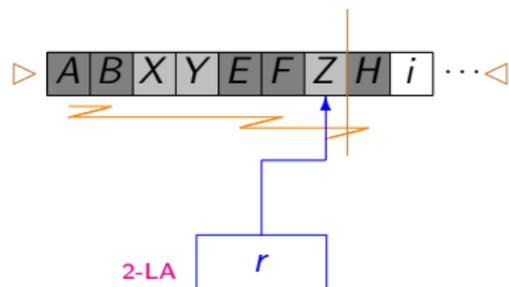
move to the left



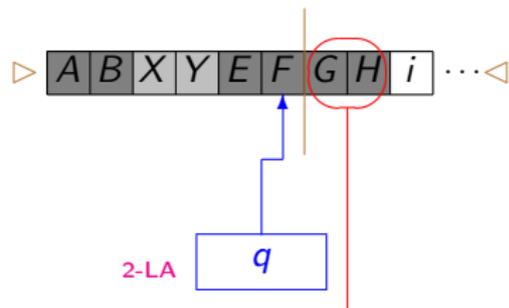
back mode



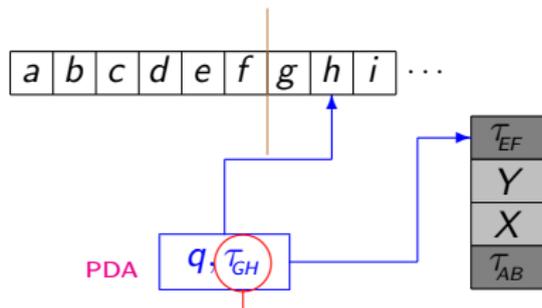
Simulation of 2-LAs by PDAs



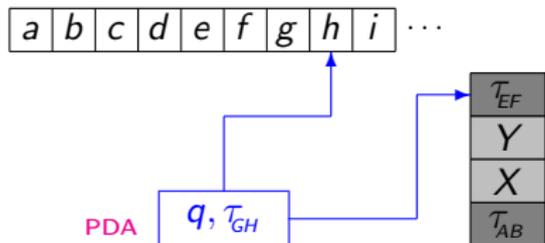
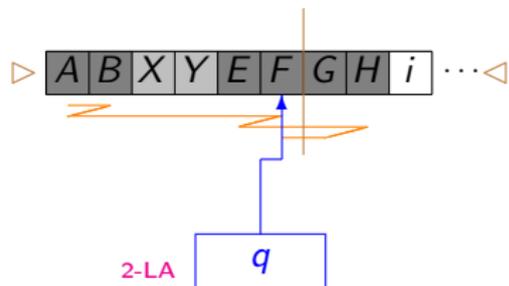
$\delta(r, Z) \ni (q, G, -1)$
move to the left



back mode

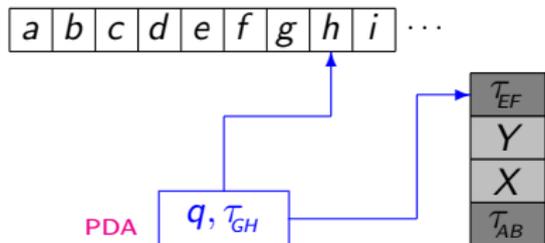
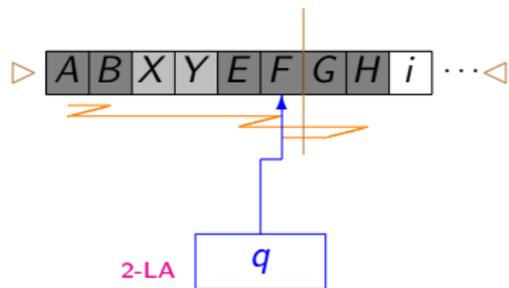


Simulation of 2-LAs by PDAs

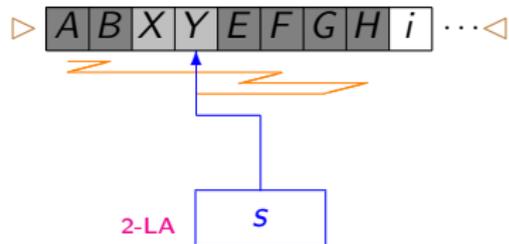


$(q, +1, s, -1) \in T_{EF}$
exit to the left
⇓

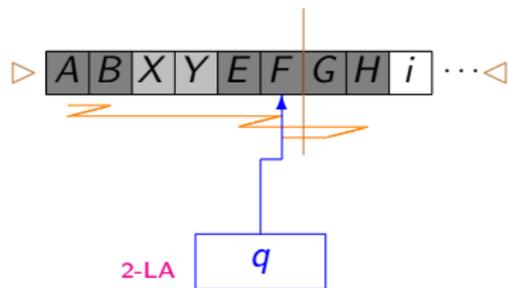
Simulation of 2-LAs by PDAs



$(q, +1, s, -1) \in T_{EF}$
exit to the left



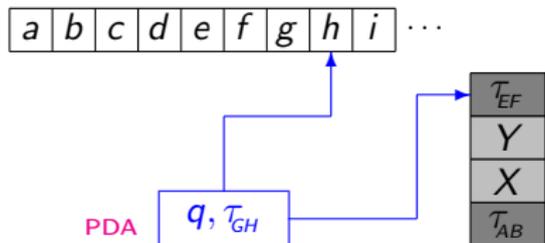
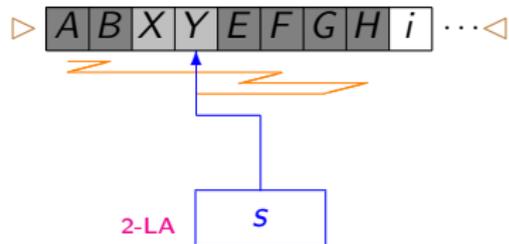
Simulation of 2-LAs by PDAs



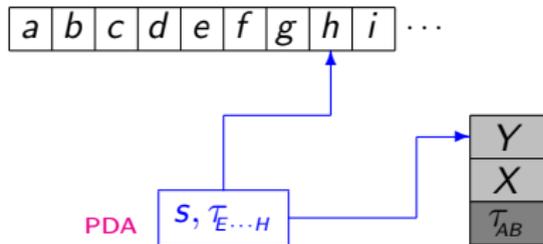
$$(q, +1, s, -1) \in \mathcal{T}_{EF}$$

exit to the left

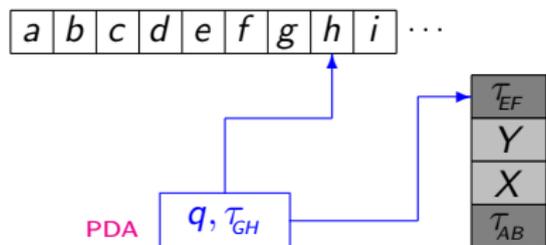
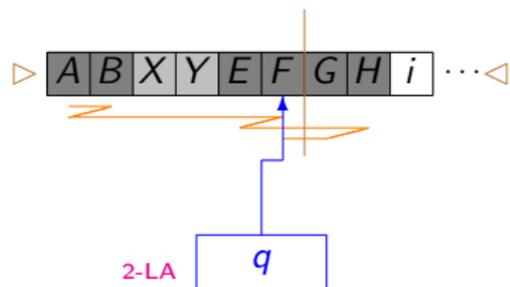
⇓



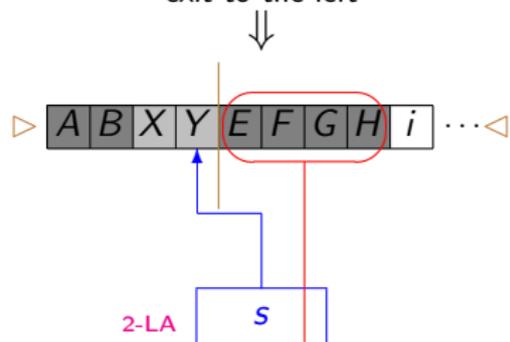
back mode



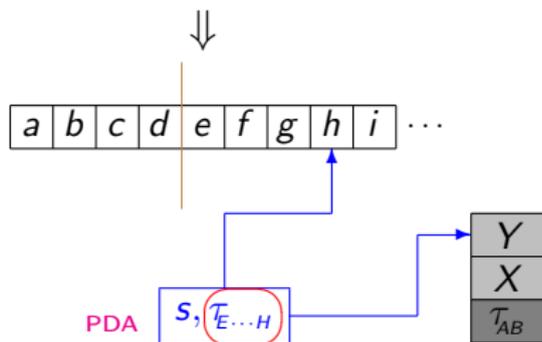
Simulation of 2-LAs by PDAs



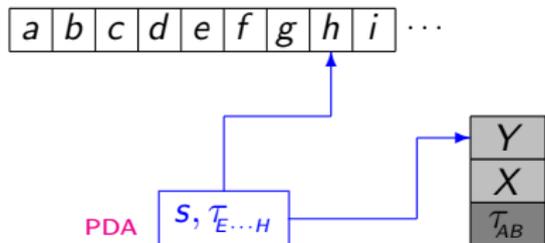
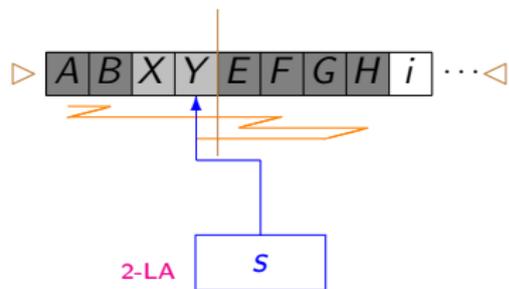
$(q, +1, s, -1) \in T_{EF}$
exit to the left



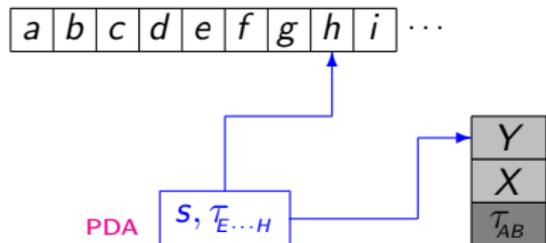
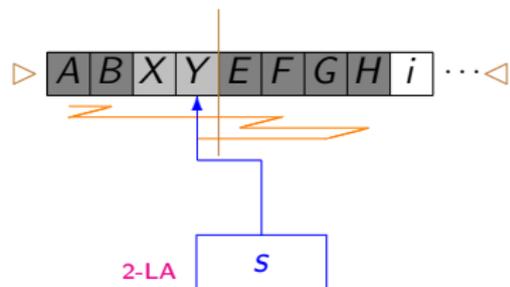
back mode



Simulation of 2-LAs by PDAs

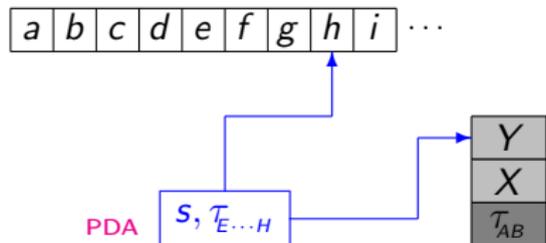
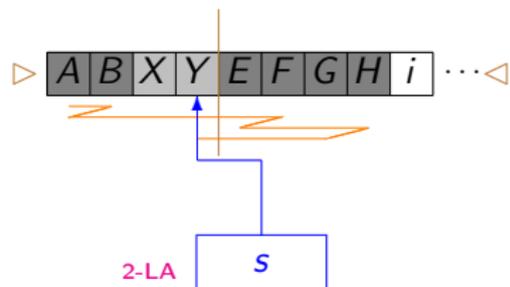


Simulation of 2-LAs by PDAs

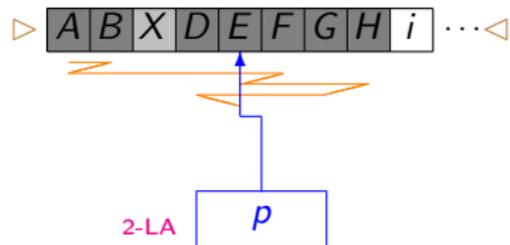


$\delta(s, Y) \ni (p, D, +1)$
move to the right
⇓

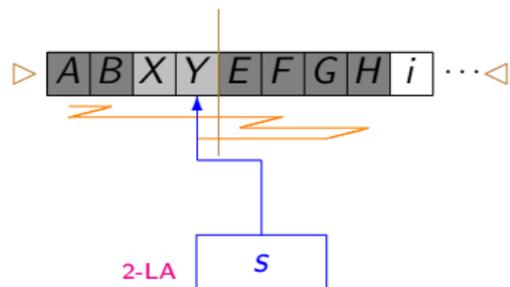
Simulation of 2-LAs by PDAs



$\delta(s, Y) \ni (p, D, +1)$
move to the right

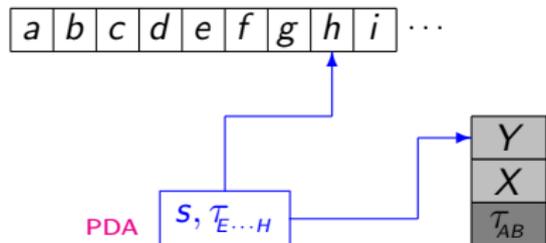
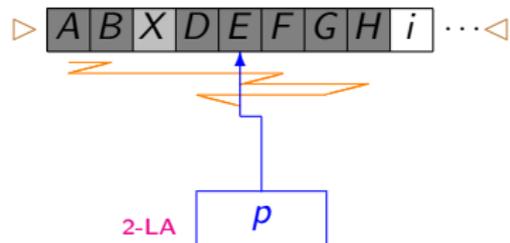


Simulation of 2-LAs by PDAs

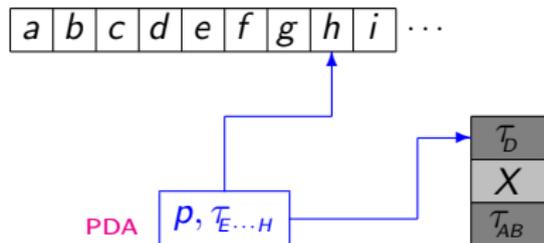


$$\delta(s, Y) \ni (p, D, +1)$$

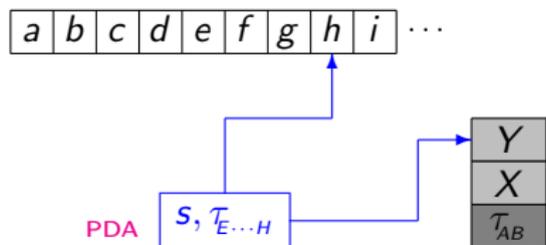
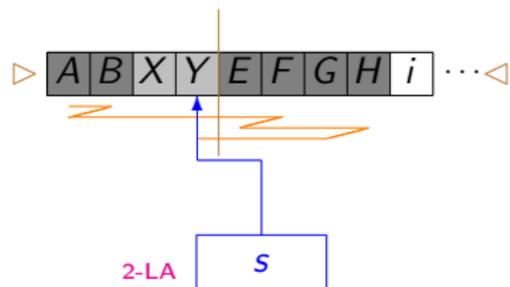
move to the right



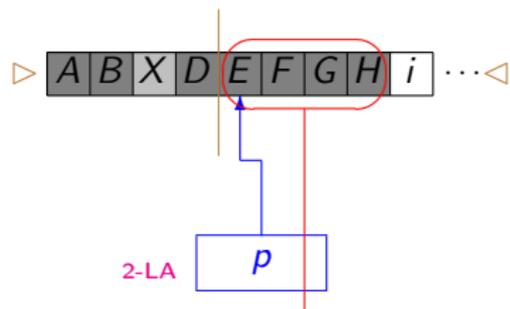
back mode



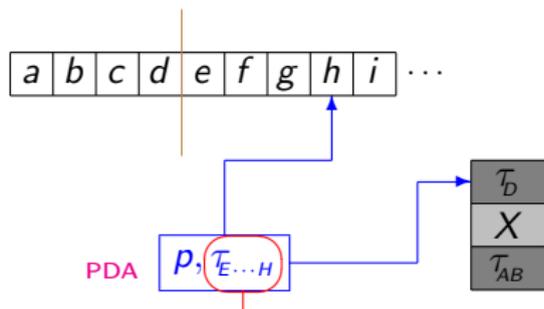
Simulation of 2-LAs by PDAs



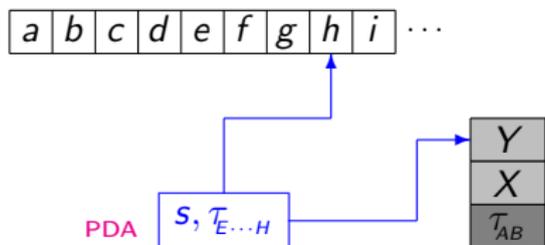
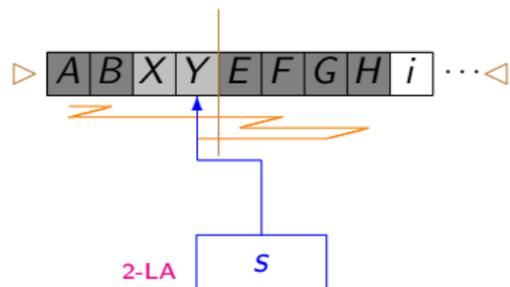
$\delta(s, Y) \ni (p, D, +1)$
move to the right



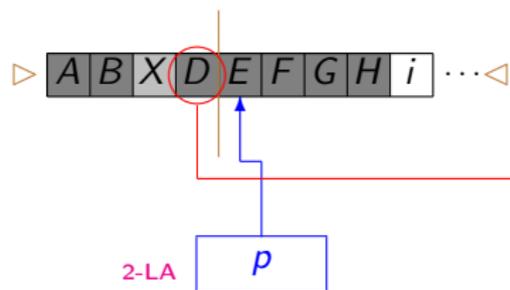
back mode



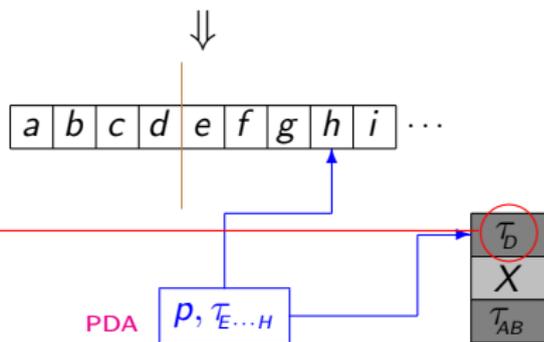
Simulation of 2-LAs by PDAs



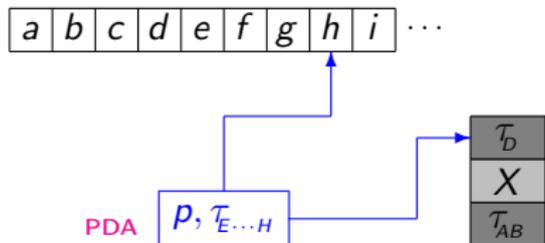
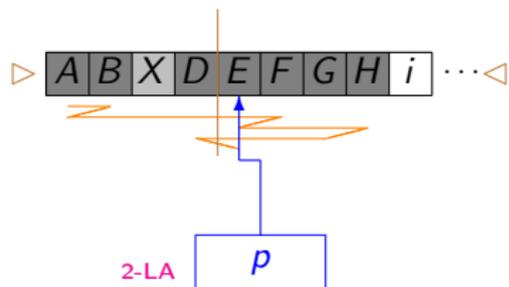
$\delta(s, Y) \ni (p, D, +1)$
move to the right



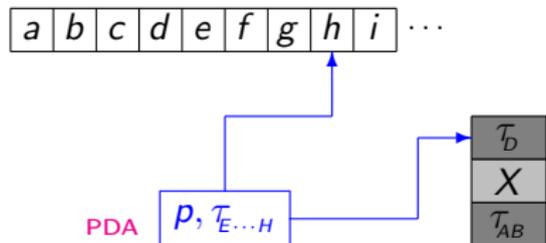
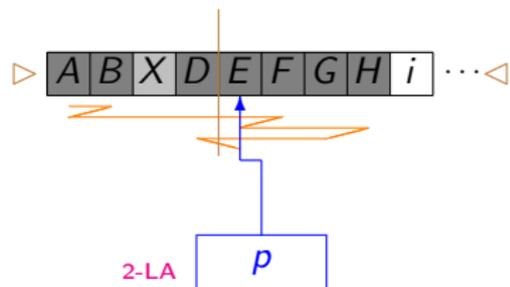
back mode



Simulation of 2-LAs by PDAs

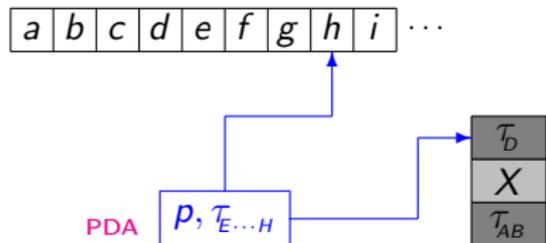
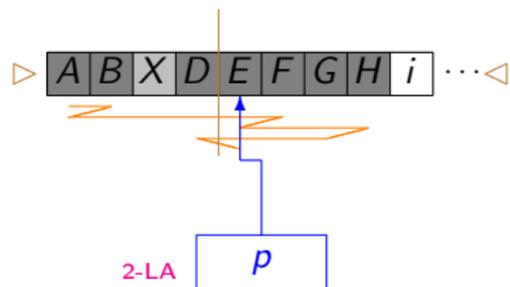


Simulation of 2-LAs by PDAs

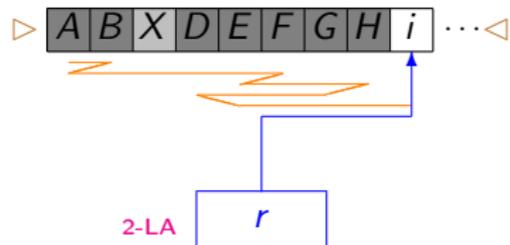


$(p, -1, r, +1) \in \mathcal{T}_{E...H}$
exit to the right
⇓

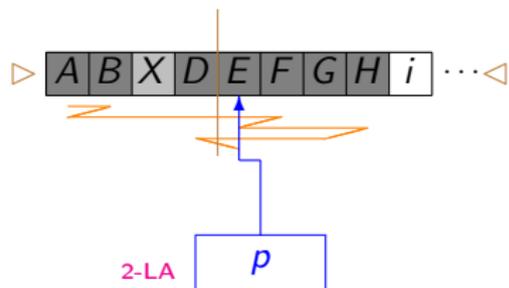
Simulation of 2-LAs by PDAs



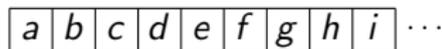
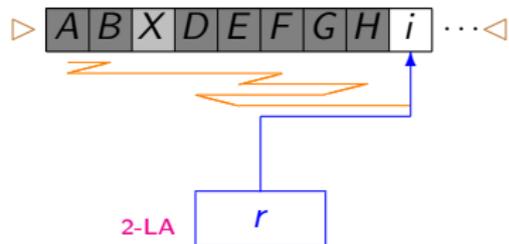
$(p, -1, r, +1) \in T_{E\dots H}$
exit to the right



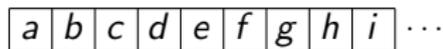
Simulation of 2-LAs by PDAs



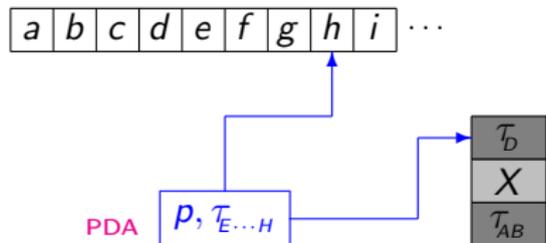
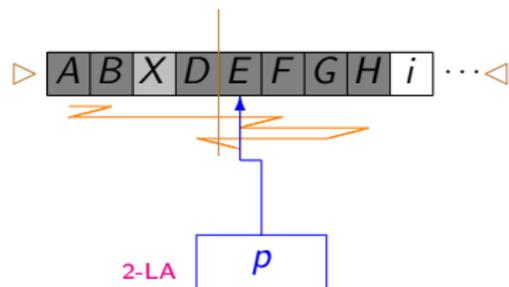
$(p, -1, r, +1) \in \tau_{E\dots H}$
exit to the right



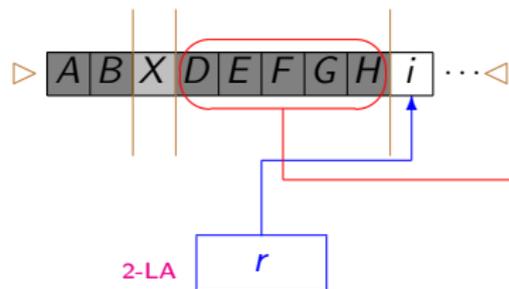
resume normal mode
move to the right



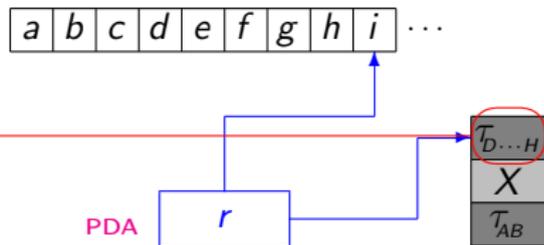
Simulation of 2-LAs by PDAs



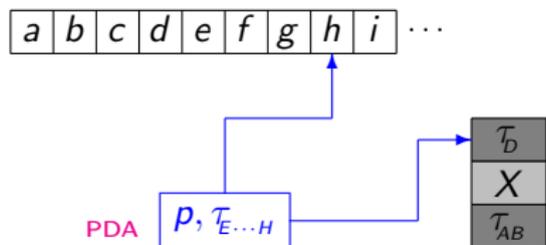
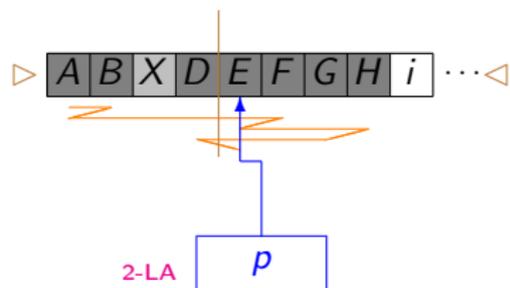
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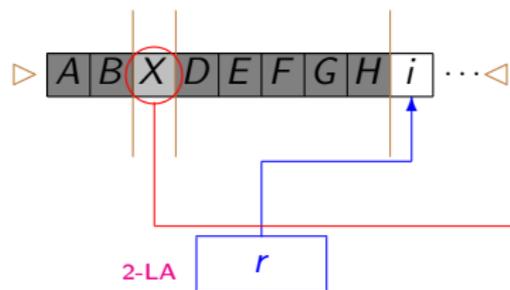
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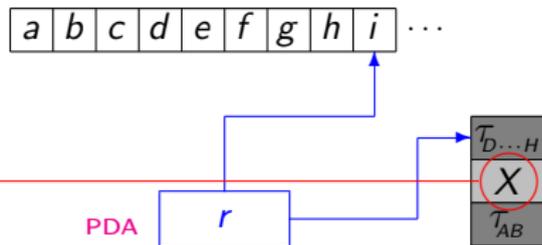
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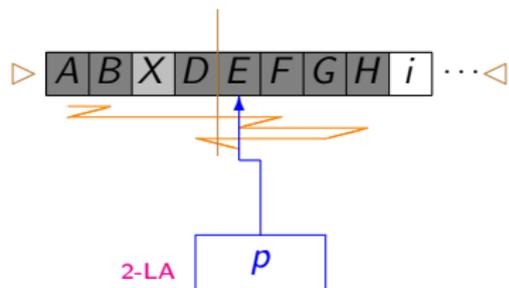
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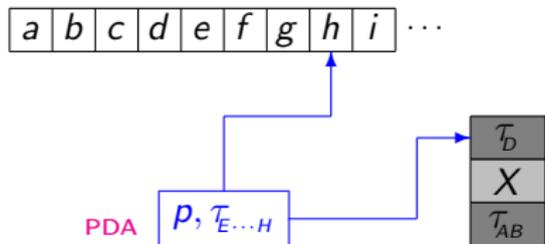
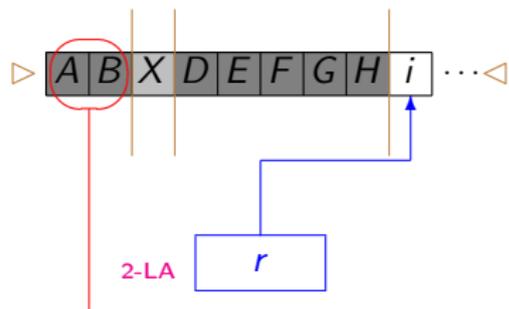
resume normal mode
move to the right



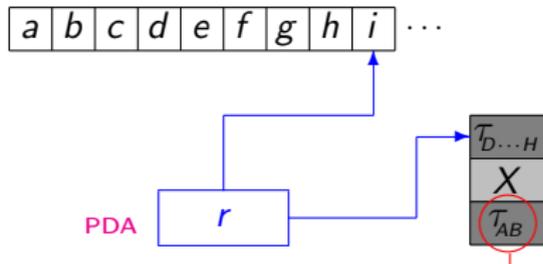
Simulation of 2-LAs by PDAs



$(p, -1, r, +1) \in \tau_{E\dots H}$
exit to the right



resume normal mode
move to the right



Simulation of 2-LAs by PDAs

Summing up...

Given a 2-LA M with:

- ▶ n states
- ▶ m symbol working alphabet

Simulation of 2-LAs by PDAs

Summing up...

Given a 2-LA M with:

- ▶ n states At most 2^{4n^2} many different tables!
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Resulting PDA:

- ▶ States
 - Normal mode: states of M
 - Back mode: (q, τ)
 q state of M , τ transition table

States
$2n(2^{4n^2} + 1) + 1$

Simulation of 2-LAs by PDAs

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▶ n states

At most 2^{4n^2} many different tables!

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Resulting PDA:

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▶ Pushdown symbols

■ Tape symbols of M

■ Transition tables

States

$$2n(2^{4n^2} + 1) + 1$$

Pushdown symbols

$$m + 2^{4n^2}$$

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Simulation of 2-LAs by PDAs

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q state of M , τ transition table

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$$2n(2^{4n^2} + 1) + 1$$

▶ Pushdown symbols

■ Tape symbols of M

■ Transition tables

Pushdown symbols

$$m + 2^{4n^2}$$

▶ Each move can increase the stack height at most by 1

2-LAs \rightarrow PDAs

Exponential cost

Optimality: the Witness Languages K_n

Given $n \geq 1$:

$$K_n =$$

Optimality: the Witness Languages K_n

Given $n \geq 1$:

$$\underbrace{a_1 \ a_2 \ \cdots \ a_n}_{x_1} \ \cdots \ \underbrace{a_{n+1} \ a_{n+2} \ \cdots \ a_{2n}}_{x_k} \ \underbrace{b_1 \ b_2 \ \cdots \ b_n}_x$$

$$K_n = \{x_1 x_2 \cdots x_k x \mid k \geq 0, x_1, x_2, \dots, x_k, x \in \{0, 1\}^n\},$$

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...

At least n of these blocks are equal
to the last block x

$$K_n = \{x_1 x_2 \cdots x_k x \mid k \geq 0, x_1, x_2, \dots, x_k, x \in \{0, 1\}^n, \\ \exists i_1 < i_2 < \cdots < i_n \in \{1, \dots, k\}, \\ x_{i_1} = x_{i_2} = \cdots = x_{i_n} = x\}$$

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Example ($n = 3$): 0 0 1 1 1 0 0 1 1 1 1 0 1 1 0 1 1 1 1 1 0

Optimality: the Witness Languages K_n

Given $n \geq 1$:

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Example ($n = 3$): 0 0 1|1 1 0|0 1 1|1 1 0|1 1 0|1 1 1|1 1 0

Optimality: the Witness Languages K_n

Given $n \geq 1$:

$$\underbrace{a_1 \ a_2 \ \cdots \ a_n}_{x_1} \ \cdots \ \underbrace{a_{n+1} \ a_{n+2} \ \cdots \ a_{2n}}_{x_k} \ \underbrace{b_1 \ b_2 \ \cdots \ b_n}_x$$

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At least n of these blocks are equal
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$$K_n = \{x_1 x_2 \cdots x_k x \mid k \geq 0, x_1, x_2, \dots, x_k, x \in \{0, 1\}^n, \\ \exists i_1 < i_2 < \cdots < i_n \in \{1, \dots, k\}, \\ x_{i_1} = x_{i_2} = \cdots = x_{i_n} = x\}$$

Example ($n = 3$): 0 0 1 | 1 1 0 | 0 1 1 | 1 1 0 | 1 1 0 | 1 1 1 | 1 1 0

How to Recognize K_n

001110011110110111110 $(n = 3)$

1. Scan all the tape from left to right
2. Start to move to the left and mark the rightmost n symbols
3. Compare each block of length n (from the right), symbol by symbol, with the last block
4. When the left end of the tape is reached accept if and only if the number of block equal to the last one is $\geq n$

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Complexity:

- ▶ K_n is accepted by a deterministic 2-LA with $O(n^2)$ states and a fixed working alphabet
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Simulation of 2-LAs by PDAs

Cost of the simulation

- ▶ Exponential size for the simulation of 2-LAs by PDAs
- ▶ Optimal

Computational Power of Limited Automata

From the simulations:

- ▶ 2-Limited Automata \equiv CFLs

What about d -Limited Automata, with $d > 2$?

- ▶ They still characterize CFLs [Hibbard '67]
- ▶ They can be simulated by exponentially larger PDAs [Kutrib&P.&Wendlandt subm.]

What about 1-Limited Automata?

- ▶ Regular languages [Vogel & Wechsung '38]

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is accepted by a *deterministic* 3-LA, but is not a DCFL

▶ Infinite hierarchy [Hibbard '67]

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1-Limited Automata

Simulation of 1-Limited Automata by Finite Automata

Main idea: transformation of *two-way* NFAs into *one-way* DFAs
[Shepherdson '59]

- ▶ First visit to a cell: direct simulation
- ▶ Further visits: *transition tables*

- ▶ Finite control of the DFA which simulates the two-way NFA:



- transition table of the already scanned input prefix
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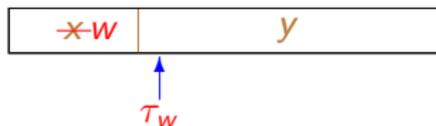


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The simulating DFA keeps in its finite control a
sets of transition tables

1-Limited Automata \rightarrow Finite Automata: Upper Bounds

Theorem

Let M be a 1-LA with n states.

- ▶ There exists an equivalent DFA with $2^{n \cdot 2^{n^2}}$ states.
- ▶ There exists an equivalent NFA with $n \cdot 2^{n^2}$ states.

If M is deterministic then there exists an equivalent DFA with no more than $n \cdot (n + 1)^n$ states.

	DFA	NFA
nondet. 1-LA		
det. 1-LA		

These upper bounds do not depend on the alphabet size of M !

The gaps are optimal!

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How to Recognize L_n : 1-Limited Automata

- ▶ Nondeterministic strategy:
Guess the leftmost positions of n input blocks containing the same factor and *Verify*
- ▶ Implementation (3 tape scans):
 1. Mark n tape cells
 2. Count the tape modulo n to check whether or not:
 - ▶ the input length is a multiple of n , and
 - ▶ the marked cells correspond to the leftmost symbols of some blocks of length n
 3. Compare, symbol by symbol, each two consecutive blocks of length n that start from the marked positions
- ▶ $O(n)$ states

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How to Recognize L_n : Deterministic Finite Automata

▶ Idea:

- For each $x \in \{0, 1\}^n$ count how many blocks coincide with x
- Accept if and only if one of the counters reaches the value n

▶ State upper bound:

- Finite control:
 - a counter (up to n) for each possible block of length n
- There are 2^n possible different blocks of length n
- Number of states double exponential in n
more precisely $(2^n - 1) \cdot n^{2^n} + n$

▶ State lower bound:

- n^{2^n} (standard distinguishability arguments)

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- ▶ **State upper bound:**
 - Finite control:
 - a counter (up to n) for each possible block of length n
 - There are 2^n possible different blocks of length n
 - Number of states double exponential in n
more precisely $(2^n - 1) \cdot n^{2^n} + n$
- ▶ State lower bound:
 - n^{2^n} (standard distinguishability arguments)

How to Recognize L_n : Deterministic Finite Automata

- ▶ Idea:
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The state gap between 1-LAs and DFAs is double exponential!

How to Recognize L_n : Nondeterministic Finite Automata

- ▶ Idea:
 - *Guess* $x \in \{0, 1\}^n$
 - *Verify* whether or not n blocks in the input contains x
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 - Finite control: a counter $\leq n$ for the occurrences of x , and a counter modulo n for input positions
 - Number of states: $O(n^2 \cdot 2^n)$
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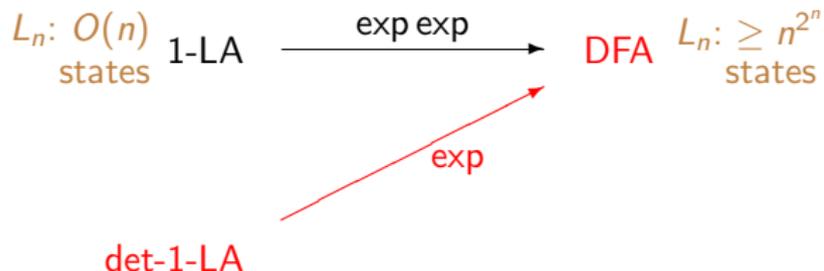
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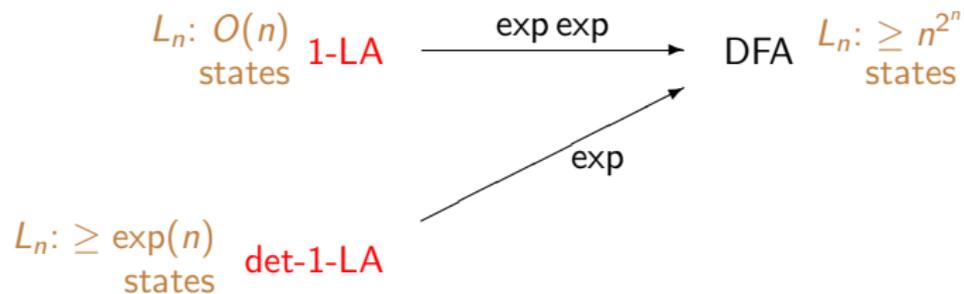
Nondeterminism vs. Determinism in 1-LAs

$L_n: O(n)$
states 1-LA $\xrightarrow{\text{exp exp}}$ DFA $L_n: \geq n^{2^n}$
states

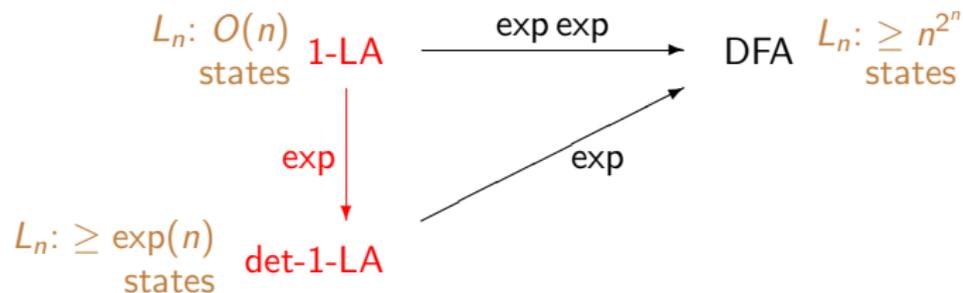
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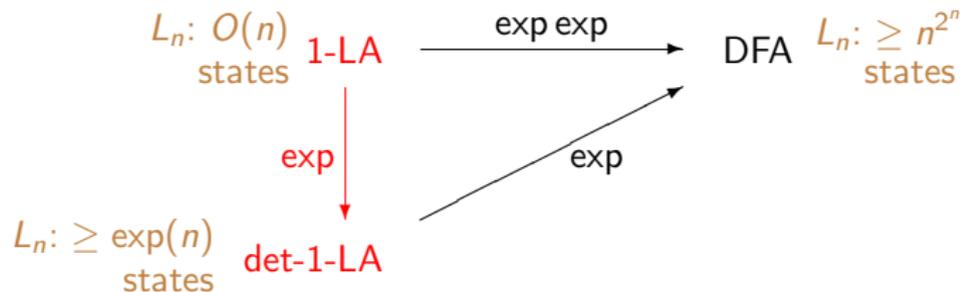
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Corollary

Removing nondeterminism from 1-LAs requires exponentially many states

Nondeterminism vs. Determinism in 1-LAs



Corollary

Removing nondeterminism from 1-LAs requires exponentially many states

Cfr. Sakoda and Sipser question [Sakoda&Sipser '78]:

How much it costs in states to remove nondeterminism from two-way finite automata?

Strongly Limited Automata

Different Restrictions

- ▶ Dyck languages are accepted without fully using capabilities of 2-limited automata
- ▶ Chomsky-Schützenberger Theorem: Recognition of CFLs can be reduced to recognition of Dyck languages

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Is it possible to restrict 2-limited automata without affecting their computational power?

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Question

Is it possible to restrict 2-limited automata without affecting their computational power?

YES!

Forgetting Automata

[Jancar&Mráz&Plátek '96]

- ▶ The content of any cell can be erased in the 1st or 2nd visit (using a fixed symbol)
- ▶ No other changes of the tape are allowed

- ▶ Model inspired by the algorithm used by 2-limited automata to recognize Dyck languages
- ▶ Restrictions on
 - state changes
 - head reversals
 - rewriting operations

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Dyck Language Recognition



- ▶ Moves to the right:
 - to search a closed bracket
- ▶ Moves to the left:
 - to search an open bracket
 - to check the tape content in the final scan from right to left
- ▶ Rewritings:
 - each closed bracket is rewritten in the first visit
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 - no rewritings in the final scan

Dyck Language Recognition



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Only one state q_0 !

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Strongly Limited Automata

- ▶ Alphabet

 - Σ input

 - Γ working

- ▶ States and moves

 - ▶ initial state, moving from left to right

 - ▶ moving from right to left

 - ▶ moves in which head moves from right to left and

 - reads the contents of the tape cell on which it is currently positioned

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 - when \triangleleft is reached move from right to left and test the membership of the tape content to a "local" language

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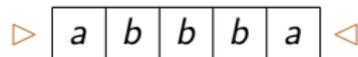
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Strongly Limited Automata: Palindromes

$$\Sigma = \{a, b\}, \Gamma = \{X, Y, Z\}$$

q_0

$$Q_L = \{q_a, q_b\}$$

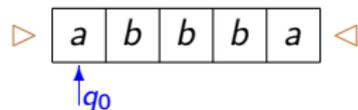


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Transitions:

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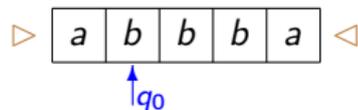
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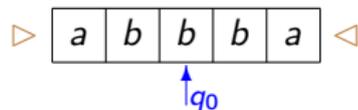
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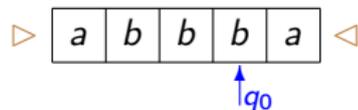
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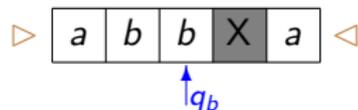
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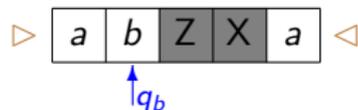
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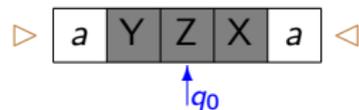
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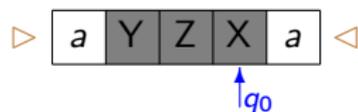
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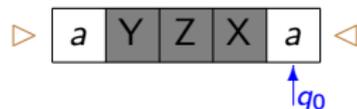
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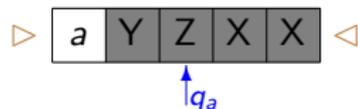
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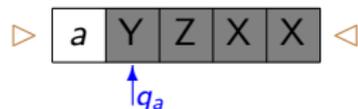
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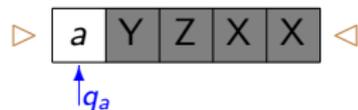
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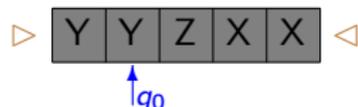
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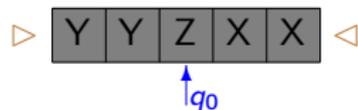
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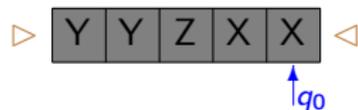
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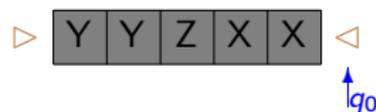
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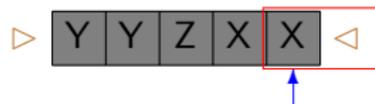
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with the exceptions of inputs of length ≤ 1

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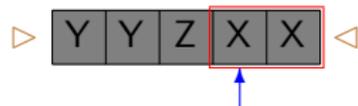
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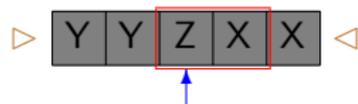
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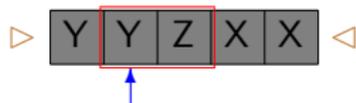
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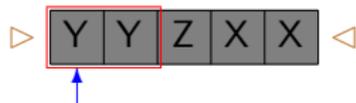
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- ▶ Descriptive power: the sizes of equivalent
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 - PDAs
 - strongly limited automataare polynomially related
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Proper subclass of deterministic context-free languages

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Final Remarks

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[Wechsung&Brandstädt '79]

Thank you for your attention!