# Determinism versus Nondeterminism in Two-Way Finite Automata Recent Results around the Sakoda and Sipser Question

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#### Outline

**Preliminaries** 

The Question of Sakoda and Sipser

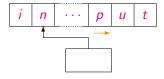
Restricted 2DFAs

The Unary Case

Relationships with  $L \stackrel{?}{=} NL$ 

Restricted 2NFAs

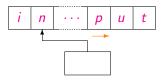
Conclusion



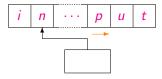
#### Base version:

one-way deterministic finite automata (1DFA)

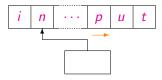
- one-way input tape
- deterministic transitions



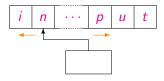
- nondeterministic transitions
  - one-way nondeterministic finite automata (1NFA)
- ▶ input head moving forth and back
  - two-way deterministic finite automata (2DFA)
  - two-way nondeterministic finite automata (2NFA)
- ▶ alternation
- **...**



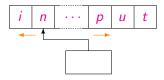
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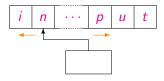
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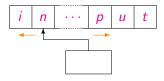
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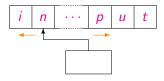
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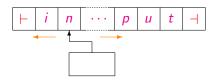


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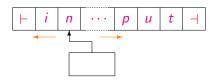
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# Two-Way Automata: Technical Details



- ▶ Input surrounded by the endmarkers  $\vdash$  and  $\dashv$
- $w \in \Sigma^*$  is accepted iff there is a computation
  - with input tape ⊢ w ⊢
  - starting at the left endmarker ⊢ in the initial state
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They share the same computational power, namely they characterize the class of *regular languages*,

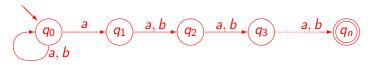
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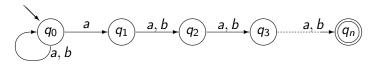
...some of them are more succinct

Example: 
$$I_n = (a + b)^* a(a + b)^{n-1}$$



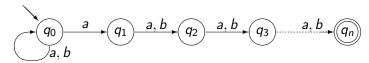
- ▶ The minimum 1DFA accepting  $I_n$  requires  $2^n$  states
- We can get a *deterministic* automaton for  $I_n$  with n + 2 states, which reverses the input head direction just one time
- ▶ Hence I<sub>n</sub> is accepted by
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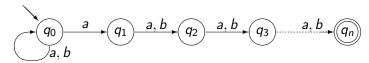
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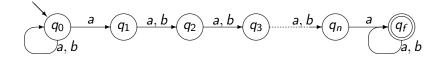


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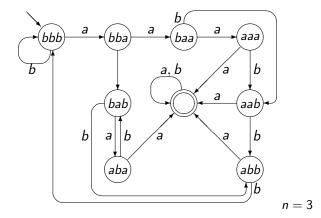
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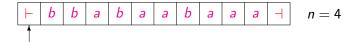
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1NFA: n + 2 states



Minimum 1DFA:  $2^n + 1$  states



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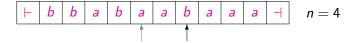
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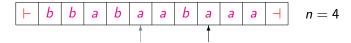
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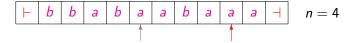
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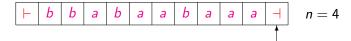
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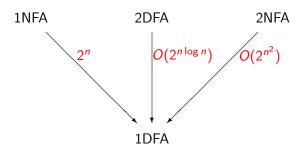
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$$\vdash$$
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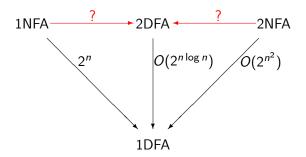
2DFA: O(n) states



[Rabin&Scott '59, Shepardson '59, Meyer&Fischer '71, ...]

#### Question

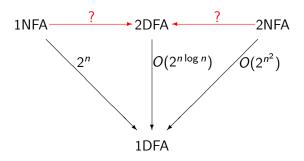
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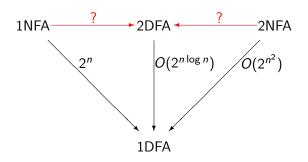
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### Conjecture

These simulations are not polynomial

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- Exponential upper bounds deriving from the simulations of 1NFAs and 2NFAs by 1DFAs
- ▶ Polynomial lower bounds for the cost c(n) of simulation of 1NFAs by 2DFAs:

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## Sakoda and Sipser Question

- Very difficult in its general form
- Not very encouraging obtained results:

Lower and upper bounds too far (Polynomial vs exponential)

► Hence:

Try to attack restricted versions of the problem!

#### 2NFAs vs 2DFAs: Restricted Versions

- (i) Restrictions on the resulting machines (2DFAs)
  - sweeping automata

[Sipser '80]

oblivious automata

[Hromkovič&Schnitger '03] [Kapoutsis '11]

- ▶ "few reversal" automata
- Restrictions on the languages
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Geffert Mereghetti&P '03]

- (iii) Restrictions on the starting machines (2NFAs)
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## Sweeping Automata

### Definition (Sweeping Automata)

A two-way automaton A is said to be sweeping if and only if

- ► A is deterministic
- ▶ the input head of A can change direction only at the endmarkers

Each computation is a sequence of complete traversals of the input

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- Oblivious automata can be exponentially smaller than sweeping automata:
  - $L_k = (\{uv \mid u, v \in \{a, b\}^k \text{ and } u \neq v\}\#)^*$
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- ▶ 1NFAs by 2DFAs
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Another possible restriction:

The unary case  $\#\Sigma = 1$ 

The costs of the optimal simulations between automata are different in the unary and in the general case

1NFA 1NFA

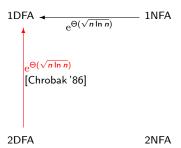
ONEA ONEA

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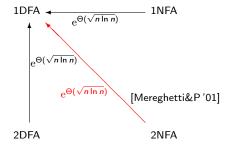
1DFA 
$$\leftarrow \frac{[\mathsf{Chrobak'86}]}{\mathrm{e}^{\Theta(\sqrt{n \ln n})}}$$
 1NFA

2DFA 2NFA

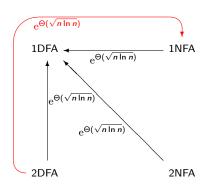
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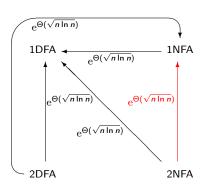


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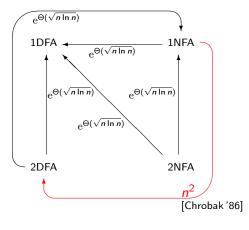
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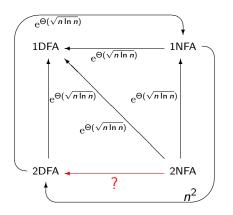
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 $\begin{array}{l} {\sf 1NFA} \rightarrow {\sf 2DFA} \\ {\sf In \ the \ unary \ case} \\ {\sf this \ question \ is \ solved!} \\ {\sf (polynomial \ conversion)} \end{array}$ 

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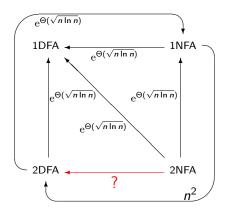


# $2NFA \rightarrow 2DFA$ *Even* in the unary case this question is open!

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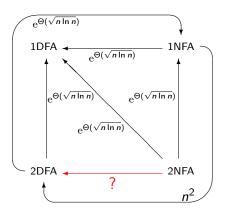


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A better upper bound  $e^{O(\ln^2 n)}$  has been proved!



## Sakoda&Sipser Question: Current Knowledge

Upper bounds

	1NFA→ 2DFA	2NFA→ 2DFA
unary case	O(n²) optimal	$e^{O(\ln^2 n)}$
general case	exponential	exponential

Unary case [Chrobak '86, Geffert Mereghetti&P '03]

Lower Bounds
In all the cases, the best known lower bound is  $\Omega(n^2)$ [Chrobak '86]

# Unary Case: Quasi Sweeping Automata [Geffert Mereghetti&P'03]

In the study of unary 2NFA, sweeping automata with some restricted nondeterministic capabilities turn out to be very useful:

#### **Definition**

A 2NFA is quasi sweeping (qsNFA) iff both

 nondeterministic choices and head reversals are possible only at the endmarkers

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#### Definition

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 nondeterministic choices and head reversals are possible only at the endmarkers

### Theorem (Quasi Sweeping Simulation)

Each n-state unary 2NFA A can be transformed into a 2NFA M s.t.

- ► M is quasi sweeping
- ▶ M has at most  $N \le 2n + 2$  states
- ► M and A are "almost equivalent" (differences are possible only for inputs of length  $\leq 5n^2$ )



# Several results using quasi sweeping simulation of unary 2NFAs have been found:

- (i) Subexponential simulation of unary 2NFAs by 2DFAs Each unary n-state 2NFA can be simulated by a 2DFA with  $e^{O(\ln^2 n)}$  states [Geffert Mereghetti&P '03
- (ii) Polynomial complementation of unary 2NFAs Inductive counting argument for qsNFAs

Geffert Mereghetti&P '07]

- (iii) Polynomial simulation of unary 2NFAs by 2DFAs under the condition L = NL [Geffert&P '10]
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$$\Rightarrow \ \mathsf{GAP} \in \mathsf{L} \ \mathsf{iff} \ \mathsf{L} = \mathsf{NL}$$

More in general,  $\mathsf{GAP} \in \mathcal{C}$  implies  $\mathcal{C} \supseteq \mathsf{NL}$  for each class  $\mathcal{C}$  closed under logspace reductions

#### ► Let A be an n-state unary 2NFA

▶ Reduction from L(A) to GAP i.e, from each string  $a^m$  we compute a graph G(m) s.t

$$a^m \in L(A) \iff G(m) \in \mathsf{GAF}$$

- Under the hypothesis L = NL this reduction is used to build a 2DFA equivalent to A, with a number of states polynomial in n
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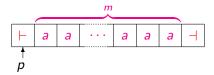
- ▶ the vertices are the states of *M*
- ightharpoonup (p,q) is an edge iff M can traverse the input
  - from one endmarker in the state p
  - to the opposite endmarker in the state q
  - without visiting the endmarkers in the meantime



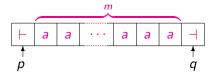
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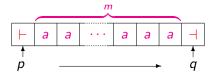
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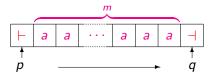
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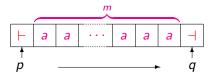


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 $a^m \in L(M)$  iff G(m) contains a path from  $q_0$  to  $q_F$ 



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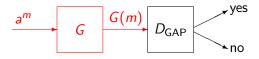
The existence of the edge (p, q) can be verified by a subroutine, implemented by a finite automaton  $A_{p,q}$  with N states



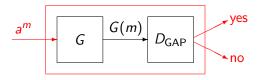
- ► Suppose L = NL
- ► Let *D*<sub>GAP</sub> be a logspace bounded *deterministic* machine solving GAP
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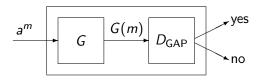
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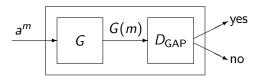


- ▶ The graph G(m) has N vertices, the number of states of M
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  The worktape of D<sub>GAP</sub> can be encoded in a finite control using a number of states polynomial in N
- ► The graph *G*(*m*) can be represented with *N*<sup>2</sup> bits

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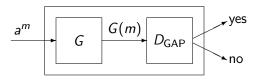


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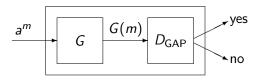


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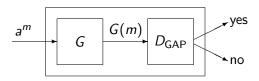




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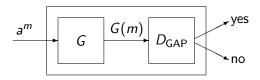


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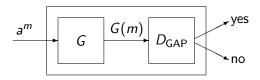




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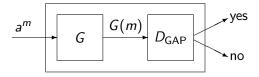


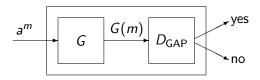
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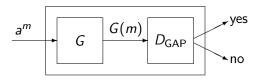
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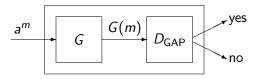




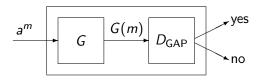
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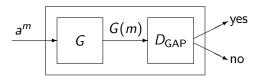
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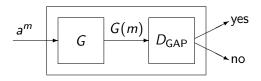
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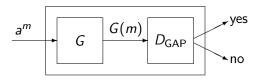
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- ▶ Each  $A_{p,q}$  uses no more than N states
- ▶ Considering all possible (p, q), this part uses at most  $N^3$  states



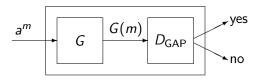
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We described the following simulation:

M 2NFA in normal form

 $\downarrow$ 

M' 2DFA equivalent to M

N states Deterministic Simulation poly(N) states

- ► M is almost equivalent to the original 2NFA A
- ▶ Hence, M' is almost equivalent to A
- ▶ Possible differences for input length  $\leq 5n^2$
- ▶ They can be fixed in a preliminary scan  $(5n^2 + 2 \text{ more states})$
- ► The resulting automaton has polynomially many states

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A given unary 2NFA n states

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\downarrow \downarrow
                                     Conversion into Normal Form
M
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                                                N < 2n + 2 states
\Downarrow
                                          Deterministic Simulation
M'
      2DFA equivalent to M
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        Preliminary scan to accept/reject inputs of length < 5n^2
\Downarrow
                           then simulation of M' for longer inputs
                                                    poly(n) states
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### Theorem ([Geffert&P'10])

If L = NL then each n-state unary 2NFA can be simulated by an equivalent 2DFA with poly(n) many states

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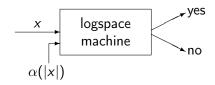
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# **Uniformity?**



# Nonuniform Deterministic Logspace

 L/poly class of languages accepted by deterministic logspace machines with a polynomial advice



Problem  $L/poly \supseteq NL ?$ 

## We did not used the uniformity of L!

▶ L can be replaced by L/poly:

If L/poly  $\supseteq$  NL then each n-state unary 2NFA can be simulated by an equivalent 2DFA with poly(n) many states

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If the simulation of unary 2NFAs by 2DFAs is polynomial in states then there is a deterministic logspace machine with a polynomial advice which solves GAP

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- ► Let *n* be a fixed integer
- ▶ GAP<sub>n</sub> denotes GAP restricted to graphs with vertex set  $V_n = \{0, ..., n-1\}$
- ▶ The binary encoding of a graph  $G = (V_n, E)$  is the standard encoding of its adjacency matrix, i.e., a string

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\langle G \rangle_2 = x_1 x_2 \cdots x_{n^2} \in \{0,1\}^{n^n}
with x_{i\cdot n+j+1} = 1 if and only if (i,j) \in E
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▶ BGAP<sub>n</sub> := { $\langle G \rangle_2 \mid G$  has a path from 0 to n-1} = { $\langle G \rangle_2 \mid G \in \mathsf{GAP}_n$ }

# Solving GAP with Two-Way Automata

Binary Encoding: Languages BGAP

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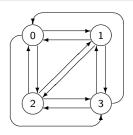
Standard nondeterministic algorithm solving graph accessibility

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▶ Implementation using  $O(n^3)$  states

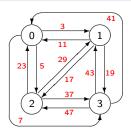
- ▶  $K_n$  := complete directed graph with vertex set  $V_n = \{0, ..., n-1\}$
- ▶ With each edge (i, j) we associate a different prime number p<sub>(i,j)</sub>
- ▶ A subgraph  $G = (V_n, E)$  of  $K_n$  is encoded by the string  $a^{m_G}$ , where

$$m_G = \prod_{(i,j)\in E} p_{(i,j)}$$



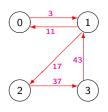
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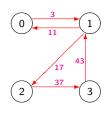
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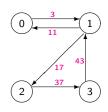


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- ► Graph  $K_n(m)$ :  $\exists$  edge (i,j) iff  $p_{(i,j)}$  divides m
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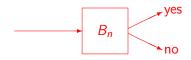
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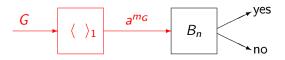
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▶ Implementation using  $O(n^4 \log n)$  states

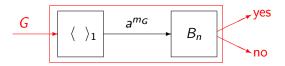
- ► Suppose the conversion of unary 2NFAs into 2DFAs is polynomial
- ▶ Let  $B_n$  be a 2DFA with poly(n) states recognizing UGAP<sub>n</sub>
- ▶ Given a graph  $G = (V_n, E)$ , compute its unary encoding  $a^{mG}$  and give it as input to  $B_n$
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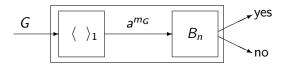
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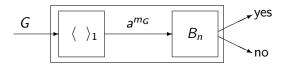
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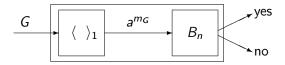
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- ► Our goal:
  - a deterministic machine
  - working in logarithmic space
  - using a polynomial advice
- ▶ The input is the graph G (size  $n^2$ )
- $\triangleright$   $B_n$  is the advice: polynomial size in n
- ▶ Representing  $a^{m_G}$  would require too much space!

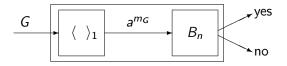


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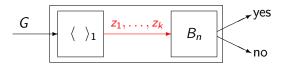
#### Outline of the Construction



#### Prime encoding:

A list of prime powers  $z_1, \ldots, z_k$  factorizing  $m_G$ 

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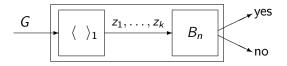


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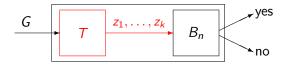
 $a^{m_G}$  is replaced by the prime encoding

Replacing Unary Encodings by Prime Encodings



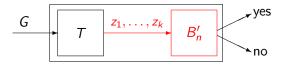
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- ► Prime encoding of  $a^{m_G}$ : list of all  $p_{(i,j)}$  associated with the edges of G
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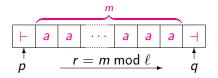
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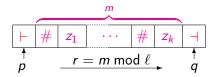
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  - poly(s) many states
  - $\blacksquare$   $B'_n$  reads the prime encoding of an integer m
  - If m is "small" then  $B'_n$  gives the output according to a finite table
  - otherwise,  $B'_n$  on its input simulates  $M_n$  on  $a^m$

# How to Obtain $B'_n$ ? Simulation on Long Inputs



#### In a sweep:

- ►  $M_n$  counts the input length modulo an integer  $\ell$
- ▶ The value of  $\ell$  depends only on the starting state p
- ▶ The ending state q depends on p and on  $r = m \mod \ell$



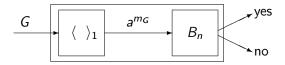
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 $B'_n$  simulates the same sweep on input  $z_1, z_2, \ldots, z_k$ , a prime encoding of m:

$$m \mod \ell = ((\cdots ((z_1 \mod \ell) \cdot z_2) \mod \ell \cdots) \cdot z_k) \mod \ell$$

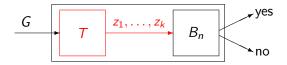
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#### ▶ We replace:

- The machine which computes  $m_G = \langle G \rangle_1$  by a logspace transducer T which outputs a prime encoding of  $m_G$
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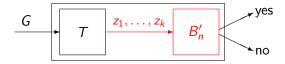
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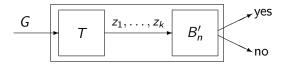
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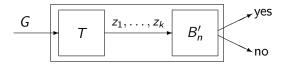
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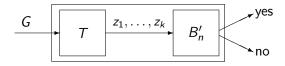
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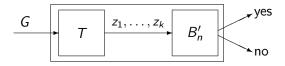
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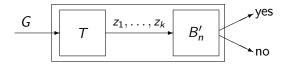
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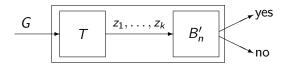
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# Solving GAP with Two-Way Automata Combining All Together



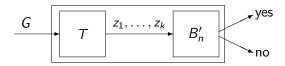
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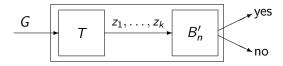
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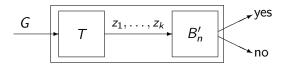
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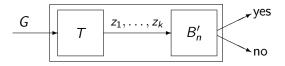


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### Theorem ([Kapoutsis&P '12])

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#### Corollary

 $L/poly \supseteq NL$  if and only if the state cost of the simulation of unary 2NFAs by 2DFAs is poly

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A two-way automaton is said to be *outer nondeterministic* iff nondeterministic choices are allowed *only* when the input head is scanning the endmarkers

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#### Hence:

- ▶ No restrictions on the *input alphabet*
- ▶ No restrictions on head reversals
- Deterministic transitions on "real" input symbols
- Nondeterministic choices only at the endmarkers

All the results we obtained for the unary case can be extended to ONFAs:

- (i) Subexponential simulation of 20NFAs by 2DFAs
- (ii) Polynomial complementation of unary 20NFAs
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[Guillon Geffert&P '12, Kapoutsis&P '12]

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While in the unary case all the proofs rely on the conversion of 2NFAs into quasi sweeping automata, in the case of 2ONFAs we do not have a similar tool!

#### ► The question of Sakoda and Sipser is very challenging

- ▶ In the investigation of restricted versions many interesting and not artificial models have been considered
- ► The results obtained for restricted versions of the problem, even if not solving the full problem, are nontrivial and, in many cases, very deep
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#### Question

Does it is possible to extend the same results (or some of them) to some less restricted models of computation?

► Input head reversals are a critical resource that deserves further investigation

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