

EANN 2014 15th International Conference on Engineering Applications of Neural Networks 5 - 7 September 2014, Sofia, Bulgaria



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Fuzzy-logic Decision Fusion for Nonintrusive Early Detection of Driver Fatigue or Drowsiness

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Topic motivations

Sixty percent of adult drivers have driven a vehicle drowsy; more than one-third have fallen asleep at the wheel.



Source: <u>Harvard Medical School Division of Sleep Medicine</u> https://sleep.med.harvard.edu/





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- Making inferences about the physiological status of a car driver is a very difficult task
- ✓ Research works demonstrate that fuzzy logic methods can be very effective if tailored on the specific nature of drowsiness detection
- ✓ The proposed method, based on fuzzy logic inference and fuzzy decision fusion, reduces the complexity and rises the reliability







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- Physiological VS behavioral information
 Autonomous Nervous System activity
- ✓ More predictors VS single predictor
 - ✓ Heart Rate Variability
 - ✓ Breathing
- Decision level data fusion VS feature level data fusion



What



 Measurement of the Sympathetic to Parasymphatetic activity balance

- ✓ Measurement of the breathing activity
- ✓ Decision level fuzzy inference







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- Sleep is a physiological state characterized by variation in ANS activity, which is reflected in heart-rate variability (HRV).
- ✓ The power spectral density (PSD) of heart rate varies with the change from wakefulness to sleep.







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System Framework

- ✓ The system consists of two layers
- ✓ The lower is a feature inferencing layer
- ✓ The upper is a decision fusion layer







Ecg FIS

- ✓ HRV is then computed from the ECG R-R intervals (R-peak to R-peak) time series
- ✓ PSD of HRV is then computed
 - ✓ very low frequencies (0-0.04 Hz)
 - ✓ low frequencies (0.04-0.15 Hz)
 - ✓ high frequencies (0.15-0.5 Hz)

if HRV(n) is Low and LF(n) is Medium Low and HF(n) is Medium High and LF/HF is Medium then the epoch is ONSET_SLEEP

if HRV(n) is High and LF(n) is High and HF(n) is Low and LF/HF is High then the epoch is WAKE

if HRV(n) is Low and LF(n) is Low and HF(n) is High and LF/HF is Low then the epoch is SLEEP





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- ✓ Breathing features:
 - ✓ Rate
 - ✓ Amplitude
- ✓ 19 rules hand tuned

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if BreathingRate(n) is Medium and BreathingAmplitude(n) is Medium then the epoch is NORMAL

if BreathingRate(n) is Low and BreathingAmplitude(n) is High then the epoch is TIRED





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Decision Fusion FIS

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- ✓ Breathing features:
 - ✓ Rate
 - Amplitude
- ✓ 15 rules hand tuned
- Additional input (Hand Movements) is considered to improve the whole system and/or replace faulty or unavailable modules

if ECG(n) is Ongoing_Sleep and Breathing(n) is Tired and Hand_Movements(n) is Low then the epoch is DROSINESS

if ECG(n) is Ongoing_Sleep and Breathing(n)_is Normal and Hand_Movements(n) is Medium then the epoch is FATIGUE





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Results - Protosystem

Protosystem based on a microcontroller from STMicroelectronics (STM32 ARM M3) and the analog front-end (AFE) from Analog Devices (AD8232).



Results - Evaluation

	Decision f	fusion E	CG features	s fusion	Breathing	features f	usion
PREDIC	IED						
	Drosiness	Normal	Drosiness	Normal	Drosiness	s Normal	
ACTUAL							
Clinical							
Drosiness	19	1	19	1	18	2	
Normal	1	19	3	17	2	18	
In the field (nonembedded)							
Drosiness	18	2	18	2	17	3	
Normal	2	18	4	16	1	19	
In the field (embedded)							
Drosiness	17	3	17	3	16	4	
Normal	3	17	5	15	2	18	

Test type | Decision fusion | ECG features fusion | Breathing features fusion

Clinical	95%	90%	90%
In the field (nonembedded)	90%	85%	90%
In the field (embedded)	85%	80%	85%

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Future developments

- ✓ General purpose personal physiological and vital parameters monitoring
 - Embedding incremental learning capabilities
 - Adaptation to match unattended and in the field operation
 - Application of evolving paradigms
 - ✓ Wearability

Meta-instrument and Natural User Interface: a new Paradigm in Music Education

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Thank you for your attention

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