Fourier transform of images

Stefano Ferrari

Università degli Studi di Milano stefano.ferrari@unimi.it

Methods for Image Processing

academic year 2014-2015

Extension to bidimensional domain

- ► The concepts introduced for the monodimensional domain can be extended for the multidimensional case:
 - ightharpoonup Impulse, δ
 - Convolution
 - ► Fourier transform
 - ► Sampling theorem
- ▶ In particular, we are interested to the bidimensional domain.

Impulse

The Dirac delta function, δ , or impulse, is defined as:

$$\delta(t,z) = \left\{ \begin{array}{ll} \infty, & t=z=0 \\ 0, & t \neq 0, z \neq 0 \end{array} \right.$$

and

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \delta(t,z) \, \mathrm{d}t \, \mathrm{d}z = 1$$

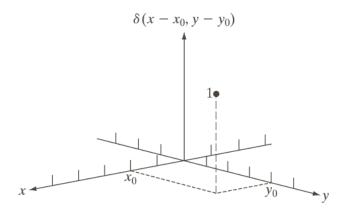
The sifting property holds also in this case:

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(t,z) \, \delta(t-t_0,z-z_0) \, \mathrm{d}t \, \mathrm{d}z = f(t_0,z_0)$$

Impulse (2)

The discrete version of δ for the bidimensional case:

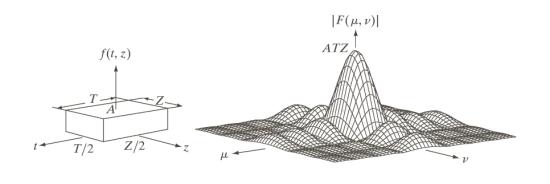
$$\delta(x,y) = \left\{ \begin{array}{ll} 1, & x = y = 0 \\ 0, & \text{otherwise} \end{array} \right.$$



2D continuous Fourier transform pair

$$F(\nu,\mu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(t,z) e^{-\iota 2\pi(\nu t + \mu z)} dt dz$$

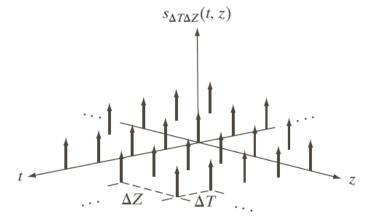
$$f(t,z) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} F(\nu,\mu) \, e^{i2\pi(\nu t + \mu z)} \, \mathrm{d} \nu \, \mathrm{d} \mu$$



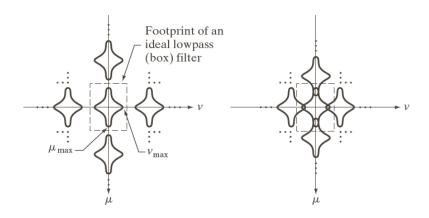
2D sampling theorem

$$\tilde{f}(t,z) = f(t,z) s_{\Delta T \Delta Z}(t,z) = \sum_{m, n=-\infty}^{\infty} f(t) \delta(t - n\Delta T, z - m\Delta Z)$$

$$rac{1}{\Delta \mathit{T}} > 2\,
u_{\mathsf{max}} \qquad \mathsf{and} \qquad rac{1}{\Delta \mathit{Z}} > 2\, \mu_{\mathsf{max}}$$

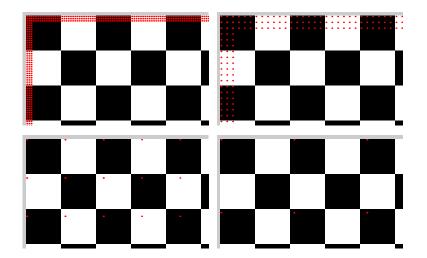


Aliasing in images



- Aliasing effects: false borders and jagged edges.
- ► Reduction:
 - smoothing before sampling
 - oversampling and averaging
- Reduction (post)
 - smoothing

Aliasing example: sampling a checkerboard



Sampling a checkerboard pattern where the sides of the squares are 96 units long.

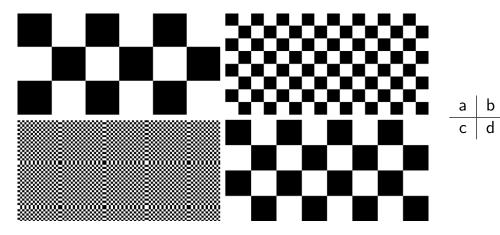
(a)
$$\Delta T = \Delta Z = 6$$

(a)
$$\Delta T = \Delta Z = 6$$
 (c) $\Delta T = \Delta Z = 105$

(b)
$$\Delta T = \Delta Z = 16$$

(d)
$$\Delta T = \Delta Z = 200$$

Aliasing example: sampling a checkerboard (2)



Sampling a checkerboard pattern where the sides of the squares are 96 units long.

(a)
$$\Delta T = \Delta Z = 6$$

(c)
$$\Delta T = \Delta Z = 105$$

(b)
$$\Delta T = \Delta Z = 16$$
 (d) $\Delta T = \Delta Z = 200$

(d)
$$\Delta T = \Delta Z = 200$$

Resampling and interpolation







- a b c
- (a) Original image
- (b) Resampled image
- (c) Applying smoothing before resampling

Note: Resampling has been operated through rows and columns deletion.

Resampling and interpolation (2)



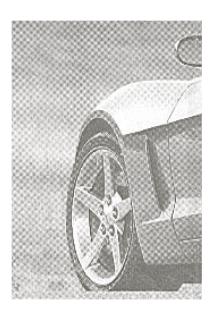


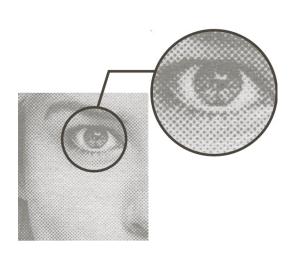


- (a) Zooming by pixel replication
- (b) Zooming by pixel bicubic interpolation
- (b) Zooming by pixel sinc interpolation

Resampling and interpolation (3)

The moirè effect is caused by the superimposition of two periodical patterns.





Bidimensional DFT pair

$$F(u, v) = \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-i2\pi(ux/M + vy/N)}$$

$$f(x, y) = \frac{1}{MN} \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{i2\pi(ux/M + vy/N)}$$

where

$$u = 0, \ldots, M-1$$
 $v = 0, \ldots, N-1$

$$x = 0, \ldots, M-1, \qquad y = 0, \ldots, N-1$$

DFT properties

► Traslation

$$\mathcal{F}\{f(x,y) e^{\iota 2\pi(u_0x/M+v_0y/N)}\} = F(u-u_0, v-0)$$
$$\mathcal{F}\{f(x-x_0, y-y_0)\} = F(u, v) e^{-\iota 2\pi(x_0u/M+y_0v/N)}$$

- Multiplying f by an exponential produces a shift in the DTF.
- ▶ Translating f has the effect of multiplying its DFT.
- ► Rotation
 - Rotating f produces an identical rotation in its DFT.

DFT properties (2)

Periodicity

$$F(u, v) = F(u + k_1 M, v + k_2 N)$$

$$f(x, y) = f(x + k_1 M, y + k_2 N)$$

where $k_1, k_2 \in \mathbb{Z}$

$$\mathcal{F}{f(x, y)(-1)^{x+y}} = F(u - M/2, v - N/2)$$

DFT properties (3)

- Simmetry
 - ► Even (symmetric) functions

$$f(x, y) = f(-x, -y)$$

Odd (antisymmetric) functions

$$f(x, y) = -f(-x, -y)$$

Symmetry properties in f involve corresponding properties in F that are useful in processing.

E.g.: If f is real and even, also F is real and even.

Fourier spectrum and phase angle

▶ The DFT can be expressed in polar form:

$$F(u, v) = |F(u, v)| e^{\iota \phi(u, v)}$$

where |F(u, v)|, called Fourier spectrum:

$$|F(u, v)| = [R^2(u, v) + I^2(u, v)]^{1/2}$$

and $\phi(u, v)$, called *phase angle*:

$$\phi(u, v) = \arctan\left(\frac{I(u, v)}{R(u, v)}\right)$$

▶ The power spectrum, P(u, v), is defined as:

$$P(u, v) = |F(u, v)|^2 = R^2(u, v) + I^2(u, v)$$

Fourier spectrum and phase angle (2)

▶ It can be shown that:

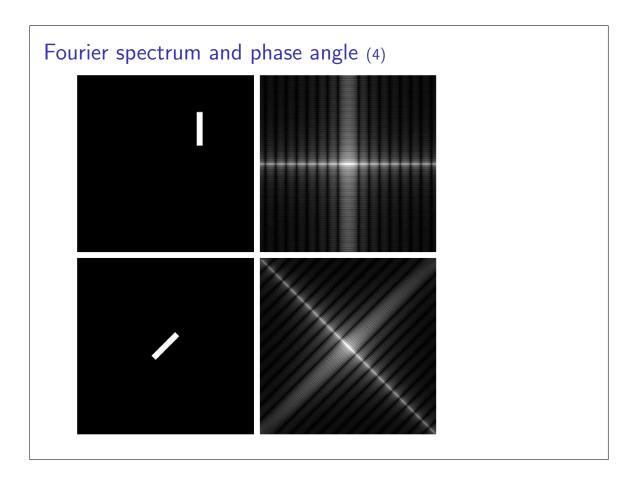
$$|F(0, 0)| = MN|\overline{f}(x, y)|$$

where \bar{f} is the f average value.

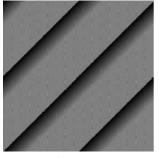
F(0, 0) is generally much larger than the other terms of F;

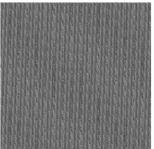
▶ logarithmic transform for displaying it.

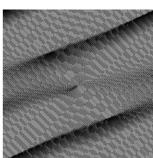
Fourier spectrum and phase angle (3)



Fourier spectrum and phase angle (5)

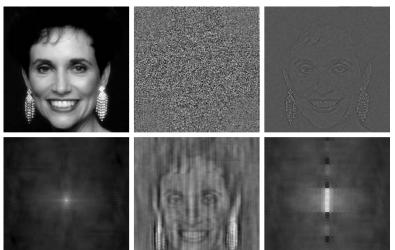






- a b c
 - (a) phase angle of the centered rectangle image;
 - (b) phase angle of the shifted rectangle image;
 - (c) phase angle of the rotated rectangle image;

Fourier spectrum and phase angle (6)



- ▶ (b): phase angle of (a);
- ► (c) and (d): IDFT(phase angle of (a)) and IDFT(spectrum of (a));
- ► (e): IDFT(phase angle of the woman + spectrum of the rectangle);
- (f): IDFT(spectrum of the woman + phase angle of the rectangle).

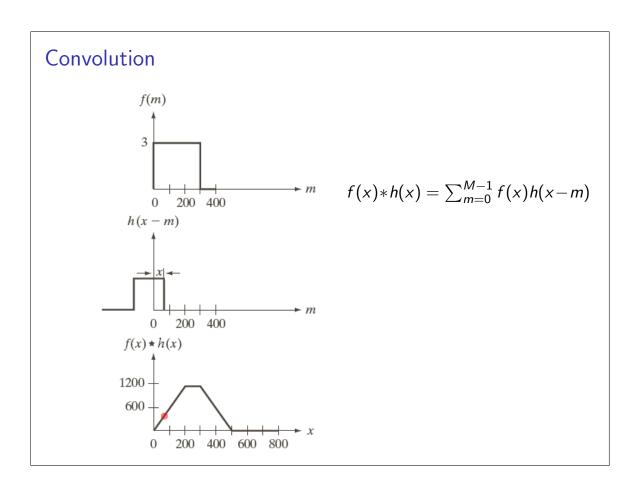
2D convolution theorem

▶ The convolution theorem can be formulated for the 2D DFT:

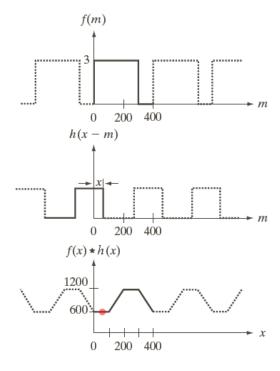
$$\mathcal{F}\{f(x, y) * h(x, y)\} = F(u, v) H(u, v)$$

$$\mathcal{F}\{f(x, y) h(x, y)\} = F(u, v) * H(u, v)$$

▶ The circular convolution has to be used.



Circular convolution



$$f(x) * h(x) =$$

$$= \sum_{m=0}^{M-1} f(x)h(x-m)$$

Wraparound error

- ► The (circular) convolution of two periodic function can cause the so called *wraparound error*.
- ▶ It can be resolved using the zero padding.
 - ► Giving two sequences of respectively *A* and *B* samples, append zeros to them such that both will have *P* elements:

$$P = A + B - 1$$

- ▶ If a function is not zero at the end of the interval, the zero padding introduces artifacts:
 - ▶ High frequency components in the transform.
- Attenuation with the windowing technique:
 - e.g., multiplying by a Gaussian.

Homeworks and suggested readings



DIP, Sections 4.5-4.6

▶ pp. 225–254



GIMP

- ▶ Image
 - ► Scale Image
 - ► Cubic
 - Sinc