Foundations of Operations Research

Master of Science in Computer Engineering

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Tuesday 13.15 - 15.15 Thursday 10.15 - 13.15

http://homes.di.unimi.it/~cordone/courses/2014-for/2014-for.html



Lesson 7: Project planning

Como, Fall 2013

Project planning

A project consists of a set $N = \{a_1, \ldots, a_n\}$ of activities

A duration $d: N \to \mathbb{R}^+$ is associated to each activity

A precedence relation connects some pairs of activities: $a_i \prec a_j$ means that activity a_j can start only after activity a_i has ended

A project can be modelled by an arc-weighted directed graph G = (N, A)

- nodes stand for activity start events, plus
 a fictitious node s for the beginning of the project and
 a fictitious node t for the end of the project
- arcs stand for precedence constraints: the given ones plus the fact that s precedes all activities and all activities precede t
- the arc cost $c_{ij} = d_i$ stands for the activity duration: the starting times of activities a_i and a_j must differ at least by d_i

The graph representing a project is acyclic (otherwise, the start event of an activity should follow its end event: a logical paradox, or a deadlock)

The problem

Find for each activity $a_i \in N$ a start time x_i respecting the precedence constraints so as to minimize the overall duration $f = x_t - x_s$ (i. e. the time needed to complete the whole project)

We conventionally set $x_s = 0$ and define as

- τ_i^{\min} the earliest start time for activity $a_i \in N$ in any feasible solution
- τ_i^{\max} the latest start time for activity $a_i \in N$ in any optimal solution All solutions with $\tau_i^{\min} \le x_i \le \tau_i^{\max}$ for all $a_i \in N$ are optimal
- slack $\sigma_i = \tau_i^{\text{max}} \tau_i^{\text{min}}$ the amount of time by which an activity can be postponed without affecting the overall duration
- critical activity an activity with identical earliest and latest time ($\sigma_i = 0$)
 A critical activity cannot be postponed without delaying the whole project

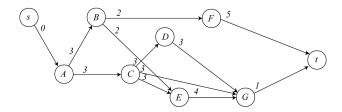
Property: The cost of each directed path from s to t is a lower bound on the overall duration f

$$f \ge c_{P_{st}}$$
 for all P_{st} path from s to t

Proof: $P_{\rm st}$ is a sequence of activities that must be performed in the same order in which they are visited in the path

Example

Activity	Duration	Predecessors
A	3	-
В	2	Α
C	3	Α
D	3	С
E	4	B,C
F	5	В
G	1	C,D,E



Why does s reach only A? Why is t reached only by F and G?

The Critical Path Method (CPM)

The critical path method (CPM) finds a solution $x^*: N \to \mathbb{R}$ such that

- · all constraints are respected
- ullet the overall duration equals the maximum cost of a path from s to t

$$f(x_t^*) = \max\{c_{P_{st}} : P_{st} \text{ is a path from } s \text{ to } t \text{in } G\}$$

If the cost of a feasible solution equals a lower bound on the optimum the solution is optimal (by contradiction: if it were not optimal, the optimum would be smaller than the lower bound)

The CPM finds τ_i^{\min} , τ_i^{\max} and the slack σ_i for each activity $a_i \in N$ applying dynamic programming

Remember that any solution with $\tau_i^{\min} \leq x_i \leq \tau_i^{\max}$ is optimal

The Critical Path Method (CPM)

① Sort the nodes topologically (the graph is acyclic); by definition, $s = n_0$ and $t = n_n$ (s precedes and t follows all the other nodes)

In order to find an optimal solution

- $2 \operatorname{Set} \tau_0^{\min} = 0$
- **3** Compute the earliest time τ_h^{\min} of each node $n_h \in N$ for h

$$au_h^{\mathsf{min}} = \max_{i:(n_i,n_h) \in \Delta_{n_h}^-} \left(au_i^{\mathsf{min}} + d_i
ight) \qquad h ext{ increasing from 1 to } n$$

(computing the minimum cost paths with inverted sign costs)

The optimal solution is $x_i^* = \tau_i^{\min}$ and its cost is $f(x^*) = \tau_n^{\min}$

In order to find all optimal solutions

- **6** Compute the latest time τ_h^{max} of each node $n_h \in N$

$$\tau_h^{\mathsf{max}} = \min_{i:(n_h, n_i) \in \Delta_{n_k}^+} (\tau_i^{\mathsf{max}} - d_h) \qquad h \text{ decreasing from } n - 1 \text{ to } 0$$

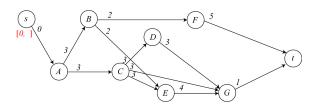
(computing backward minimum cost paths with inverted sign costs)



Application of the CPM(1)

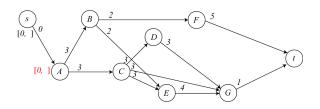
CPM(N, A, d)

Return $(\tau^{\min}, \tau^{\max});$



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\begin{split} & \text{TopologicalSort}(\textit{N}); & \textit{s} & \textit{A} & \textit{B} \\ & \tau_0^{\min} := 0; & \textit{n}_5 & \textit{n}_6 & \textit{n}_7 \\ & \textbf{For } h := 1 \text{ to } n \text{ do} & \\ & \tau_h^{\min} := \max_{i \in N: (i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\min} + d_i\right); & \tau_0^{\min} := 0 \\ & \tau_n^{\max} := \tau_n^{\min}; & \\ & \textbf{For } h := n-1 \text{ downto } 0 \text{ do} \\ & \tau_h^{\max} := \min_{i \in N: (n_h, n_i) \in \Delta_{n_h}^+} \left(\tau_i^{\max} - d_h\right); & \end{split}
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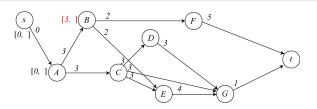
Application of the CPM(2)



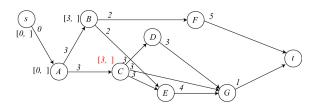
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\begin{array}{llll} \mathsf{CPM}(N,A,d) & & & & & & & & & & & & & & & & & \\ \mathsf{TopologicalSort}(N); & & & & & & & & & & & & & & & & \\ \tau_0^{\min} := 0; & & & & & & & & & & & & & & & \\ \mathsf{For} \ \ h := 1 \ \ \mathsf{to} \ \ n \ \ \mathsf{do} & & & & & & & & & & & & & & \\ \mathsf{For} \ \ h := 1 \ \ \mathsf{to} \ \ n \ \ \mathsf{do} & & & & & & & & & & & & \\ \tau_h^{\min} := & \max_{i \in N: (i,h) \in \Delta_{n_h}^-} \left( \tau_i^{\min} + d_i \right); & & & & & & & \\ \tau_n^{\max} := & \max_{i \in N: (n_h, n_i) \in \Delta_{n_h}^+} \left( \tau_i^{\min} - d_h \right); & & & & & \\ \mathsf{For} \ \ h := & & & & & & & \\ \tau_h^{\max} := & & & & & & \\ \tau_h^{\max} := & & & & & \\ \iota \in N: (n_h, n_i) \in \Delta_{n_h}^+ \left( \tau_i^{\max} - d_h \right); & & & & \\ \mathsf{Return} \ \ (\tau_i^{\min}, \tau_i^{\max}); & & & & & \\ \end{array}
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Application of the CPM(3)

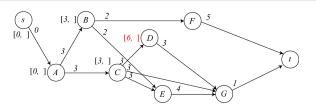
Return $(\tau^{\min}, \tau^{\max});$



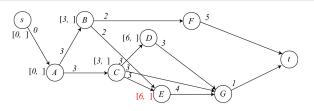
Application of the CPM (4)



Application of the CPM (5)



Application of the CPM (6)

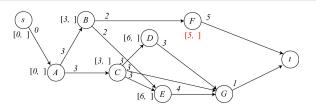


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\begin{split} & \mathsf{CPM}(N,A,d) \\ & \mathsf{TopologicalSort}(N); \\ & \tau_0^{\min} := 0; \\ & \mathsf{For} \ \ h := 1 \ \ \mathsf{to} \ \ n \ \ \mathsf{do} \\ & \tau_h^{\min} := \max_{i \in N: (i,h) \in \Delta_{\overline{n}_h}} \left( \tau_i^{\min} + d_i \right); \\ & \tau_n^{\max} := \tau_n^{\min}; \\ & \mathsf{For} \ \ h := n-1 \ \ \mathsf{downto} \ \ 0 \ \ \mathsf{do} \\ & \tau_h^{\max} := \min_{i \in N: (n_h, n_i) \in \Delta_{n_h}^+} \left( \tau_i^{\max} - d_h \right); \\ & \mathsf{Return} \ \ \left( \tau_h^{\min}, \tau_h^{\max} \right); \end{split}
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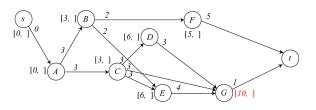
$$h_5 \quad h_6 \quad h_7 \quad h_8$$
 $E \quad F \quad G \quad t$
 $h = 5$
 $\tau_5^{\min} := \max \left(\tau_2^{\min} + d_{n_2}, \tau_3^{\min} + d_{n_3} \right) = 6$

 n_4

Application of the CPM(7)



Application of the CPM (8)



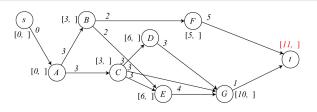
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\begin{split} \mathsf{CPM}(N,A,d) \\ \mathsf{TopologicalSort}(N); \\ \tau_0^{\mathsf{min}} &:= 0; \\ \mathsf{For} \ \ h := 1 \ \ \mathsf{to} \ \ n \ \ \mathsf{do} \\ \tau_h^{\mathsf{min}} &:= \max_{i \in N: (i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\mathsf{min}} + d_i\right); \\ \tau_n^{\mathsf{max}} &:= \tau_n^{\mathsf{min}}; \\ \mathsf{For} \ \ h := n-1 \ \ \mathsf{downto} \ \ 0 \ \ \mathsf{do} \\ \tau_h^{\mathsf{max}} &:= \min_{i \in N: (n_h, n_i) \in \Delta_{n_h}^+} \left(\tau_i^{\mathsf{max}} - d_h\right); \end{split}
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Return $(\tau^{\min}, \tau^{\max});$

$$egin{array}{lll} n_5 & n_6 & n_7 & n_8 \ E & F & G & t \ \end{array} \ h = 7 \ & au_7^{ ext{min}} := ext{max}(au_3^{ ext{min}} + d_3, au_4^{ ext{min}} + d_{n_4}, au_{n_6}^{ ext{min}} + d_5) = 10 \ \end{array}$$

Application of the CPM(9)

Return $(\tau^{\min}, \tau^{\max});$



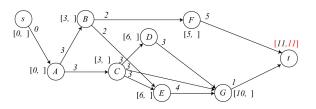
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\begin{aligned} \mathsf{CPM}(N,A,d) & n_0 & n_1 \\ \mathsf{TopologicalSort}(N); & s & A \\ \tau_0^{\min} &:= 0; & n_5 & n_6 \\ E & F \end{aligned} \begin{aligned} \mathsf{For} & h &:= 1 & \mathbf{to} & n & \mathbf{do} \\ \tau_h^{\min} &:= \max_{i \in \mathcal{N}: (i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\min} + d_i\right); & h &= 8 \\ \tau_n^{\min} &:= \max_{i \in \mathcal{N}: (i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\min} + d_i\right); & max \\ \tau_n^{\max} &:= \tau_n^{\min}; & = 11 \end{aligned} \begin{aligned} \mathsf{For} & h &:= n-1 & \mathbf{downto} & 0 & \mathbf{do} \\ \tau_h^{\max} &:= \min_{i \in \mathcal{N}: (n_h, n_i) \in \Delta_{n_h}^+} \left(\tau_i^{\max} - d_h\right); & max \end{aligned}
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$$n_5 \quad n_6 \quad n_7 \quad n_8$$
 $E \quad F \quad G \quad t$
 $h = 8$
 $\tau_8^{\min} := \max \left(\tau_6^{\min} + d_{n_6}, \tau_7^{\min} + d_{n_7} \right) = 0$

 n_4

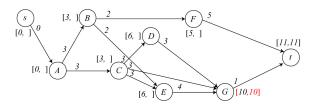
Application of the CPM (10)

Return $(\tau^{\min}, \tau^{\max});$



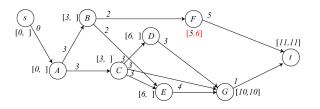
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 \begin{split} \mathsf{CPM}(N,A,d) & n_0 & n_1 & n_2 & n_3 & n_4 \\ \mathsf{TopologicalSort}(N); & s & A & B & C & D \\ \tau_0^{\min} & := 0; & n_5 & n_6 & n_7 & n_8 \\ \mathsf{For} & h := 1 & \mathbf{to} & n & \mathbf{do} \\ & \tau_h^{\min} & := \max_{i \in N:(i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\min} + d_i\right); \\ & \tau_n^{\max} & := \tau_n^{\min}; & \tau_8^{\max} & := 11 \\ \mathsf{For} & h := n - 1 & \mathsf{downto} & 0 & \mathsf{do} \\ & \tau_h^{\max} & := \min_{i \in N:(n_h,n_i) \in \Delta_{n_h}^+} \left(\tau_i^{\max} - d_h\right); \end{aligned}
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Application of the CPM (11)

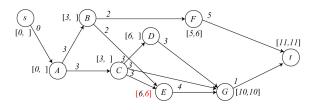


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\begin{array}{lll} \mathsf{CPM}(N,A,d) & n_0 & n_1 & n_2 & n_3 & n_4 \\ \mathsf{TopologicalSort}(N); & s & A & B & C & D \\ \tau_0^{\min} := 0; & n_5 & n_6 & n_7 & n_8 \\ \mathsf{For} & h := 1 & \mathbf{to} & n & \mathbf{do} \\ & \tau_h^{\min} := \max_{i \in N: (i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\min} + d_i\right); \\ & \tau_n^{\max} := \tau_n^{\min}; \\ \mathsf{For} & h := n - 1 & \mathbf{downto} & 0 & \mathbf{do} \\ & & & h = 7 \\ & & & & \\ \tau_h^{\max} := \min_{i \in N: (n_h, n_i) \in \Delta_{n_h}^+} \left(\tau_i^{\max} - d_h\right); & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{Return} & \left(\tau_k^{\min}, \tau_k^{\max}\right); & \\ & & \\ \mathsf{R
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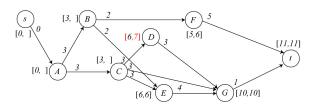
Application of the CPM (12)



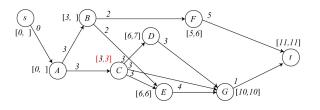
Application of the CPM (13)



Application of the CPM (14)

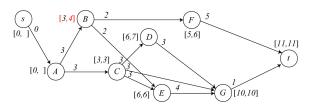


Application of the CPM (15)

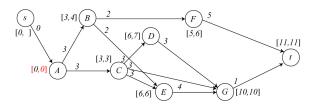


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\begin{array}{llll} \mathsf{CPM}(N,A,d) & n_0 & n_1 & n_2 & n_3 & n_4 \\ \mathsf{TopologicalSort}(N); & s & A & B & C & D \\ \tau_0^{\min} := 0; & n_5 & n_6 & n_7 & n_8 \\ \mathsf{For} & h := 1 & \mathbf{to} & n & \mathbf{do} \\ & \tau_h^{\min} := \max_{i \in N: (i,h) \in \Delta_{n_h}^-} \left(\tau_i^{\min} + d_i\right); \\ & \tau_n^{\max} := \tau_n^{\min}; \\ \mathsf{For} & h := n - 1 & \mathbf{downto} & 0 & \mathbf{do} \\ & & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ &
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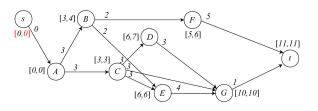
Application of the CPM (16)



Application of the CPM (17)

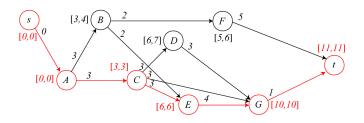


Application of the CPM (18)



Critical path

An optimal solution always has at least one critical path, that is a path from s to t whose nodes correspond to critical activities

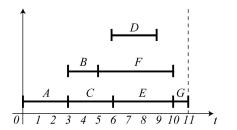


- (s, A, C, E, G, t) is a critical path
- A, C, E and G are critical activities
- B, D and F are noncritical activities: their starting time can be delayed by the same slack ($\sigma_2 = \sigma_4 = \sigma_6 = 1$) without affecting the overall shortest duration ($f^* = 11$)

Gantt diagram (at earliest)

The Gantt diagram is a temporal representation of a project

- the horizontal axis represent time
- the activities are distributed along the vertical axis
- activity schedules are horizontal segments
 - 1 from τ_i^{\min} to $\tau_i^{\min} + d_i$ in the diagram at earliest
 - 2 from $\tau_i^{\max} d_i$ to τ_i^{\max} in the diagram at latest

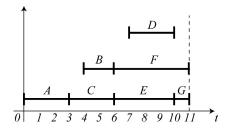


i	d	$ au_i^{min}$	$ au_i^{min} + d_i$
Α	3	0	3
B C	2	3	5
C	3	3	6
D	3	6	9
Ε	4	6	10
E F G	5	5	10
G	1	10	11

Gantt diagram (at latest)

The Gantt diagram is a temporal representation of a project

- the horizontal axis represent time
- the activities are distributed along the vertical axis
- activity schedules are horizontal segments
 - 1 from τ_i^{\min} to $\tau_i^{\min} + d_i$ in the diagram at earliest
 - 2 from $\tau_i^{\text{max}} d_i$ to τ_i^{max} in the diagram at latest



i	d	τ_i^{max}	$ au_i^{max} + d_i$
Α	3	0	3
A B C	2 3	4	6
C	3	3	6
D	3	7	10
Ε	4	6	10
D E F G	4 5	6	11
G	1	10	11